

# **IS&T International Symposium on Electronic Imaging (EI 2023)**

3D Imaging and Applications 2023

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# 3D Imaging and Applications 2023

MONDAY 16 JANUARY 2023

## Monday 16 January PLENARY: Neural Operators for Solving PDEs

Session Chair: Robin Jenkin, NVIDIA Corporation (United States)

2:00 PM – 3:00 PM

Cyril Magnin I/II/III

*Deep learning surrogate models have shown promise in modeling complex physical phenomena such as fluid flows, molecular dynamics, and material properties. However, standard neural networks assume finite-dimensional inputs and outputs, and hence, cannot withstand a change in resolution or discretization between training and testing. We introduce Fourier neural operators that can learn operators, which are mappings between infinite dimensional spaces. They are independent of the resolution or grid of training data and allow for zero-shot generalization to higher resolution evaluations. When applied to weather forecasting, neural operators capture fine-scale phenomena and have similar skill as gold-standard numerical weather models for predictions up to a week or longer, while being 4-5 orders of magnitude faster.*

**Anima Anandkumar**, Bren professor, California Institute of Technology, and senior director of AI Research, NVIDIA Corporation (United States)

*Anima Anandkumar is a Bren Professor at Caltech and Senior Director of AI Research at NVIDIA. She is passionate about designing principled AI algorithms and applying them to interdisciplinary domains. She has received several honors such as the IEEE fellowship, Alfred. P. Sloan Fellowship, NSF Career Award, and Faculty Fellowships from Microsoft, Google, Facebook, and Adobe. She is part of the World Economic Forum's Expert Network. Anandkumar received her BTech from Indian Institute of Technology Madras, her PhD from Cornell University, and did her postdoctoral research at MIT and assistant professorship at University of California Irvine.*

## EI 2023 Highlights Session

Session Chair: Robin Jenkin, NVIDIA Corporation (United States)

3:30 – 5:00 PM

Cyril Magnin II

*Join us for a session that celebrates the breadth of what EI has to offer with short papers selected from EI conferences.*

*NOTE: The EI-wide "EI 2023 Highlights" session is concurrent with Monday afternoon COIMG, COLOR, IMAGE, and IQSP conference sessions.*

N/A

**Evaluation of image quality metrics designed for DRI tasks with automotive cameras**, Valentine Klein, Yiqi LI, Claudio Greco, Laurent Chanas, and Frédéric Guichard, DXOMARK (France)

N/A  
**Human performance using stereo 3D in a helmet mounted display and association with individual stereo acuity**, *Bonnie Posselt, RAF Centre of Aviation Medicine (United Kingdom)*

N/A  
**Smartphone-enabled point-of-care blood hemoglobin testing with color accuracy-assisted spectral learning**, *Sang Mok Park<sup>1</sup>, Yuhyun Ji<sup>1</sup>, Semin Kwon<sup>1</sup>, Andrew R. O'Brien<sup>2</sup>, Ying Wang<sup>2</sup>, and Young L. Kim<sup>1</sup>; <sup>1</sup>Purdue University and <sup>2</sup>Indiana University School of Medicine (United States)*

N/A  
**Designing scenes to quantify the performance of automotive perception systems**, *Zhenyi Liu<sup>1</sup>, Devesh Shah<sup>2</sup>, Alireza Rahimpour<sup>2</sup>, Joyce Farrell<sup>1</sup>, and Brian Wandell<sup>1</sup>; <sup>1</sup>Stanford University and <sup>2</sup>Ford Motor Company (United States)*

N/A  
**Visualizing and monitoring the process of injection molding**, *Christian A. Steinparz<sup>1</sup>, Thomas Mitterlehner<sup>2</sup>, Bernhard Praher<sup>2</sup>, Klaus Straka<sup>1,2</sup>, Holger Stitz<sup>1,3</sup>, and Marc Streit<sup>1,3</sup>; <sup>1</sup>Johannes Kepler University, <sup>2</sup>Moldsonics GmbH, and <sup>3</sup>datavisyn GmbH (Austria)*

N/A  
**Commissioning the James Webb Space Telescope**, *Joseph M. Howard, NASA Goddard Space Flight Center (United States)*

N/A  
**Critical flicker frequency (CFF) at high luminance levels**, *Alexandre Chapiro<sup>1</sup>, Nathan Matsuda<sup>1</sup>, Maliha Ashraf<sup>2</sup>, and Rafal Mantiuk<sup>3</sup>; <sup>1</sup>Meta (United States), <sup>2</sup>University of Liverpool (United Kingdom), and <sup>3</sup>University of Cambridge (United Kingdom)*

N/A  
**Physics guided machine learning for image-based material decomposition of tissues from simulated breast models with calcifications**, *Muralikrishnan Gopalakrishnan Meena<sup>1</sup>, Amir K. Ziabari<sup>1</sup>, Singanallur Venkatakrishnan<sup>1</sup>, Isaac R. Lyngaas<sup>1</sup>, Matthew R. Norman<sup>1</sup>, Balint Joo<sup>1</sup>, Thomas L. Beck<sup>1</sup>, Charles A. Bouman<sup>2</sup>, Anuj Kapadia<sup>1</sup>, and Xiao Wang<sup>1</sup>; <sup>1</sup>Oak Ridge National Laboratory and <sup>2</sup>Purdue University (United States)*

N/A  
**Layered view synthesis for general images**, *Loïc Dehan, Wiebe Van Ranst, and Patrick Vandewalle, Katholieke University Leuven (Belgium)*

N/A

**A self-powered asynchronous image sensor with independent in-pixel harvesting and sensing operations**, *Ruben Gomez-Merchan, Juan Antonio Leñero-Bardallo, and Ángel Rodríguez-Vázquez, University of Seville (Spain)*

N/A

**Color blindness and modern board games**, *Alessandro Rizzi<sup>1</sup> and Matteo Sassi<sup>2</sup>; <sup>1</sup>Università degli Studi di Milano and <sup>2</sup>consultant (Italy)*

## TUESDAY 17 JANUARY 2023

### Tuesday 17 January PLENARY: Embedded Gain Maps for Adaptive Display of High Dynamic Range Images

Session Chair: Robin Jenkin, NVIDIA Corporation (United States)

2:00 PM – 3:00 PM

Cyril Magnin I/II/III

*Images optimized for High Dynamic Range (HDR) displays have brighter highlights and more detailed shadows, resulting in an increased sense of realism and greater impact. However, a major issue with HDR content is the lack of consistency in appearance across different devices and viewing environments. There are several reasons, including varying capabilities of HDR displays and the different tone mapping methods implemented across software and platforms. Consequently, HDR content authors can neither control nor predict how their images will appear in other apps.*

*We present a flexible system that provides consistent and adaptive display of HDR images. Conceptually, the method combines both SDR and HDR renditions within a single image and interpolates between the two dynamically at display time. We compute a Gain Map that represents the difference between the two renditions. In the file, we store a Base rendition (either SDR or HDR), the Gain Map, and some associated metadata. At display time, we combine the Base image with a scaled version of the Gain Map, where the scale factor depends on the image metadata, the HDR capacity of the display, and the viewing environment.*

**Eric Chan**, Fellow, Adobe Inc. (United States)

*Eric Chan is a Fellow at Adobe, where he develops software for editing photographs. Current projects include Photoshop, Lightroom, Camera Raw, and Digital Negative (DNG). When not writing software, Chan enjoys spending time at his other keyboard, the piano. He is an enthusiastic nature photographer and often combines his photo activities with travel and hiking.*

**Paul M. Hubel**, director of Image Quality in Software Engineering, Apple Inc. (United States)

*Paul M. Hubel is director of Image Quality in Software Engineering at Apple. He has worked on computational photography and image quality of photographic systems for many years on all aspects of the imaging chain, particularly for iPhone. He trained in optical engineering at University*

of Rochester, Oxford University, and MIT, and has more than 50 patents on color imaging and camera technology. Hubel is active on the ISO-TC42 committee Digital Photography, where this work is under discussion, and is currently a VP on the IS&T Board. Outside work he enjoys photography, travel, cycling, coffee roasting, and plays trumpet in several bay area ensembles.

## WEDNESDAY 18 JANUARY 2023

### 3D Segmentation and Recognition (W1)

**Session Chair:** Tyler Bell, University of Iowa (United States)

8:45 – 10:10 AM

Powell I/II

8:45

#### Conference Welcome

8:50

3DIA-100

**Few-shot learning on point clouds for railroad segmentation,** *Abdur R. Fayjie and Patrick Vandewalle, Katholieke University Leuven (Belgium)*

9:10

3DIA-101

**Appearance segmentation and documentation applied to cultural heritage surfaces,** *Sunita Saha<sup>1</sup>, Amalia Siatou<sup>2,3</sup>, Christian Degryny<sup>3</sup>, Alamin Mansouri<sup>2</sup>, and Robert Sitnik<sup>1</sup>; <sup>1</sup>Politechnika Warszawska (Poland), <sup>2</sup>University of Burgundy (France), and <sup>3</sup>University of Applied Sciences and Arts Western Switzerland (HES-SO) (Switzerland)*

9:30

3DIA-102

**Learned visual localization with camera pose refinement and verification based on differentiable renderer,** *Chanchang Tsai, Hajime Taira, and Masatoshi Okutomi, Tokyo Institute of Technology (Japan)*

9:50

3DIA-103

**3D mesh saliency from local spiral hop descriptors,** *Olivier Lézoray<sup>1</sup> and Anass Nouri<sup>2</sup>; <sup>1</sup>University of Caen Normandy (France) and <sup>2</sup>Ibn Tofail University (Morocco)*

### Depth Estimation and 3D Reconstruction (W2)

**Session Chair:** Tyler Bell, University of Iowa (United States)

10:40 AM – 12:20 PM

Powell I/II

10:40

3DIA-104

**Layered view synthesis for general images,** *Loïc Dehan, Wiebe Van Ranst, and Patrick Vandewalle, Katholieke University Leuven (Belgium)*

11:00

3DIA-105

**DL-based floorplan generation from noisy point clouds,** *Xin Liu, Egor Bondarev, and Peter H. de With, Eindhoven University of Technology (the Netherlands)*

11:20

3DIA-107

**A comparative evaluation of 3D geometries of scenes estimated using factor graph based disparity estimation algorithms,** *Hanieh Shabani<sup>1</sup> and Madhusudhanan Balasubramanian<sup>2</sup>; <sup>1</sup>Northern Kentucky University and <sup>2</sup>University of Memphis (United States)*

11:40

3DIA-108

**Assistive mobile application for real-time 3D spatial audio soundscapes toward improving safe and independent navigation**, Broderick S. Schwartz and Tyler Bell, University of Iowa (United States)

12:00

3DIA-109

**3D nuclei segmentation for multicellular quantification for zebrafish embryo using NISNet3D**, Linlin Li, Liming Wu, Alain Chen, Edward J. Delp, and David M. Umulis, Purdue University (United States)

### **Wednesday 18 January PLENARY: Bringing Vision Science to Electronic Imaging: The Pyramid of Visibility**

Session Chair: Andreas Savakis, Rochester Institute of Technology (United States)

2:00 PM – 3:00 PM

Cyril Magnin I/II/III

*Electronic imaging depends fundamentally on the capabilities and limitations of human vision. The challenge for the vision scientist is to describe these limitations to the engineer in a comprehensive, computable, and elegant formulation. Primary among these limitations are visibility of variations in light intensity over space and time, of variations in color over space and time, and of all of these patterns with position in the visual field. Lastly, we must describe how all these sensitivities vary with adapting light level. We have recently developed a structural description of human visual sensitivity that we call the Pyramid of Visibility, that accomplishes this synthesis. This talk shows how this structure accommodates all the dimensions described above, and how it can be used to solve a wide variety of problems in display engineering.*

**Andrew B. Watson**, chief vision scientist, Apple Inc. (United States)

*Andrew Watson is Chief Vision Scientist at Apple, where he leads the application of vision science to technologies, applications, and displays. His research focuses on computational models of early vision. He is the author of more than 100 scientific papers and 8 patents. He has 21,180 citations and an h-index of 63. Watson founded the Journal of Vision, and served as editor-in-chief 2001-2013 and 2018-2022. Watson has received numerous awards including the Presidential Rank Award from the President of the United States.*