

# **2023 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS 2023)**

**Detroit, Michigan, USA  
1-5 October 2023**

**Pages 1-607**



**IEEE Catalog Number:** CFP23IRO-POD  
**ISBN:** 978-1-6654-9191-4

**Copyright © 2023 by the Institute of Electrical and Electronics Engineers, Inc.  
All Rights Reserved**

*Copyright and Reprint Permissions:* Abstracting is permitted with credit to the source. Libraries are permitted to photocopy beyond the limit of U.S. copyright law for private use of patrons those articles in this volume that carry a code at the bottom of the first page, provided the per-copy fee indicated in the code is paid through Copyright Clearance Center, 222 Rosewood Drive, Danvers, MA 01923.

For other copying, reprint or republication permission, write to IEEE Copyrights Manager, IEEE Service Center, 445 Hoes Lane, Piscataway, NJ 08854. All rights reserved.

**\*\*\* *This is a print representation of what appears in the IEEE Digital Library. Some format issues inherent in the e-media version may also appear in this print version.***

|                         |                   |
|-------------------------|-------------------|
| IEEE Catalog Number:    | CFP23IRO-POD      |
| ISBN (Print-On-Demand): | 978-1-6654-9191-4 |
| ISBN (Online):          | 978-1-6654-9190-7 |
| ISSN:                   | 2153-0858         |

**Additional Copies of This Publication Are Available From:**

Curran Associates, Inc  
57 Morehouse Lane  
Red Hook, NY 12571 USA  
Phone: (845) 758-0400  
Fax: (845) 758-2633  
E-mail: [curran@proceedings.com](mailto:curran@proceedings.com)  
Web: [www.proceedings.com](http://www.proceedings.com)

## TABLE OF CONTENTS

|   |     |
|---|-----|
| Prototypical Contrastive Transfer Learning for Multimodal Language Understanding .....                                    | 1   |
| <i>Seitaro Otsuki, Shintaro Ishikawa, Komei Sugiura</i>   |     |
| Re-Thinking Classification Confidence with Model Quality Quantification .....   | 9   |
| <i>Yancheng Pan, Huijing Zhao</i>   |     |
| Self-Supervised Drivable Area Segmentation Using LiDAR's Depth Information for Autonomous Driving .....                   | 17  |
| <i>Fulong Ma, Yang Liu, Sheng Wang, Jin Wu, Weiqing Qi, Ming Liu</i>  |     |
| Vehicle Motion Forecasting Using Prior Information and Semantic-Assisted Occupancy Grid Maps .....                        | 25  |
| <i>Rabbia Asghar, Manuel Diaz-Zapata, Lukas Rummelhard, Anne Spalanzani, Christian Laugier</i>                            |     |
| Enhance Local Feature Consistency with Structure Similarity Loss for 3D Semantic Segmentation.....                        | 31  |
| <i>Cheng-Wei Lin, Fang-Yu Syu, Yi-Ju Pan, Kuan-Wen Chen</i>   |     |
| Lightweight Semantic Segmentation Network for Semantic Scene Understanding on Low-Compute Devices .....                   | 38  |
| <i>Hojun Son, James Weiland</i>   |     |
| LiDAR-SGMOS: Semantics-Guided Moving Object Segmentation with 3D LiDAR.....   | 46  |
| <i>Shuo Gu, Suling Yao, Jian Yang, Chengzhong Xu, Hui Kong</i>  |     |
| Robust Fusion for Bayesian Semantic Mapping.....  | 52  |
| <i>David Morilla-Cabello, Lorenzo Mur-Labadia, Ruben Martinez-Cantin, Eduardo Montijano</i>                               |     |
| ConSOR: A Context-Aware Semantic Object Rearrangement Framework for Partially Arranged Scenes.....                        | 58  |
| <i>Kartik Ramachandruni, Max Zuo, Sonia Chernova</i>  |     |
| IDA: Informed Domain Adaptive Semantic Segmentation .....   | 66  |
| <i>Zheng Chen, Zhengming Ding, Jason M. Gregory, Lantao Liu</i>   |     |
| A Handle Robot for Providing Bodily Support to Elderly Persons .....  | 74  |
| <i>Roberto Bolli, Paolo Bonato, H. Harry Asada</i>  |     |
| A Hybrid FNS Generator for Human Trunk Posture Control with Incomplete Knowledge of Neuromusculoskeletal Dynamics .....   | 82  |
| <i>Xuefeng Bao, Aidan R. Friederich, Ronald J. Triolo, Musa L. Audu</i>   |     |
| Insole-Type Walking Assist Device Capable of Inducing Inversion-Eversion of the Ankle Angle to the Neutral Position ..... | 89  |
| <i>Taku Itami, Kazuki Date, Yuta Ishii, Jun Yoneyama, Takaaki Aoki</i>  |     |
| Design for Hip Abduction Assistive Device Based on Relationship Between Hip Joint Motion and Torque During Running.....   | 95  |
| <i>Myunghyun Lee, Man Bok Hong, Gwang Tae Kim, Seonwoo Kim</i>  |     |
| Dynamic Hand Proprioception Via a Wearable Glove with Fabric Sensors.....   | 101 |
| <i>Lily Behnke, Lina Sanchez-Botero, William R. Johnson, Anjali Agrawala, Rebecca Kramer-Bottiglio</i>                    |     |

|  |     |
|--|-----|
| A Wearable Robotic Rehabilitation System for Neuro-Rehabilitation Aimed at Enhancing<br>Mediolateral Balance.....              | 107 |
| <i>Zhenyu Yu, Varun Nalam, Abbas Alili, He Helen Huang</i>   |     |
| Analysis of Lower Extremity Shape Characteristics in Various Walking Situations for the<br>Development of Wearable Robot.....  | 113 |
| <i>Joohyun Park, Ho Seon Choi, Hyunki In</i>   |     |
| Finding Biomechanically Safe Trajectories for Robot Manipulation of the Human Body in a Search<br>and Rescue Scenario.....     | 119 |
| <i>Elizabeth Peiros, Zih-Yun Chiu, Yuheng Zhi, Nikhil Shinde, Michael C. Yip</i>   |     |
| Dynamic Multi-Query Motion Planning with Differential Constraints and Moving Goals .....                                       | 126 |
| <i>Michael Gentner, Fabian Zillenbiller, Andre Kraft, Eckehard Steinbach</i>   |     |
| Reactive and Safe Co-Navigation with Haptic Guidance.....  | 134 |
| <i>Mela Coffey, Dawei Zhang, Roberto Tron, Alyssa Pierson</i>  |     |
| An MCTS-DRL Based Obstacle and Occlusion Avoidance Methodology in Robotic Follow-Ahead<br>Applications.....                    | 142 |
| <i>Sahar Leisiazar, Edward J. Park, Angelica Lim, Mo Chen</i>  |     |
| Proactive Model Predictive Control with Multi-Modal Human Motion Prediction in Cluttered<br>Dynamic Environments .....         | 150 |
| <i>Lukas Heuer, Luigi Palmieri, Andrey Rudenko, Anna Mannucci, Martin Magnusson, Kai O.<br/>Arras</i>                          |     |
| A Novel Obstacle-Avoidance Solution with Non-Iterative Neural Controller for Joint-Constrained<br>Redundant Manipulators ..... | 158 |
| <i>Weibing Li, Zilian Yi, Yanying Zou, Haimei Wu, Yang Yang, Yongping Pan</i>  |     |
| TTC4MCP: Monocular Collision Prediction Based on Self-Supervised TTC Estimation .....  | 165 |
| <i>Changlin Li, Yeqiang Qian, Cong Sun, Weihao Yan, Chunxiang Wang, Ming Yang</i>  |     |
| DAMON: Dynamic Amorphous Obstacle Navigation Using Topological Manifold Learning and<br>Variational Autoencoding .....         | 172 |
| <i>Apan Dastider, Mingjie Lin</i>  |     |
| Gatekeeper: Online Safety Verification and Control for Nonlinear Systems in Dynamic<br>Environments.....                       | 180 |
| <i>Devansh Agrawal, Ruichang Chen, Dimitra Panagou</i>   |     |
| Combinatorial Disjunctive Constraints for Obstacle Avoidance in Path Planning .....  | 188 |
| <i>Raul Garcia, Illya V. Hicks, Joey Huchette</i>  |     |
| Reachability-Aware Collision Avoidance for Tractor-Trailer System with Non-Linear MPC and<br>Control Barrier Function .....    | 195 |
| <i>Yucheng Tang, Ilshat Mamaev, Jing Qin, Christian Wurll, Björn Hein</i>  |     |
| Continuous Implicit SDF Based Any-Shape Robot Trajectory Optimization .....  | 203 |
| <i>Tingrui Zhang, Jingping Wang, Chao Xu, Alan Gao, Fei Gao</i>  |     |
| Robo-Centric ESDF: A Fast and Accurate Whole-Body Collision Evaluation Tool for Any-Shape<br>Robotic Planning .....            | 211 |
| <i>Shuang Geng, Qianhao Wang, Lei Xie, Chao Xu, Yanjun Cao, Fei Gao</i>  |     |

|   |     |
|---|-----|
| Global Map Assisted Multi-Agent Collision Avoidance Via Deep Reinforcement Learning Around Complex Obstacles.....   | 219 |
| <i>Yuanyuan Du, Jianan Zhang, Jie Xu, Xiang Cheng, Shuguang Cui</i>   |     |
| Aggregating Single-Wheeled Mobile Robots for Omnidirectional Movements .....  | 227 |
| <i>Meng Wang, Yao Su, Hang Li, Jiarui Li, Jixiang Liang, Hangxin Liu</i>  |     |
| Smooth Stride Length Change of Rat Robot with a Compliant Actuated Spine Based on CPG Controller .....  | 234 |
| <i>Yuhong Huang, Zhenshan Bing, Zitao Zhang, Kai Huang, Fabrice O. Morin, Alois Knoll</i>   |     |
| Learning Terrain-Adaptive Locomotion with Agile Behaviors by Imitating Animals .....  | 242 |
| <i>Tingguang Li, Yizheng Zhang, Chong Zhang, Qingxu Zhu, Jiapeng Sheng, Wanchao Chi, Cheng Zhou, Lei Han</i>  |     |
| A Stable Adaptive Extended Kalman Filter for Estimating Robot Manipulators Link Velocity and Acceleration.....  | 249 |
| <i>Seyed Ali Baradaran Birjandi, Harshit Khurana, Aude Billard, Sami Haddadin</i>   |     |
| Provably Correct Sensor-Driven Path-Following for Unicycles Using Monotonic Score Functions.....  | 257 |
| <i>Benton Clark, Varun Hariprasad, Hasan A. Poonawala</i>   |     |
| Contact Reduction with Bounded Stiffness for Robust Sim-To-Real Transfer of Robot Assembly.....   | 264 |
| <i>Nghia Vuong, Quang-Cuong Pham</i>  |     |
| Trajectory Tracking Via Multiscale Continuous Attractor Networks .....  | 271 |
| <i>Therese Joseph, Tobias Fischer, Michael Milford</i>  |     |
| Design and Control of a Ballbot Drivetrain with High Agility, Minimal Footprint, and High Payload .....   | 279 |
| <i>Chenzhang Xiao, Mahshid Mansouri, David Lam, Joao Ramos, Elizabeth T. Hsiao-Wecksler</i>   |     |
| A Bayesian Reinforcement Learning Method for Periodic Robotic Control Under Significant Uncertainty .....   | 287 |
| <i>Yuanyuan Jia, Pedro Miguel Uriguen Eljuri, Tadahiro Taniguchi</i>  |     |
| Residual Physics Learning and System Identification for Sim-To-Real Transfer of Policies on Buoyancy Assisted Legged Robots .....                             | 295 |
| <i>Nitish Sontakke, Hosik Chae, Sangjoon Lee, Tianle Huang, Dennis W. Hong, Sehoon Hal</i>  |     |
| DiffClothAI: Differentiable Cloth Simulation with Intersection-Free Frictional Contact and Differentiable Two-Way Coupling with Articulated Rigid Bodies..... | 303 |
| <i>Xinyuan Yu, Siheng Zhao, Siyuan Luo, Gang Yang, Lin Shao</i>   |     |
| Timor Python: A Toolbox for Industrial Modular Robotics.....  | 311 |
| <i>Jonathan Külz, Matthias Mayer, Matthias Althoff</i>  |     |
| Ultra-Low Inertia 6-DOF Manipulator Arm for Touching the World.....   | 319 |
| <i>Kazutoshi Nishii, Akira Hatano, Yoshihiro Okumatsu</i>   |     |
| Determination of the Characteristics of Gears of Robot-Like Systems by Analytical Description of Their Structure.....   | 326 |
| <i>Stefan Landler; Raúl Molina Blanco, Michael Otto, Birgit Vogel-Heuser, Markus Zimmermann, Karsten Stahl</i>  |     |
| Tension Jamming for Deployable Structures.....  | 333 |
| <i>Daniel Hasegawa, Buse Aktas, Robert D. Howe</i>  |     |

|   |     |
|---|-----|
| Task2Morph: Differentiable Task-Inspired Framework for Contact-Aware Robot Design .....   | 339 |
| <i>Yishuai Cai, Shaowu Yang, Minglong Li, Xinglin Chen, Yunxin Mao, Xiaodong Yi, Wenjing Yang</i>   |     |
| Constraint Programming for Component-Level Robot Design .....   | 347 |
| <i>Andrew Wilhelm, Nils Napp</i>  |     |
| Design and Implementation of a Two-Limbed 3T1R Haptic Device .....  | 354 |
| <i>Long Kang, Yang Yang, Byung-Ju Yi</i>  |     |
| Combining Measurement Uncertainties with the Probabilistic Robustness for Safety Evaluation of Robot Systems .....                        | 360 |
| <i>Woo-Jeong Baek, Christoph Ledermann, Tamim Asfour, Torsten Kröger</i>  |     |
| Computational Design of Closed-Chain Linkages: Respawn Algorithm for Generative Design .....  | 368 |
| <i>Dmitriy V. Ivolga, Ivan I. Borisov, Kirill V. Nasonov, Sergey A. Kolyubin</i>  |     |
| On Designing a Learning Robot: Improving Morphology for Enhanced Task Performance and Learning .....                                      | 374 |
| <i>Maks Sorokin, Chuyuan Fu, Jie Tan, C. Karen Liu, Yunfei Bai, Wenlong Lu, Sehoon Ha, Mohi Khansari</i>                                  |     |
| Development of a Dynamic Quadruped with Tunable, Compliant Legs .....   | 382 |
| <i>Fuchen Chen, Weijia Tao, Daniel M. Aukes</i>   |     |
| Soft Robot Shape Estimation: A Load-Agnostic Geometric Method .....   | 390 |
| <i>Christian Sorensen, Marc D. Killpack</i>   |     |
| Robust Generalized Proportional Integral Control for Trajectory Tracking of Soft Actuators in a Pediatric Wearable Assistive Device ..... | 397 |
| <i>Caio Mucchiani, Zhichao Liu, Ipsita Sahin, Elena Kokkoni, Konstantinos Karydis</i>   |     |
| Data-Efficient Online Learning of Ball Placement in Robot Table Tennis .....  | 405 |
| <i>Philip Tobuschat, Hao Ma, Dieter Büchler, Bernhard Schölkopf, Michael Muehlebach</i>   |     |
| Learning Reduced-Order Soft Robot Controller .....  | 412 |
| <i>Chen Liang, Xifeng Gao, Kui Wu, Zherong Pan</i>  |     |
| A Single-Parameter Model for Soft Bellows Actuators Under Axial Deformation and Loading .....   | 420 |
| <i>Emma Treadway, Melissa Brei, Audrey Sedal, R. Brent Gillespie</i>  |     |
| Task and Configuration Space Compliance of Continuum Robots Via Lie Group and Modal Shape Formulations .....                              | 428 |
| <i>Andrew L. Orekhov, Garrison L. H. Johnston, Nabil Simaan</i>   |     |
| A Localization Framework for Boundary Constrained Soft Robots .....   | 436 |
| <i>Koki Tanaka, Qiyuan Zhou, Ankit Srivastava, Matthew Spenko</i>   |     |
| EViper: A Scalable Platform for Untethered Modular Soft Robots .....  | 442 |
| <i>Hsin Cheng, Zhiwu Zheng, Prakhar Kumar, Wali Afridi, Ben Kim, Sigurd Wagner, Naveen Verma, James C. Sturm, Minjie Chen</i>             |     |
| Domain Randomization for Robust, Affordable and Effective Closed-Loop Control of Soft Robots .....  | 450 |
| <i>Gabriele Tiboni, Andrea Protopapa, Tatiana Tommasi, Giuseppe Averta</i>  |     |

|   |     |
|---|-----|
| Implementation of a Cosserat Rod-Based Configuration Tracking Controller on a Multi-Segment Soft Robotic Arm.....                   | 458 |
| <i>Azadeh Doroudchi, Zhi Qiao, Wenlong Zhang, Spring Berman</i>   |     |
| IF-Based Trajectory Planning and Cooperative Control for Transportation System of Cable Suspended Payload with Multi UAVs .....     | 465 |
| <i>Yu Zhang, Jie Xu, Cheng Zhao, Jiuxiang Dong</i>  |     |
| Cooperative Dual-Arm Control for Heavy Object Manipulation Based on Hierarchical Quadratic Programming.....                         | 473 |
| <i>Maximilian Dio, Andreas Völz, Knut Graichen</i>  |     |
| Multi-UAV Adaptive Path Planning Using Deep Reinforcement Learning .....  | 479 |
| <i>Jonas Westheider, Julius Rückin, Marija Popovic</i>  |     |
| Emergent Cooperative Behavior in Distributed Target Tracking with Unknown Occlusions .....  | 487 |
| <i>Tianqi Li, Lucas W. Krakow, Swaminathan Gopalswamy</i>   |     |
| Multi-Objective Sparse Sensing with Ergodic Optimization.....   | 495 |
| <i>Ananya Rao, Howie Choset</i>   |     |
| Team Coordination on Graphs with State-Dependent Edge Costs .....   | 501 |
| <i>Manshi Limbu, Zechen Hu, Sara Oughourli, Xuan Wang, Xuesu Xiao, Daigo Shishika</i>   |     |
| Incorporating Stochastic Human Driving States in Cooperative Driving Between a Human-Driven Vehicle and an Autonomous Vehicle ..... | 507 |
| <i>Sanzida Hossain, Jiaxing Lu, He Bai, Weihua Sheng</i>  |     |
| Epistemic Planning for Heterogeneous Robotic Systems.....   | 513 |
| <i>Lauren Bramblett, Nicola Bezzo</i>   |     |
| Reinforced Potential Field for Multi-Robot Motion Planning in Cluttered Environments.....   | 521 |
| <i>Dengyu Zhang, Xinyu Zhang, Zheng Zhang, Bo Zhu, Qingrui Zhang</i>  |     |
| Robot Team Data Collection with Anywhere Communication.....   | 527 |
| <i>Matthew A. Schack, John G. Rogers, Qi Han, Neil T. Dantam</i>  |     |
| Coordination of Multiple Mobile Manipulators for Ordered Sorting of Cluttered Objects.....  | 534 |
| <i>Jeeho Ahn, Seabin Lee, Changjoo Nam</i>  |     |
| MOTLEE: Distributed Mobile Multi-Object Tracking with Localization Error Elimination.....   | 541 |
| <i>Mason B. Peterson, Parker C. Lusk, Jonathan P. How</i>   |     |
| Dynamic Object Tracking for Quadruped Manipulator with Spherical Image-Based Approach .....   | 549 |
| <i>Tianlin Zhang, Sikai Guo, Xiaogang Xiong, Wanlei Li, Zeheng Qi, Yunjiang Lou</i>   |     |
| Proprioception and Tail Control Enable Extreme Terrain Traversal by Quadruped Robots .....  | 557 |
| <i>Yanhao Yang, Joseph Norby, Justin K. Yim, Aaron M. Johnson</i>   |     |
| Run and Catch: Dynamic Object-Catching of Quadrupedal Robots .....  | 565 |
| <i>Yangwei You, Tianlin Liu, Xiaowei Liang, Zhe Xu, Mingliang Zhou, Zhibin Li, Shiwu Zhang</i>                                      |     |
| A Composite Control Strategy for Quadruped Robot by Integrating Reinforcement Learning and Model-Based Control .....                | 573 |
| <i>Shangke Lyu, Han Zhao, Donglin Wang</i>  |     |

|   |     |
|---|-----|
| Load Awareness: Sensorless Body Payload Sensing and Localization for Heavy Quadruped Robot .....                                  | 581 |
| <i>Shaoxun Liu, Shiyu Zhou, Zheng Pan, Zhihua Niu, Rongrong Wang</i>  |     |
| Evolutionary-Based Online Motion Planning Framework for Quadruped Robot Jumping.....  | 589 |
| <i>Linzhu Yue, Zhitao Song, Hongbo Zhang, Xuanqi Zeng, Lingwei Zhang, Yun-Hui Liu</i>   |     |
| Multi-IMU Proprioceptive Odometry for Legged Robots.....  | 596 |
| <i>Shuo Yang, Zixin Zhang, Benjamin Bokser, Zachary Manchester</i>  |     |
| Design and Motion Guidelines for Quadrupedal Locomotion of Maximum Speed Or Efficiency<br>with Serial and Parallel Legs.....      | 602 |
| <i>Konstantinos Machairas, Evangelos Papadopoulos</i>   |     |
| Towards Legged Locomotion on Steep Planetary Terrain.....   | 608 |
| <i>Giorgio Valsecchi, Cedric Weibel, Hendrik Kolvenbach, Marco Hutter</i>   |     |
| Dynamic Hybrid Locomotion and Jumping for Wheeled-Legged Quadrupeds .....   | 615 |
| <i>Mojtaba Hosseini, Diego Rodriguez, Sven Behnke</i>   |     |
| Quadrupedal Footstep Planning Using Learned Motion Models of a Black-Box Controller.....  | 622 |
| <i>Ilyass Taouil, Giulio Turrisi, Daniel Schleich, Victor Barasuol, Claudio Semini, Sven Behnke</i>                               |     |
| Locomotion Planning of a Truss Robot on Irregular Terrain.....  | 629 |
| <i>Jangho Bae, Inha Park, Mark Yim, Taewon Seo</i>  |     |
| A Model Predictive Path Integral Method for Fast, Proactive, and Uncertainty-Aware UAV<br>Planning in Cluttered Environments..... | 635 |
| <i>Jacob Higgins, Nicholas Mohammad, Nicola Bezzo</i>   |     |
| Energy-Efficient Team Orienteering Problem in the Presence of Time-Varying Ocean Currents .....                                   | 643 |
| <i>Ariella Mansfield, Douglas G. Macharet, M. Ani Hsieh</i>   |     |
| Multi-Agent Multi-Objective Ergodic Search Using Branch and Bound.....  | 649 |
| <i>Akshaya Kesaramangalam Srinivasan, Geordan Gutow, Zhongqiang Ren, Ian Abraham,<br/>Bhaskar Vundurthy, Howie Choset</i>         |     |
| Leveraging Single-Goal Predictions to Improve the Efficiency of Multi-Goal Motion Planning with<br>Dynamics.....                  | 655 |
| <i>Yuanjie Lu, Erion Plaku</i>  |     |
| DynGMP: Graph Neural Network-Based Motion Planning in Unpredictable Dynamic<br>Environments.....                                  | 663 |
| <i>Wenjin Zhang, Xiao Zang, Lingyi Huang, Yang Sui, Jingjin Yu, Yingying Chen, Bo Yuan</i>  |     |
| Symbolic State Space Optimization for Long Horizon Mobile Manipulation Planning .....   | 671 |
| <i>Xiaohan Zhang, Yifeng Zhu, Yan Ding, Yuqian Jiang, Yuke Zhu, Peter Stone, Shiqi Zhang</i>                                      |     |
| A Fast and Map-Free Model for Trajectory Prediction in Traffics .....   | 678 |
| <i>Junhong Xiang, Jingmin Zhang, Zhixiong Nan</i>   |     |
| Local Non-Cooperative Games with Principled Player Selection for Scalable Motion Planning .....                                   | 685 |
| <i>Makram Chahine, Roya Firoozi, Wei Xiao, Mac Schwager, Daniela Rus</i>  |     |
| Target Attribute Perception Based UAV Real-Time Task Planning in Dynamic Environments.....  | 693 |
| <i>Jinhong He, Zheyu Sun, Ningbo Cao, Delie Ming, Chao Cai</i>  |     |

|  |     |
|--|-----|
| GraNet: A Multi-Level Graph Network for 6-DoF Grasp Pose Generation in Cluttered Scenes .....                                | 701 |
| <i>Haowen Wang, Wanhao Niu, Chungang Zhuang</i>  |     |
| Modular Neural Network Policies for Learning In-Flight Object Catching with a Robot Hand-Arm System .....                    | 708 |
| <i>Wenbin Hu, Fernando Acero, Eleftherios Triantafyllidis, Zhaocheng Liu, Zhibin Li</i>                                      |     |
| GVCCI: Lifelong Learning of Visual Grounding for Language-Guided Robotic Manipulation.....                                   | 716 |
| <i>Junghyun Kim, Gi-Cheon Kang, Jaein Kim, Suyeon Shin, Byoung-Tak Zhang</i>   |     |
| Bag All You Need: Learning a Generalizable Bagging Strategy for Heterogeneous Objects.....                                   | 724 |
| <i>Arpit Bahety, Shreya Jain, Huy Ha, Nathalie Hager, Benjamin Burchfiel, Eric Cousineau, Siyuan Feng, Shuran Song</i>       |     |
| Multi-Source Fusion for Voxel-Based 7-DoF Grasping Pose Estimation.....  | 732 |
| <i>Junning Qiu, Fei Wang, Zheng Dang</i>   |     |
| VL-Grasp: A 6-Dof Interactive Grasp Policy for Language-Oriented Objects in Cluttered Indoor Scenes.....                     | 740 |
| <i>Yuhao Lu, Yixuan Fan, Beixing Deng, Fangfu Liu, Yali Li, Shengjin Wang</i>  |     |
| QDP: Learning to Sequentially Optimise Quasi-Static and Dynamic Manipulation Primitives for Robotic Cloth Manipulation ..... | 748 |
| <i>David Blanco-Mulero, Gokhan Alcan, Fares J. Abu-Dakka, Ville Kyrki</i>  |     |
| Robust Visual Sim-To-Real Transfer for Robotic Manipulation .....  | 756 |
| <i>Ricardo Garcia, Robin Strudel, Shizhe Chen, Etienne Arlaud, Ivan Laptev, Cordelia Schmid</i>                              |     |
| Multi-Dimensional Deformable Object Manipulation Using Equivariant Models.....   | 764 |
| <i>Tianyu Fu, Yang Tang, Tianyu Wu, Xiaowu Xia, Jianrui Wang, Chaoqiang Zhao</i>   |     |
| Adversarial Object Rearrangement in Constrained Environments with Heterogeneous Graph Neural Networks .....                  | 772 |
| <i>Xibai Lou, Houjian Yu, Ross Worobel, Yang Yang, Changhyun Choi</i>  |     |
| Probabilistic Slide-Support Manipulation Planning in Clutter .....   | 780 |
| <i>Shusei Nagato, Tomohiro Motoda, Takao Nishi, Petit Damien, Takuya Kiyokawa, Weiwei Wan, Kensuke Harada</i>                |     |
| GOATS: Goal Sampling Adaptation for Scooping with Curriculum Reinforcement Learning.....                                     | 787 |
| <i>Yaru Niu, Shiyu Jin, Zeqing Zhang, Jiacheng Zhu, Ding Zhao, Liangjun Zhang</i>  |     |
| Tight Collision Probability for UAV Motion Planning in Uncertain Environment .....   | 795 |
| <i>Tianyu Liu, Fu Zhang, Fei Gao, Jia Pan</i>  |     |
| Dodging Like a Bird: An Inverted Dive Maneuver Taking by Lifting-Wing Multicopters .....                                     | 803 |
| <i>Wenhan Gao, Shuai Wang, Quan Quan</i>   |     |
| Model-Based Planning and Control for Terrestrial-Aerial Bimodal Vehicles with Passive Wheels.....                            | 810 |
| <i>Ruimin Zhang, Junxiao Lin, Yuze Wu, Yuman Gao, Chi Wang, Chao Xu, Yanjun Cao, Fei Gao</i>                                 |     |
| Polynomial-Based Online Planning for Autonomous Drone Racing in Dynamic Environments.....                                    | 818 |
| <i>Qianhao Wang, Dong Wang, Chao Xu, Alan Gao, Fei Gao</i>   |     |
| Autonomous Power Line Inspection with Drones Via Perception-Aware MPC.....   | 826 |
| <i>Jiaxu Xing, Giovanni Cioffi, Javier Hidalgo-Carrió, Davide Scaramuzza</i>   |     |

|  |     |
|--|-----|
| A Perching and Tilting Aerial Robot for Precise and Versatile Power Tool Work on Vertical Walls.....   | 834 |
| <i>Roman Dautzenberg, Timo Küster, Timon Mathis, Yann Roth, Curdin Steinauer, Gabriel Käppeli, Julian Santen, Alina Arranhado, Friederike Biffar, Till Kötter, Christian Lanegger, Mike Allenspach, Roland Siegwart, Rik Bähnemann</i> |     |
| Resource-Constrained Station-Keeping for Latex Balloons Using Reinforcement Learning .....   | 842 |
| <i>Jack Saunders, Loïc Prenevost, Özgür Simsek, Alan Hunter, Wenbin Li</i>   |     |
| A Light-Weight, Low-Cost, and Sustainable Planning System for UAVs Using a Local Map Origin Update Approach.....   | 850 |
| <i>Dasol Lee, Jinche La, Sanghyun Joo</i>  |     |
| Bubble Explorer: Fast UAV Exploration in Large-Scale and Cluttered 3D-Environments Using Occlusion-Free Spheres.....   | 858 |
| <i>Benxu Tang, Yunfan Ren, Fangcheng Zhu, Rui He, Siqi Liang, Fanze Kong, Fu Zhang</i>   |     |
| UPPLIED: UAV Path Planning for Inspection Through Demonstration.....   | 866 |
| <i>Shyam Sundar Kannan, Vishnunandan L. N. Venkatesh, Revanth Krishna Senthilkumaran, Byung-Cheol Min</i>  |     |
| Self-Supervised Instance Segmentation by Grasping.....   | 874 |
| <i>Yuxuan Liu, Xi Chen, Pieter Abbeel</i>  |     |
| Fusing Visual Appearance and Geometry for Multi-Modality 6DoF Object Tracking.....   | 882 |
| <i>Manuel Stoiber, Mariam Elsayed, Anne E. Reichert, Florian Steidle, Dongheui Lee, Rudolph Triebel</i>  |     |
| Viewpoint Push Planning for Mapping of Unknown Confined Spaces.....  | 890 |
| <i>Nils Dengler, Sicong Pan, Vamsi Kalagaturu, Rohit Menon, Murad Dawood, Maren Bennewitz</i>  |     |
| Depth-Based 6DoF Object Pose Estimation Using Swin Transformer.....  | 897 |
| <i>Zhujun Li, Ioannis Stamos</i>   |     |
| DR-Pose: A Two-Stage Deformation-And-Registration Pipeline for Category-Level 6D Object Pose Estimation.....   | 904 |
| <i>Lei Zhou, Zhiyang Liu, Runze Gan, Haozhe Wang, Marcelo H. Ang</i>   |     |
| Learning from Pixels with Expert Observations.....   | 912 |
| <i>Minh-Huy Hoang, Long Dinh, Hai Nguyen</i>   |     |
| RMBench: Benchmarking Deep Reinforcement Learning for Robotic Manipulator Control.....   | 919 |
| <i>Yanfei Xiang, Xin Wang, Shu Hu, Bin Zhu, Xiaomeng Huang, Xi Wu, Siwei Lyu</i>   |     |
| Shape Completion with Prediction of Uncertain Regions .....  | 927 |
| <i>Matthias Humt, Dominik Winkelbauer, Ulrich Hillenbrand</i>  |     |
| Structure from Action: Learning Interactions for 3D Articulated Object Structure Discovery .....   | 934 |
| <i>Neil Nie, Samir Yitzhak Gadre, Kiana Ehsani, Shuran Song</i>  |     |
| Object-Oriented Option Framework for Robotics Manipulation in Clutter.....   | 942 |
| <i>Jing-Cheng Pang, Si-Hang Yang, Xiong-Hui Chen, Xinyu Yang, Yang Yu, Mas Ma, Ziqi Guo, Howard Yang, Bill Huang</i>   |     |
| Weakly Supervised Referring Expression Grounding Via Dynamic Self-Knowledge Distillation .....   | 950 |
| <i>Jinpeng Mi, Zhiqian Chen, Jianwei Zhang</i>   |     |

|  |      |
|--|------|
| EventTransAct: A Video Transformer-Based Framework for Event-Camera Based Action Recognition .....   | 957  |
| <i>Tristan De Blegiers, Ishan Rajendrakumar Dave, Adeel Yousaf, Mubarak Shah</i>   |      |
| Virtual Ski Training System that Allows Beginners to Acquire Ski Skills Based on Physical and Visual Feedbacks .....                       | 964  |
| <i>Yushi Okada, Chanjin Seo, Shunichi Miyakawa, Motofumi Taniguchi, Kazuyuki Kanosue, Hiroyuki Ogata, Jun Ohya</i>                         |      |
| Attention-Based VR Facial Animation with Visual Mouth Camera Guidance for Immersive Telepresence Avatars .....                             | 972  |
| <i>Andre Rochow, Max Schwarz, Sven Behnke</i>  |      |
| Test-Time Adaptation for Point Cloud Upsampling Using Meta-Learning .....  | 980  |
| <i>Ahmed Hatem, Yiming Qian, Yang Wang</i>   |      |
| Revisiting Event-Based Video Frame Interpolation .....   | 988  |
| <i>Jiaben Chen, Yichen Zhu, Dongze Lian, Jiaqi Yang, Yifu Wang, Renrui Zhang, Xinhang Liu, Shenhan Qian, Laurent Kneip, Shenghua Gao</i>   |      |
| Revisiting Deformable Convolution for Depth Completion.....  | 996  |
| <i>Xinglong Sun, Jean Ponce, Yu-Xiong Wang</i>   |      |
| Long-Distance Gesture Recognition Using Dynamic Neural Networks .....  | 1003 |
| <i>Shubhang Bhatnagar, Sharath Gopal, Narendra Ahuja, Liu Ren</i>  |      |
| Neural Implicit Vision-Language Feature Fields.....  | 1009 |
| <i>Kenneth Blomqvist, Francesco Milano, Jen Jen Chung, Lionel Ott, Roland Siegwart</i>   |      |
| Language Guided Robotic Grasping with Fine-Grained Instructions .....  | 1015 |
| <i>Qiang Sun, Haitao Lin, Ying Fu, Yanwei Fu, Xiangyang Xue</i>  |      |
| Whole Shape Estimation of Transparent Object from Its Contour Using Statistical Shape Model.....   | 1023 |
| <i>Kaihei Okada, Riku Kobayashi, Tokuo Tsuji, Tatsuhiro Hiramitsu, Hiroaki Seki, Toshihiro Nishimura, Yosuke Suzuki, Tetsuyou Watanabe</i> |      |
| Off the Radar: Uncertainty-Aware Radar Place Recognition with Introspective Querying and Map Maintenance .....                             | 1030 |
| <i>Jianhao Yuan, Paul Newman, Matthew Gadd</i>   |      |
| Global Localization in Unstructured Environments Using Semantic Object Maps Built from Various Viewpoints.....                             | 1038 |
| <i>Jacqueline Ankenbauer, Parker C. Lusk, Annika Thomas, Jonathan P. How</i>   |      |
| Constructing Metric-Semantic Maps Using Floor Plan Priors for Long-Term Indoor Localization .....  | 1046 |
| <i>Nicky Zimmerman, Matteo Sodano, Elias Marks, Jens Behley, Cyrill Stachniss</i>  |      |
| DisPlacing Objects: Improving Dynamic Vehicle Detection Via Visual Place Recognition Under Adverse Conditions .....                        | 1053 |
| <i>Stephen Hausler, Sourav Garg, Punarjay Chakravarty, Shubham Shrivastava, Ankit Vora, Michael Milford</i>                                |      |
| FM-Loc: Using Foundation Models for Improved Vision-Based Localization .....   | 1061 |
| <i>Reihaneh Mirjalili, Michael Krawez, Wolfram Burgard</i>   |      |
| Joint On-Manifold Gravity and Accelerometer Intrinsics Estimation for Inertially Aligned Mapping .....                                     | 1068 |
| <i>Ryan Nemiroff, Kenny Chen, Brett T. Lopez</i>   |      |

|  |      |
|--|------|
| I2P-Rec: Recognizing Images on Large-Scale Point Cloud Maps Through Bird's Eye View Projections.....                                 | 1075 |
| <i>Shuhang Zheng, Yixuan Li, Zhu Yu, Beinan Yu, Si-Yuan Cao, Minhang Wang, Jintao Xu, Rui Ai, Weihao Gu, Lun Luo, Hui-Liang Shen</i> |      |
| LIO-PPF: Fast LiDAR-Inertial Odometry Via Incremental Plane Pre-Fitting and Skeleton Tracking.....                                   | 1081 |
| <i>Xingyu Chen, Peixi Wu, Ge Li, Thomas H. Li</i>  |      |
| EDI: ESKF-Based Disjoint Initialization for Visual-Inertial SLAM Systems.....  | 1089 |
| <i>Weihan Wang, Jiani Li, Yuhang Ming, Philippos Mordohai</i>  |      |
| SELVO: A Semantic-Enhanced Lidar-Visual Odometry .....   | 1096 |
| <i>Kun Jiang, Shuang Gao, Xudong Zhang, Jijunnan Li, Yandong Guo, Shijie Liu, Chunlai Li, Jianyu Wang</i>                            |      |
| LIWO: LiDAR-Inertial-Wheel Odometry.....   | 1104 |
| <i>Zikang Yuan, Fengtian Lang, Tianle Xu, Xin Yang</i>   |      |
| VIW-Fusion: Extrinsic Calibration and Pose Estimation for Visual-IMU-Wheel Encoder System .....                                      | 1112 |
| <i>Chunxiao Qiao, Shuying Zhao, Yunzhou Zhang, Yahui Wang, Dan Zhang</i>   |      |
| LiDAR-Inertial SLAM with Efficiently Extracted Planes.....   | 1120 |
| <i>Chao Chen, Hangyu Wu, Yukai Ma, Jiajun Lv, Laijian Li, Yong Liu</i>   |      |
| Learning to Map Efficiently by Active Echolocation.....  | 1128 |
| <i>Xixi Hu, Senthil Purushwalkam, David Harwath, Kristen Grauman</i>   |      |
| Visual-LiDAR-Inertial Odometry: A New Visual-Inertial SLAM Method Based on an iPhone 12 Pro .....                                    | 1134 |
| <i>Lingqiu Jin, Cang Ye</i>  |      |
| Optimization-Based VINS: Consistency, Marginalization, and FEJ .....   | 1140 |
| <i>Chuchu Chen, Patrick Geneva, Yuxiang Peng, Woosik Lee, Guoquan Huang</i>  |      |
| Visual-Inertial-Laser-Lidar (VILL) SLAM: Real-Time Dense RGB-D Mapping for Pipe Environments.....                                    | 1148 |
| <i>Tina Tian, Luyuan Wang, Xinzhi Yan, Fujun Ruan, G. Jaya Aadityaa, Howie Choset, Lu Li</i>   |      |
| Joint Imitation Learning of Behavior Decision and Control for Autonomous Intersection Navigation .....                               | 1155 |
| <i>Zeyu Zhu, Huijing Zhao</i>  |      |
| Improving the Performance of Backward Chained Behavior Trees that Use Reinforcement Learning .....                                   | 1163 |
| <i>Mart Kartasev, Justin Salér, Petter Ögren</i>   |      |
| Fast Decision Support for Air Traffic Management at Urban Air Mobility Vertiports Using Graph Learning .....                         | 1171 |
| <i>Prajit Krishnakumar, Jhoel Witter, Steve Paul, Hanvit Cho, Karthik Dantu, Souma Chowdhury</i>                                     |      |
| Scaling Vision-Based End-To-End Autonomous Driving with Multi-View Attention Learning.....   | 1177 |
| <i>Yi Xiao, Felipe Codevilla, Diego Porres, Antonio M. López</i>   |      |
| Value of Assistance for Mobile Agents.....   | 1185 |
| <i>Adi Amuzig, David Dovrat, Sarah Keren</i>   |      |

|   |      |
|---|------|
| Feature Explanation for Robust Trajectory Prediction .....  | 1192 |
| <i>Xukai Zhai, Renze Hu, Zhishuai Yin</i>   |      |
| Adversarial Driving Behavior Generation Incorporating Human Risk Cognition for Autonomous Vehicle Evaluation.....                 | 1200 |
| <i>Zhen Liu, Hang Gao, Hao Ma, Shuo Cai, Yunfeng Hu, Ting Qu, Hong Chen, Xun Gong</i>   |      |
| Predicting Center of Mass by Iterative Pushing for Object Transportation and Manipulation.....                                    | 1206 |
| <i>Steven M. Hyland, Jing Xiao, Cagdas D. Onal</i>  |      |
| The Impact of Overall Optimization on Warehouse Automation .....  | 1212 |
| <i>Hiroshi Yoshitake, Pieter Abbeel</i>   |      |
| Kinematics-Only Differential Flatness Based Trajectory Tracking for Autonomous Racing.....  | 1220 |
| <i>Yashom Dighe, Youngjin Kim, Smit Rajguru, Yash Turkar, Tarunraj Singh, Karthik Dantu</i>                                       |      |
| LEF: Late-To-Early Temporal Fusion for LiDAR 3D Object Detection .....  | 1228 |
| <i>Tong He, Pei Sun, Zhaoqi Leng, Chenxi Liu, Dragomir Anguelov, Mingxing Tan</i>   |      |
| Hierarchical Decision Transformer.....  | 1236 |
| <i>André Correia, Luis A. Alexandre</i>   |      |
| Imitation-Guided Multimodal Policy Generation from Behaviourally Diverse Demonstrations .....                                     | 1242 |
| <i>Shibei Zhu, Rituraj Kaushik, Samuel Kaski, Ville Kyrki</i>   |      |
| Model-Based Adversarial Imitation Learning from Demonstrations and Human Reward.....  | 1250 |
| <i>Jie Huang, Jiangshan Hao, Rongshun Juan, Randy Gomez, Keisuke Nakarnura, Guangliang Li</i>                                     |      |
| Interpretable Motion Planner for Urban Driving Via Hierarchical Imitation Learning .....  | 1258 |
| <i>Bikun Wang, Zhipeng Wang, Chenhao Zhu, Zhiqiang Zhang, Zhichen Wang, Penghong Lin, Jingchu Liu, Qian Zhang</i>                 |      |
| Hierarchical Imitation Learning for Stochastic Environments .....   | 1264 |
| <i>Maximilian Igl, Punit Shah, Paul Mougin, Sirish Srinivasan, Tarun Gupta, Brandyn White, Kyriacos Shiarlis, Shimon Whiteson</i> |      |
| Efficient Deep Learning of Robust, Adaptive Policies Using Tube MPC-Guided Data Augmentation .....                                | 1272 |
| <i>Tong Zhao, Andrea Tagliabue, Jonathan P. How</i>   |      |
| Masked Imitation Learning: Discovering Environment-Invariant Modalities in Multimodal Demonstrations.....                         | 1280 |
| <i>Yilun Hao, Ruinan Wang, Zhangjie Cao, Zihan Wang, Yuchen Cui, Dorsa Sadigh</i>   |      |
| Does Unpredictability Influence Driving Behavior? .....   | 1287 |
| <i>Sepehr Samavi, Florian Shkurti, Angela P. Schoellig</i>  |      |
| From Temporal-Evolving to Spatial-Fixing: A Keypoints-Based Learning Paradigm for Visual Robotic Manipulation.....                | 1295 |
| <i>Kevin Riou, Kaiwen Dong, Kevin Subrin, Yanjing Sun, Patrick Le Callet</i>  |      |
| Accurate and Interactive Visual-Inertial Sensor Calibration with Next-Best-View and Next-Best-Trajectory Suggestion.....          | 1302 |
| <i>Christopher L. Choi, Binbin Xu, Stefan Leutenegger</i>   |      |

|  |      |
|--|------|
| A ROS-Based Kinematic Calibration Tool for Serial Robots.....  | 1310 |
| <i>Caroline Pascal, Olivier Doaré, Alexandre Chapoutot</i>   |      |
| FUSE-D: Framework for UAV System-Parameter Estimation with Disturbance Detection.....  | 1317 |
| <i>Christoph Böhm, Stephan Weiss</i>   |      |
| Multiplanar Self-Calibration for Mobile Cobot 3D Object Manipulation Using 2D Detectors and Depth Estimation.....                                      | 1325 |
| <i>Tuan Dang, Khang Nguyen, Manfred Huber</i>  |      |
| Labelling Lightweight Robot Energy Consumption: A Mechatronics-Based Benchmarking Metric Set.....  | 1332 |
| <i>Juan Heredia, Robin Jeanne Kirschner, Christian Schlette, Saeed Abdolshah, Sami Haddadin, Mikkel Baun Kjærgaard</i>                                 |      |
| The Role of Absolute Positioning Error in Hand-Eye Calibration and Robotic Guidance Systems: An Analysis .....   | 1340 |
| <i>Michal Chaluš, Ondrej Vanicek, Jindrich Liška</i>   |      |
| Robotic Kinematic Calibration with Only Position Data and Consideration of Non-Geometric Errors Using POE-Based Model and Gaussian Mixture Models..... | 1346 |
| <i>Xiao Luo, Yitian Xian, Mancheong Lei, Jian Li, Ke Xie, Limin Zou, Zheng Li</i>  |      |
| MOISST: Multimodal Optimization of Implicit Scene for SpatioTemporal Calibration.....  | 1353 |
| <i>Quentin Herau, Nathan Piasco, Moussab Bennehar, Luis Roldão, Dzmitry Tsishkou, Cyrille Migniot, Pascal Vasseur, Cédric Demonceaux</i>               |      |
| Automatic Spatial Radar Camera Calibration Via Geometric Constraints with Doppler-Optical Flow Fusion.....   | 1361 |
| <i>Jintian Ge, Yanxin Zhou, Baichuan Lou, Chen Lv</i>  |      |
| Extrinsic Calibration of Camera to LIDAR Using a Differentiable Checkerboard Model.....  | 1368 |
| <i>Lanke Frank Tarimo Fu, Nived Chebrolu, Maurice Fallon</i>   |      |
| Graph-Based Visual-Kinematic Fusion and Monte Carlo Initialization for Fast-Deployable Cable-Driven Robots.....  | 1375 |
| <i>R. Khorrambakht, H. Damirchi, M. R. Dindarloo, A. Saki, S. A. Khalilpour, Hamid D. Taghirad, Stephan Weiss</i>                                      |      |
| P2O-Calib: Camera-LiDAR Calibration Using Point-Pair Spatial Occlusion Relationship.....   | 1383 |
| <i>Su Wang, Shini Zhang, Xuchong Qiu</i>   |      |
| Wrench Estimation of Modular Manipulator with External Actuation and Joint Locking .....   | 1391 |
| <i>Yonghyeok Kim, Hasun Lee, Jeongseob Lee, Dongjun Lee</i>  |      |
| AV-PedAware: Self-Supervised Audio-Visual Fusion for Dynamic Pedestrian Awareness.....   | 1398 |
| <i>Yizhuo Yang, Shenghai Yuan, Muqing Cao, Jianfei Yang, Lihua Xie</i>   |      |
| A Multitask and Kernel Approach for Learning to Push Objects with a Target-Parameterized Deep Q-Network.....   | 1405 |
| <i>Marco Ewerton, Michael Villamizar, Julius Jankowski, Sylvain Calinon, Jean-Marc Odobez</i>  |      |
| DRKF: Distilled Rotated Kernel Fusion for Efficient Rotation Invariant Descriptors in Local Feature Matching.....                                      | 1412 |
| <i>Ranran Huang, Jiancheng Cai, Chao Li, Zhuoyuan Wu, Xinmin Liu, Zhenhua Chai</i>   |      |

|  |      |
|--|------|
| Efficient Q-Learning Over Visit Frequency Maps for Multi-Agent Exploration of Unknown Environments.....  | 1420 |
| <i>Xuyang Chen, Ashvin N. Iyer, Zixing Wang, Ahmed H. Qureshi</i>  |      |
| Real-Time Trajectory-Based Social Group Detection .....  | 1428 |
| <i>Simindokht Jahangard, Munawar Hayat, Hamid Rezatofighi</i>  |      |
| Point2Point: A Framework for Efficient Deep Learning on Hilbert Sorted Point Clouds with Applications in Spatio-Temporal Occupancy Prediction..... | 1436 |
| <i>Athrva Atul Pandhare</i>  |      |
| Motion Planning Diffusion: Learning and Planning of Robot Motions with Diffusion Models .....  | 1443 |
| <i>João Carvalho, An T. Le, Mark Baierl, Dorothea Koert, Jan Peters</i>  |      |
| Active Task Randomization: Learning Robust Skills Via Unsupervised Generation of Diverse and Feasible Tasks.....                                   | 1451 |
| <i>Kuan Fang, Toki Migimatsu, Ajay Mandlekar, Li Fei-Fei, Jeannette Bohg</i>   |      |
| Robust Self-Supervised Extrinsic Self-Calibration .....  | 1459 |
| <i>Takayuki Kanai, Igor Vasiljevic, Vitor Guizilini, Adrien Gaidon, Rares Ambrus</i>   |      |
| Do More with Less: Single-Model, Multi-Goal Architectures for Resource-Constrained Robots .....  | 1467 |
| <i>Zili Wang, Drew Threatt, Sean B. Andersson, Roberto Tron</i>  |      |
| Enhancing State Estimation in Robots: A Data-Driven Approach with Differentiable Ensemble Kalman Filters .....                                     | 1474 |
| <i>Xiao Liu, Geoffrey Clark, Joseph Campbell, Yifan Zhou, Heni Ben Amor</i>  |      |
| Learning a Causal Transition Model for Object Cutting .....  | 1482 |
| <i>Zeyu Zhang, Muzhi Han, Baoxiong Jia, Ziyuan Jiao, Yixin Zhu, Song-Chun Zhu, Hangxin Liu</i>   |      |
| Object Rearrangement Planning for Target Retrieval in a Confined Space with Lateral View .....   | 1490 |
| <i>Minjae Kang, Junseok Kim, Hogun Kee, Songhwai Oh</i>  |      |
| Learning Type-Generalized Actions for Symbolic Planning .....  | 1496 |
| <i>Daniel Tanneberg, Michael Gienger</i>   |      |
| CAR-DESPOT: Causally-Informed Online POMDP Planning for Robots in Confounded Environments.....   | 1504 |
| <i>Ricardo Cannizzaro, Lars Kunze</i>  |      |
| Recurrent Macro Actions Generator for POMDP Planning.....  | 1512 |
| <i>Yuanchu Liang, Hanna Kurniawati</i>   |      |
| Task Planning and Motion Control with Temporal Logic Specifications .....  | 1520 |
| <i>Marcos S. Pereira, Luciano C. A. Pimenta, Bruno V. Adorno</i>   |      |
| Simultaneous Action and Grasp Feasibility Prediction for Task and Motion Planning Through Multi-Task Learning.....                                 | 1528 |
| <i>Smail Ait Bouhsain, Rachid Alami, Thierry Siméon</i>  |      |
| Differentiable Task Assignment and Motion Planning .....   | 1535 |
| <i>Jimmy Envall, Roi Poranne, Stelian Coros</i>  |      |
| Effectively Rearranging Heterogeneous Objects on Cluttered Tabletops.....  | 1543 |
| <i>Kai Gao, Justin Yu, Tanay Sandeep Punjabi, Jingjin Yu</i>   |      |

|  |      |
|--|------|
| Semantics-Aware Mission Adaptation for Autonomous Exploration in Urban Environments .....  | 1551 |
| <i>Sangwoo Moon, Oriana Peltzer, Joshua Ott, Sung-Kyun Kim, Ali-Akbar Agha-Mohammadi</i>   |      |
| Optimal Cost-Preference Trade-Off Planning with Multiple Temporal Tasks.....   | 1557 |
| <i>Peter Amorese, Morteza Lahijanian</i>   |      |
| Optimal and Stable Multi-Layer Object Rearrangement on a Tabletop.....   | 1564 |
| <i>Andy Xu, Kai Gao, Si Wei Feng, Jingjin Yu</i>   |      |
| Task and Motion Planning with Large Language Models for Object Rearrangement.....  | 1572 |
| <i>Yan Ding, Xiaohan Zhang, Chris Paxton, Shiqi Zhang</i>  |      |
| Improving Amputee Endurance Over Activities of Daily Living with a Robotic Knee-Ankle Prosthesis: A Case Study .....                               | 1579 |
| <i>T. Kevin Best, Curt A. Laubscher, Ross J. Cortino, Shihao Cheng, Robert D. Gregg</i>  |      |
| Controlling Powered Prostheses Kinematics Over Continuous Transitions Between Walk and Stair Ascent.....   | 1586 |
| <i>Shihao Cheng, Curt A. Laubscher, Robert D. Gregg</i>  |      |
| Calibration of a Tibia-Based Phase Variable for Control of Robotic Transtibial Prostheses .....  | 1594 |
| <i>Ryan R. Posh, Jonathan A. Tittle, James P. Schmiedeler, Patrick M. Wensing</i>  |      |
| On Intuitive Control of Ankle-Foot Prostheses: A Sensor Fusion-Based Algorithm for Real-Time Prediction of Transitions to Compliant Surfaces ..... | 1600 |
| <i>Charikleia Angelidou, Panagiotis Artermiadis</i>  |      |
| Powered Knee and Ankle Prosthesis Control for Adaptive Ambulation at Variable Speeds, Inclines, and Uneven Terrains.....                           | 1606 |
| <i>Liam M. Sullivan, Suzi Creveling, Marissa Cowan, Lukas Gabert, Tommaso Lenzi</i>  |      |
| Motor Unit Action Potential Based Classification of Hand and Arm Motions.....  | 1612 |
| <i>Michael D. Twardowski, Michael D. Chan, Zhi Li, Gianluca De Luca, Joshua C. Kline, John P. Chiodini</i>   |      |
| Adjusting the Quasi-Stiffness of an Ankle-Foot Prosthesis Improves Walking Stability During Locomotion Over Compliant Terrain .....                | 1618 |
| <i>Chrysostomos Karakasis, Robert Salati, Panagiotis Artermiadis</i>   |      |
| A Unified Controller for Natural Ambulation on Stairs and Level Ground with a Powered Robotic Knee Prosthesis .....                                | 1624 |
| <i>Marissa Cowan, Suzi Creveling, Liam M. Sullivan, Lukas Gabert, Tommaso Lenzi</i>  |      |
| Volitional EMG Control Enables Stair Climbing with a Robotic Powered Knee Prosthesis.....  | 1630 |
| <i>Suzi Creveling, Marissa Cowan, Liam M. Sullivan, Lukas Gabert, Tommaso Lenzi</i>  |      |
| Development and Online Validation of an Intrinsic Fault Detector for a Powered Robotic Knee Prosthesis.....  | 1636 |
| <i>Amirreza Naseri, Ming Liu, I-Chieh Lee, Helen He Huang</i>  |      |
| Collision-Free Reconfiguration Planning for Variable Topology Trusses Using a Linking Invariant .....  | 1643 |
| <i>Alexander Spinos, Mark Yim</i>  |      |
| Hybrid Map-Based Path Planning for Robot Navigation in Unstructured Environments .....   | 1649 |
| <i>Jiayang Liu, Xieyuanli Chen, Junhao Xiao, Sichao Lin, Zhiqiang Zheng, Huimin Lu</i>   |      |

|  |      |
|--|------|
| CDT-Dijkstra: Fast Planning of Globally Optimal Paths for All Points in 2D Continuous Space .....  | 1657 |
| <i>Jinyuan Liu, Minglei Fu, Wenan Zhang, Bo Chen, Ryhor Prakapovich, Uladzislau Sychou</i>   |      |
| Large Scale Pursuit-Evasion Under Collision Avoidance Using Deep Reinforcement Learning.....   | 1665 |
| <i>Helei Yang, Peng Ge, Junjie Cao, Yifan Yang, Yong Liu</i>   |      |
| Exploring Social Motion Latent Space and Human Awareness for Effective Robot Navigation in<br>Crowded Environments .....   | 1673 |
| <i>Junaid Ahmed Ansari, Satyajit Tourani, Gourav Kumar, Brojeshwar Bhowmick</i>  |      |
| DS-MPEPC: Safe and Deadlock-Avoiding Robot Navigation in Cluttered Dynamic Scenes.....   | 1681 |
| <i>Senthil Hariharan Arul, Jong Jin Park, Dinesh Manocha</i>   |      |
| Path-Following Control with Path and Orientation Snap-In.....  | 1689 |
| <i>Christian Hartl-Nesic, Elias Pritzi, Andreas Kugi</i>   |      |
| Design and Control of a Reluctance-Based Micropositioning Stage for Scanning Motion<br>Applications.....   | 1697 |
| <i>Mohammad Al Saadeh, Natheer Alatawneh, Khaled Aljanaideh, Mohammad Al Janaideh</i>  |      |
| Body Posture Controller for Actively Articulated Tracked Vehicles Moving Over Rough and<br>Unknown Terrains .....  | 1703 |
| <i>Filipe Rocha, Andre Cid, Mário Delunardo, Renato P. Junior, Nilton S Thiago, Luiz Barros,<br/>Jacó D. Domingues, Gustavo Pessin, Gustavo Freitas, Ramon Costa</i> |      |
| Exploring Learning-Based Control Policy for Fish-Like Robots in Altered Background Flows .....   | 1711 |
| <i>Xiaozhu Lin, Wenbin Song, Xiaopei Liu, Xuming He, Yang Wang</i>   |      |
| On the Design of Region-Avoiding Metrics for Collision-Safe Motion Generation on Riemannian<br>Manifolds .....   | 1719 |
| <i>Holger Klein, Noémie Jaquier, Andre Meixner, Tamim Asfour</i>   |      |
| Towards Connecting Control to Perception: High-Performance Whole-Body Collision Avoidance<br>Using Control-Compatible Obstacles .....                                | 1727 |
| <i>Moritz Eckhoff, Dennis Knobbe, Henning Zwirnmann, Abdalla Swikir, Sami Haddadin</i>   |      |
| Real-Time Whole-Body Collision Avoidance and Path Following of a Snake Robot Through MPC-<br>Based Optimization Strategies.....                                      | 1735 |
| <i>Liuyin Wang, Gang Wang, Yuan Li, Peng Li, Yunfeng Ji, Chaoli Wang, Yantao Shen</i>  |      |
| Safety-Critical Coordination for Cooperative Legged Locomotion Via Control Barrier Functions .....   | 1741 |
| <i>Jeeseop Kim, Jaemin Lee, Aaron D. Ames</i>  |      |
| Staged Contact Optimization: Combining Contact-Implicit and Multi-Phase Hybrid Trajectory<br>Optimization.....   | 1749 |
| <i>Michael R. Turski, Joseph Norby, Aaron M. Johnson</i>   |      |
| Hierarchical Relaxation of Safety-Critical Controllers: Mitigating Contradictory Safety Conditions<br>with Application to Quadruped Robots .....                     | 1757 |
| <i>Jaemin Lee, Jeeseop Kim, Aaron D. Ames</i>  |      |
| Design of Novel Knee Joint Mechanism of Lower-Limb Exoskeleton to Realize Spatial Motion of<br>Human Knee.....   | 1765 |
| <i>Man Bok Hong, Yongcheol Kim, Gwang Tae Kim, Myunghyun Lee, Seonwoo Kim</i>  |      |

|   |      |
|---|------|
| A Novel Coiled Cable-Conduit-Driven Hyper-Redundant Manipulator for Remote Operating in Narrow Spaces.....  | 1772 |
| <i>Mingrui Luo, Yunong Tian, En Li, Minghao Chen, Cunfeng Kang, Guodong Yang, Min Tan</i>   |      |
| Design and Testing of a Flexure-Based XYZ Micropositioner with High Space-Utilization Efficiency .....  | 1779 |
| <i>Zekui Lyu, Qingsong Xu</i>   |      |
| Design and Development of a Deformable In-Pipe Inspection Robot for Various Diameter Pipes.....   | 1785 |
| <i>Huafeng Xu, Jiannong Cao, Zhiqin Cheng, Zhixuan Liang, Jinlin Chen</i>   |      |
| A Bioinspired Underactuated Dual Tendon-Based Adaptive Gripper for Space Applications .....   | 1793 |
| <i>Hamid Isakhani, Samia Nefiti-Meziani, Steve Davis, Helya Isakhani</i>  |      |
| Parallel-Jaw Gripper and Grasp Co-Optimization for Sets of Planar Objects .....   | 1801 |
| <i>Rebecca H. Jiang, Neel Doshi, Ravi Gondhalekar, Alberto Rodriguez</i>  |      |
| Inertial Propulsion Robot Using the Shape Characteristics of a Streamlined Body Frame.....  | 1809 |
| <i>Masatsugu Nishihara, Fumihiko Asano</i>  |      |
| Two-Stage Trajectory-Tracking Control of Cable-Driven Upper-Limb Exoskeleton Robots with Series Elastic Actuators: A Simple, Accurate, and Force-Sensorless Method..... | 1816 |
| <i>Yana Shu, Yu Chen, Xuan Zhang, Shisheng Zhang, Gong Chen, Jing Ye, Xiang Li</i>  |      |
| A Retractable Soft Growing Robot with a Flexible Backbone .....   | 1823 |
| <i>Xinyi Pi, Isabella A. Szczech, Lin Cao</i>   |      |
| CurveQuad: A Centimeter-Scale Origami Quadruped that Leverages Curved Creases to Self-Fold and Crawl with One Motor.....  | 1831 |
| <i>Daniel Feshbach, Xuelin Wu, Satviki Vasireddy, Louis Beardell, Bao To, Yuliy Baryshnikov, Cynthia Sung</i>   |      |
| A Pendulum-Driven Legless Rolling Jumping Robot .....   | 1839 |
| <i>Jake Buzhardt, Prashanth Chivkula, Phanindra Tallapragada</i>  |      |
| Vine Robot Localization Via Collision .....   | 1845 |
| <i>Eugenio Frias-Miranda, Alankriti Srivastava, Sicheng Wang, Laura H. Blumenschein</i>   |      |
| Mapping Unknown Environments Through Passive Deformation of Soft, Growing Robots.....   | 1852 |
| <i>Francesco Fuentes, Laura H. Blumenschein</i>   |      |
| Stable Real-Time Feedback Control of a Pneumatic Soft Robot.....  | 1858 |
| <i>Sean Even, Tongjia Zheng, Hai Lin, Yasemin Ozkan-Aydin</i>   |      |
| Real2Sim2Real Transfer for Control of Cable-Driven Robots Via a Differentiable Physics Engine .....   | 1864 |
| <i>Kun Wang, William R. Johnson, Shiyang Lu, Xiaonan Huang, Joran Booth, Rebecca Kramer-Bottiglio, Mridul Aanjaneya, Kostas Bekris</i>                                  |      |
| Multi-Gait Locomotion Planning and Tracking for Tendon-Actuated Terrestrial Soft Robot (TerreSoRo).....   | 1872 |
| <i>Arun Niddish Mahendran, Caitlin Freeman, Alexander H. Chang, Michael McDougall, Patricio A. Vela, Vishesh Vikas</i>  |      |
| Learning Soft Robot Dynamics Using Differentiable Kalman Filters and Spatio-Temporal Embeddings.....  | 1880 |
| <i>Xiao Liu, Shuhei Ikemoto, Yuhei Yoshimitsu, Heni Ben Amor</i>  |      |

|   |      |
|---|------|
| Closed Loop Control of Tendon Driven Continuum Robots Using IMUs .....  | 1888 |
| <i>Manu Srivastava, Richard Groff, Ian D. Walker</i>  |      |
| Machine Learning Best Practices for Soft Robot Proprioception.....  | 1894 |
| <i>Annan Zhang, Tsun-Hsuan Wang, Ryan L. Truby, Lillian Chin, Daniela Rus</i>   |      |
| Active Capsule System for Multiple Therapeutic Patch Delivery: Preclinical Evaluation.....  | 1902 |
| <i>Jihun Lee, Hoang Manh Cuong, Jayoung Kim, Eunho Choi, Hyeonwoo Kee, Seungun Yang, Jong-Oh Park, Sukho Park</i>                                 |      |
| Parallel Cell Array Patterning and Target Cell Lysis on an Optoelectronic Micro-Well Device .....   | 1909 |
| <i>Chunyuan Gan, Hongyi Xiong, Jiawei Zhao, Ao Wang, Chutian Wang, Shuzhang Liang, Jiaying Zhang, Lin Feng</i>                                    |      |
| Microrobot Control Method Based on Movement of Field Free Point in Gradient Magnetic Field .....  | 1915 |
| <i>Chutian Wang, Yiming Ji, Xinyun Luo, Chunyuan Gan, Jiapeng Yang, Jiawei Zhao, Luyao Wang, Lin Feng</i>   |      |
| Helical Propulsion in Low-Re Numbers with Near-Zero Angle of Attack .....   | 1921 |
| <i>Leendert-Jan W. Ligtenberg, Ilse A. A. Ekkelenkamp, Frank R. Halfwerk, Constantinos Goulas, Jutta Arens, Michiel Warlé, Islam S. M. Khalil</i> |      |
| Influence of Nanoparticle Coating on the Differential Magnetometry and Wireless Actuation of Biohybrid Microrobots .....                          | 1927 |
| <i>Veronika Magdanz, Jack R. Cumming, Sadaf Salamzadeh, Sven Tesselaar, Lejla Alic, Leon Abelmann, Islam S. M. Khalil</i>                         |      |
| Using Piezoceramic-Actuated Stages in Precision Long-Stroke Motion Systems: A Design Procedure.....   | 1933 |
| <i>Yazan M. Al-Rawashdeh, Mohammad Al Saaideh, Mohammad Al Janaideh</i>   |      |
| Buoyancy Enabled Non-Inertial Dynamic Walking .....   | 1939 |
| <i>Mark Yim, Walker Gosrich, Marc Miskin</i>  |      |
| Ultrafast Acoustic Holography with Physics-Reinforced Self-Supervised Learning for Precise Robotic Manipulation.....                              | 1947 |
| <i>Qingyi Lu, Chengxi Zhong, Qing Liu, Teng Li, Hu Su, Song Liu</i>   |      |
| Surface Navigation of Alginate Artificial Cells in Mucus Solutions .....  | 1953 |
| <i>Louis William Rogowski, Justin Wood, Tobias Cooke, Gokhan Kararsiz, Min Jun Kim</i>  |      |
| Design and Control of Microscale Dual Locomotion Mode Multi-Functional Robots ( $\mu$ DMMFs).....   | 1961 |
| <i>Aaron C. Davis, David J. Cappelleri</i>  |      |
| A New 1-Mg Fast Unimorph SMA-Based Actuator for Microrobotics.....  | 1967 |
| <i>Conor K. Trygstad, Xuan-Truc Nguyen, Néstor O. Pérez-Arancibia</i>   |      |
| Toward Sub-Gram Helicopters: Designing a Miniaturized Flybar for Passive Stability .....  | 1975 |
| <i>Kyle Johnson, Vicente Arroyos, Raul Villanueva, Adriana Schulz, Sawyer Fuller, Vikram Iyer</i>   |      |
| Manipulation of Optical Force-Induced Micro-Assemblies at the Air-Liquid Interface .....  | 1983 |
| <i>Nicholas Carlisle, Martin A. K. Williams, Catherine P. Whitby, Volker Nock, Jack L. Y. Chen, Ebubekir Avci</i>                                 |      |
| Creating a Dynamic Quadrupedal Robotic Goalkeeper with Reinforcement Learning.....  | 1989 |
| <i>Xiaoyu Huang, Zhongyu Li, Yanzhen Xiang, Yiming Ni, Yufeng Chi, Yunhao Li, Lizhi Yang, Xue Bin Peng, Koushil Sreenath</i>                      |      |

|   |      |
|---|------|
| Walking in Narrow Spaces: Safety-Critical Locomotion Control for Quadrupedal Robots with Duality-Based Optimization ..... | 1997 |
| <i>Qiayuan Liao, Zhongyu Li, Akshay Thirugnanam, Jun Zeng, Koushil Sreenath</i>   |      |
| ARMP: Autoregressive Motion Planning for Quadruped Locomotion and Navigation in Complex Indoor Environments .....         | 2005 |
| <i>Jeonghwan Kim, Tianyu Li, Sehoon Ha</i>  |      |
| Perceptive Hexapod Legged Locomotion for Climbing Joist Environments .....  | 2012 |
| <i>Zixian Zang, Maxime Kawawa-Beaudan, Wenhao Yu, Tingnan Zhang, Avideh Zakhor</i>  |      |
| Design of STARQ: A Multimodal Quadrupedal Robot for Running, Climbing, and Swimming.....                                  | 2020 |
| <i>Derek A. Vasquez, David Jay, Michael Dina, Max Austin, Shayne McCconomy, Jonathan E. Clark</i>                         |      |
| Hierarchical Adaptive Control for Collaborative Manipulation of a Rigid Object by Quadrupedal Robots.....                 | 2026 |
| <i>Mohsen Sombolestan, Quan Nguyen</i>  |      |
| Proprioception and Reaction for Walking Among Entanglements .....   | 2034 |
| <i>Justin K. Yim, Jiming Ren, David Ologan, Selvin Garcia Gonzalez, Aaron M. Johnson</i>                                  |      |
| Learning a Single Policy for Diverse Behaviors on a Quadrupedal Robot Using Scalable Motion Imitation .....               | 2042 |
| <i>Arnaud Klipfel, Nitish Sontakke, Ren Liu, Sehoon Ha</i>  |      |
| A Novel Lockable Spring-Loaded Prismatic Spine to Support Agile Quadrupedal Locomotion.....                               | 2050 |
| <i>Keran Ye, Kenneth Chung, Konstantinos Karydis</i>  |      |
| Efficient Path Planning in Manipulation Planning Problems by Actively Reusing Validation Effort .....                     | 2058 |
| <i>Valentin N. Hartmann, Joaquim Ortiz-Haro, Marc Toussaint</i>   |      |
| Improving Reliable Navigation Under Uncertainty Via Predictions Informed by Non-Local Information .....                   | 2066 |
| <i>Raihan Islam Arnob, Gregory J. Stein</i>   |      |
| TOP-UAV: Open-Source Time-Optimal Trajectory Planner for Point-Masses Under Acceleration and Velocity Constraints .....   | 2074 |
| <i>Fabian Meyer, Katharina Glock, David Sayah</i>   |      |
| Fast Asymptotically Optimal Path Planning in Dynamic, Uncertain Environments .....  | 2082 |
| <i>Lu Huang, Xingjian Jing</i>  |      |
| An Efficient Trajectory Planner for Car-Like Robots on Uneven Terrain.....  | 2089 |
| <i>Long Xu, Kaixin Chai, Zhichao Han, Hong Liu, Chao Xu, Yanjun Cao, Fei Gao</i>  |      |
| Robots as AI Double Agents: Privacy in Motion Planning.....   | 2097 |
| <i>Rahul Shome, Zachary Kingston, Lydia E. Kavraki</i>  |      |
| Bang-Bang Boosting of RRTs .....  | 2105 |
| <i>Alexander J. La Valle, Basak Sakcak, Steven M. Lavalle</i>   |      |
| Geometric Gait Optimization for Inertia-Dominated Systems with Nonzero Net Momentum .....                                 | 2113 |
| <i>Yanhao Yang, Ross L. Hatton</i>  |      |

|   |      |
|---|------|
| Real-Time Tube-Based Non-Gaussian Risk Bounded Motion Planning for Stochastic Nonlinear Systems in Uncertain Environments Via Motion Primitives ..... | 2121 |
| <i>Weiqiao Han, Ashkan Jasour, Brian Williams</i>   |      |
| Learning Bifunctional Push-Grasping Synergistic Strategy for Goal-Agnostic and Goal-Oriented Tasks.....   | 2129 |
| <i>Dafa Ren, Shuang Wu, Xiaofan Wang, Yan Peng, Xiaoqiang Ren</i>   |      |
| Domain Adaptation on Point Clouds for 6D Pose Estimation in Bin-Picking Scenarios .....   | 2137 |
| <i>Liang Zhao, Meng Sun, Wei Jie Lv, Xin Yu Zhang, Long Zeng</i>  |      |
| Learning Robotic Powder Weighing from Simulation for Laboratory Automation .....  | 2144 |
| <i>Yuki Kadokawa, Masashi Hamaya, Kazutoshi Tanaka</i>  |      |
| Constrained Generative Sampling of 6-DoF Grasps .....   | 2152 |
| <i>Jens Lundell, Francesco Verdoja, Tran Nguyen Le, Arsalan Mousavian, Dieter Fox, Ville Kyrki</i>  |      |
| RGBD Fusion Grasp Network with Large-Scale Tableware Grasp Dataset.....   | 2159 |
| <i>Jaemin Yoon, Joonmo Ahn, Changsu Ha, Rakjoon Chung, Dongwoo Park, Heungwoo Han, Sungchul Kang</i>  |      |
| One-Shot Affordance Learning (OSAL): Learning to Manipulate Articulated Objects by Observing Once .....   | 2167 |
| <i>Ruomeng Fan, Taohan Wang, Masahiro Hirano, Yuji Yamakawa</i>   |      |
| EARL: Eye-On-Hand Reinforcement Learner for Dynamic Grasping with Active Pose Estimation .....  | 2175 |
| <i>Baichuan Huang, Jingjin Yu, Siddarth Jain</i>  |      |
| KGNv2: Separating Scale and Pose Prediction for Keypoint-Based 6-DoF Grasp Synthesis on RGB-D Input .....   | 2183 |
| <i>Yiye Chen, Ruinian Xu, Yunzhi Lin, Hongyi Chen, Patricio A. Vela</i>   |      |
| Learning-Based Real-Time Torque Prediction for Grasping Unknown Objects with a Multi-Fingered Hand .....  | 2191 |
| <i>Dominik Winkelbauer, Berthold Bäuml, Rudolph Triebel</i>   |      |
| A Grasp Pose is All You Need: Learning Multi-Fingered Grasping with Deep Reinforcement Learning from Vision and Touch.....                            | 2197 |
| <i>Federico Ceola, Elisa Maiettini, Lorenzo Rosasco, Lorenzo Natale</i>   |      |
| Physics-Informed Learning to Enable Robotic Screw-Driving Under Hole Pose Uncertainties.....  | 2205 |
| <i>Omey M. Manyar, Santosh V Narayan, Rohin Lengade, Satyandra K. Gupta</i>   |      |
| ADMNet: Anti-Drone Real-Time Detection and Monitoring.....  | 2213 |
| <i>Xunkuai Zhou, Guidong Yang, Yizhou Chen, Chuanxiang Gao, Benyun Zhao, Li Li, Ben M. Chen</i>   |      |
| Multi-View Stereo with Learnable Cost Metric .....  | 2221 |
| <i>Guidong Yang, Xunkuai Zhou, Chuanxiang Gao, Benyun Zhao, Jihan Zhang, Yizhou Chen, Xi Chen, Ben M. Chen</i>  |      |
| A Comparison Between Framed-Based and Event-Based Cameras for Flapping-Wing Robot Perception.....   | 2229 |
| <i>R. Tapia, J. P. Rodríguez-Gómez, J. A. Sanchez-Díaz, F. J. Gañán, I. G. Rodríguez, J. Luna-Santamaría, J. R. Martínez-De Dios, A. Ollero</i>       |      |

|   |      |
|---|------|
| Flexible Multi-DoF Aerial 3D Printing Supported with Automated Optimal Chunking .....   | 2237 |
| <i>Marios-Nektarios Stamatopoulos, Avijit Banerjee, George Nikolakopoulos</i>   |      |
| Memory Maps for Video Object Detection and Tracking on UAVs .....   | 2244 |
| <i>Benjamin Kiefer, Yitong Quan, Andreas Zell</i>   |      |
| Robust Localization of Aerial Vehicles Via Active Control of Identical Ground Vehicles .....  | 2252 |
| <i>Igor Spasojevic, Xu Liu, Ankit Prabhu, Alejandro Ribeiro, George J. Pappas, Vijay Kumar</i>  |      |
| Semantically-Enhanced Deep Collision Prediction for Autonomous Navigation Using Aerial<br>Robots.....                                       | 2260 |
| <i>Mihir Kulkarni, Huan Nguyen, Kostas Alexis</i>   |      |
| Demonstrating Autonomous 3D Path Planning on a Novel Scalable UGV-UAV Morphing Robot .....  | 2268 |
| <i>Eric Sihite, Filip Slezak, Ioannis Mandralis, Adarsh Salagame, Milad Ramezani, Arash<br/>Kalantari, Alireza Ramezani, Morteza Gharib</i> |      |
| Topology-Guided Perception-Aware Receding Horizon Trajectory Generation for UAVs .....  | 2274 |
| <i>Gang Sun, Xuetao Zhang, Yisha Liu, Hanhang Wang, Xuebo Zhang, Yan Zhuang</i>   |      |
| Nonlinear Deterministic Observer for Inertial Navigation Using Ultra-Wideband and IMU Sensor<br>Fusion .....                                | 2281 |
| <i>Hashim A. Hashim, Abdelrahman E. E. Eltoukhy, Kyriakos G. Vamvoudakis, Mohammed I.<br/>Abouheaf</i>                                      |      |
| Model-Free Grasping with Multi-Suction Cup Grippers for Robotic Bin Picking.....  | 2287 |
| <i>Philipp Schillinger, Miroslav Gabriel, Alexander Kuss, Hanna Ziesche, Ngo Anh Vien</i>   |      |
| Vision-Based State and Pose Estimation for Robotic Bin Picking of Cables .....  | 2294 |
| <i>Andrea Monguzzi, Christian Cella, Andrea Maria Zanchettin, Paolo Rocco</i>   |      |
| Efficient Visuo-Haptic Object Shape Completion for Robot Manipulation .....   | 2301 |
| <i>Lukas Rustler, Jiri Matas, Matej Hoffmann</i>  |      |
| Force Map: Learning to Predict Contact Force Distribution from Vision .....   | 2309 |
| <i>Ryo Hanai, Yukiyasu Domae, Ixchel G. Ramirez-Alpizar, Bruno Leme, Tetsuya Ogata</i>  |      |
| Push to Know! - Visuo-Tactile Based Active Object Parameter Inference with Dual Differentiable<br>Filtering .....                           | 2317 |
| <i>Anirvan Dutta, Etienne Burdet, Mohsen Kaboli</i>   |      |
| IOSG: Image-Driven Object Searching and Grasping.....   | 2325 |
| <i>Houjian Yu, Xibai Lou, Yang Yang, Changhyun Choi</i>   |      |
| DexRepNet: Learning Dexterous Robotic Grasping Network with Geometric and Spatial Hand-<br>Object Representations.....                      | 2333 |
| <i>Qingtao Liu, Yu Cui, Qi Ye, Zhengnan Sun, Haoming Li, Gaofeng Li, Lin Shao, Jiming Chen</i>  |      |
| Active Acoustic Sensing for Robot Manipulation .....  | 2341 |
| <i>Shihan Lu, Heather Culbertson</i>  |      |
| Grasp Region Exploration for 7-DoF Robotic Grasping in Cluttered Scenes .....   | 2349 |
| <i>Zibo Chen, Zhixuan Liu, Shangjin Xie, Wei-Shi Zheng</i>  |      |
| Bagging by Learning to Singulate Layers Using Interactive Perception.....   | 2356 |
| <i>Lawrence Yunliang Chen, Baiyu Shi, Roy Lin, Daniel Seita, Ayah Ahmad, Richard Cheng,<br/>Thomas Kollar, David Held, Ken Goldberg</i>     |      |

|   |      |
|---|------|
| Real-Time Simultaneous Multi-Object 3D Shape Reconstruction, 6DoF Pose Estimation and Dense Grasp Prediction .....  | 2364 |
| <i>Shubham Agrawal, Nikhil Chavan-Dafle, Isaac Kasahara, Selim Engin, Jinwook Huh, Volkan Isler</i>   |      |
| Flexible Handover with Real-Time Robust Dynamic Grasp Trajectory Generation .....   | 2372 |
| <i>Gu Zhang, Hao-Shu Fang, Hongjie Fang, Cewu Lu</i>  |      |
| HyperTraj: Towards Simple and Fast Scene-Compliant Endpoint Conditioned Trajectory Prediction .....   | 2380 |
| <i>Renhai Huang, Maurice Pagnucco, Yang Song</i>  |      |
| PanelPose: A 6D Pose Estimation of Highly-Variable Panel Object for Robotic Robust Cockpit Panel Inspection .....   | 2386 |
| <i>Han Sun, Peiyuan Ni, Zhiqi Li, Yizhao Wang, Xiaoxiao Zhu, Qixin Cao</i>  |      |
| Image Restoration Via UAVFormer for Under-Display Camera of UAV.....  | 2394 |
| <i>Zhuoran Zheng, Xiuyi Jia</i>   |      |
| Semantic Scene Difference Detection in Daily Life Patrolling by Mobile Robots Using Pre-Trained Large-Scale Vision-Language Model .....   | 2400 |
| <i>Yoshiki Obinata, Kento Kawaharazuka, Naoaki Kanazawa, Naoya Yamaguchi, Naoto Tsukamoto, Iori Yanokura, Shingo Kitagawa, Koki Shinjo, Kei Okada, Masayuki Inaba</i>   |      |
| Seeing the Fruit for the Leaves: Robotically Mapping Apple Fruitlets in a Commercial Orchard.....   | 2406 |
| <i>Ans Qureshi, David Smith, Trevor Gee, Mahla Nejati, Jalil Shahabi, Jongyoon Lim, Ho Seok Ahn, Ben McGuinness, Catherine Downes, Rahul Jangali, Kale Black, Hin Lim, Mike Duke, Bruce Macdonald, Henry Williams</i> |      |
| Cross-Domain Autonomous Driving Perception Using Contrastive Appearance Adaptation .....  | 2412 |
| <i>Ziqiang Zheng, Yingshu Chen, Binh-Son Hua, Yang Wu, Sai-Kit Yeung</i>  |      |
| MENTOR: Multilingual tExt detectioN TOward leaRning by analogy .....  | 2420 |
| <i>Hsin-Ju Lin, Tsu-Chun Chung, Ching-Chun Hsiao, Pin-Yu Chen, Wei-Chen Chiu, Ching-Chun Huang</i>  |      |
| Towards a Robust Adversarial Patch Attack Against Unmanned Aerial Vehicles Object Detection .....   | 2428 |
| <i>Samridha Shrestha, Saurabh Pathak, Eduardo K. Viegas</i>   |      |
| Fast Point to Mesh Distance by Domain Voxelization .....  | 2436 |
| <i>Geordan Gutow, Howie Choset</i>  |      |
| AirLine: Efficient Learnable Line Detection with Local Edge Voting .....  | 2442 |
| <i>Xiao Lin, Chen Wang</i>  |      |
| 3D Skeletonization of Complex Grapevines for Robotic Pruning.....   | 2450 |
| <i>Eric Schneider, Sushanth Jayanth, Abhisesh Silwal, George Kantor</i>   |      |
| AdaptSeqVPR: An Adaptive Sequence-Based Visual Place Recognition Pipeline .....   | 2456 |
| <i>Heshan Li, Guohao Peng, Jun Zhang, Sriram Vaikundam, Danwei Wang</i>   |      |
| Towards Automated Void Detection for Search and Rescue with 3D Perception.....  | 2462 |
| <i>Ananya Bal, Ashutosh Gupta, Pranav Goyal, David Merrick, Robin Murphy, Howie Choset</i>  |      |
| Visual Localization Based on Multiple Maps.....   | 2470 |
| <i>Yukai Lin, Liu Liu, Xiao Liang, Jiangwei Li</i>  |      |

|  |      |
|--|------|
| An Interacting Multiple Model Approach Based on Maximum Correntropy Student's T Filter.....                              | 2478 |
| <i>Fethi Candan, Aykut Beke, Lyudmila Mihaylova</i>  |      |
| Deep Robust Multi-Robot Re-Localisation in Natural Environments.....   | 2486 |
| <i>Milad Ramezani, Ethan Griffiths, Maryam Haghigat, Alex Pitt, Peyman Moghadam</i>                                      |      |
| FVLoc-NeRF : Fast Vision-Only Localization Within Neural Radiation Field.....  | 2493 |
| <i>Guo Wenzhi, Bai Haiyang, Mou Yuanqu, Liu Jia, Chen Lijun</i>  |      |
| RADA: Robust Adversarial Data Augmentation for Camera Localization in Challenging Conditions .....                       | 2499 |
| <i>Jialu Wang, Muhamad Risqi U. Saputra, Chris Xiaoxuan Lu, Niki Trigoni, Andrew Markham</i>                             |      |
| MagHT: A Magnetic Hough Transform for Fast Indoor Place Recognition.....   | 2507 |
| <i>Iad Abdul Raouf, Vincent Gay-Bellile, Steve Bourgeois, Cyril Joly, Alexis Paljic</i>                                  |      |
| What to Learn: Features, Image Transformations, or Both?.....  | 2515 |
| <i>Yuxuan Chen, Binbin Xu, Frederike Dümbgen, Timothy D. Barfoot</i>   |      |
| Global Localization: Utilizing Relative Spatio-Temporal Geometric Constraints from Adjacent and<br>Distant Cameras ..... | 2522 |
| <i>Mohammad Altillawi, Zador Pataki, Shile Li, Ziyuan Liu</i>  |      |
| Uncertainty-Aware Lidar Place Recognition in Novel Environments .....  | 2530 |
| <i>Keita Mason, Joshua Knights, Milad Ramezani, Peyman Moghadam, Dimity Miller</i>                                       |      |
| Data-Driven Based Cascading Orientation and Translation Estimation for Inertial Navigation .....                         | 2538 |
| <i>Xiangyu Deng, Shenyue Wang, Chunxiang Shan, Jinjie Lu, Ke Jin, Jijunnan Li, Yandong Guo</i>                           |      |
| Converting Depth Images and Point Clouds for Feature-Based Pose Estimation .....   | 2546 |
| <i>Robert Lösch, Mark Sastuba, Jonas Toth, Bernhard Jung</i>   |      |
| AirVO: An Illumination-Robust Point-Line Visual Odometry.....  | 2553 |
| <i>Kuan Xu, Yuefan Hao, Shenghai Yuan, Chen Wang, Lihua Xie</i>  |      |
| NeRF-SLAM: Real-Time Dense Monocular SLAM with Neural Radiance Fields .....  | 2561 |
| <i>Antoni Rosinol, John J. Leonard, Luca Carlone</i>   |      |
| Scale Jump-Aware Pose Graph Relaxation for Monocular SLAM with Re-Initializations .....                                  | 2569 |
| <i>Runze Yuan, Ran Cheng, Lige Liu, Tao Sun, Laurent Kneip</i>   |      |
| Optimizing the Extended Fourier Mellin Transformation Algorithm .....  | 2577 |
| <i>Wenqing Jiang, Chengqian Li, Jinyue Cao, Sören Schwertfeger</i>   |      |
| Marker-Based Visual SLAM Leveraging Hierarchical Representations .....   | 2585 |
| <i>Ali Tourani, Hriday Bavle, Jose Luis Sanchez-Lopez, Rafael Muñoz Salinas, Holger Voos</i>                             |      |
| RVWO: A Robust Visual-Wheel SLAM System for Mobile Robots in Dynamic Environments.....                                   | 2592 |
| <i>Jaafar Mahmoud, Andrey Penkovskiy, Ha The Long Vuong, Aleksey Burkov, Sergey Kolyubin</i>                             |      |
| Event Camera-Based Visual Odometry for Dynamic Motion Tracking of a Legged Robot Using<br>Adaptive Time Surface .....    | 2599 |
| <i>Shifan Zhu, Zhipeng Tang, Michael Yang, Erik Learned-Miller, Donghyun Kim</i>   |      |
| Enhancing Robustness of Line Tracking Through Semi-Dense Epipolar Search in Line-Based<br>SLAM.....                      | 2607 |
| <i>Dong-Uk Seo, Hyungtae Lim, Eungchang Mason Lee, Hyunjung Lim, Hyun Myung</i>  |      |

|   |      |
|---|------|
| Stereo Visual Odometry with Deep Learning-Based Point and Line Feature Matching Using an Attention Graph Neural Network .....           | 2615 |
| <i>Shenbagaraj Kannapiran, Nalin Bendapudi, Ming-Yuan Yu, Devarth Parikh, Spring Berman, Ankit Vora, Gaurav Pandey</i>                  |      |
| Selective Presentation of AI Object Detection Results While Maintaining Human Reliance .....  | 2623 |
| <i>Yosuke Fukuchi, Seiji Yamada</i>   |      |
| Ego-Noise Reduction of a Mobile Robot Using Noise Spatial Covariance Matrix Learning and Minimum Variance Distortionless Response ..... | 2629 |
| <i>Pierre-Olivier Lagacé, François Ferland, François Grondin</i>  |      |
| Extracting Dynamic Navigation Goal from Natural Language Dialogue.....  | 2635 |
| <i>Lanjun Liang, Ganghui Bian, Huailin Zhao, Yanzhi Dong, Huaping Liu</i>   |      |
| TidyBot: Personalized Robot Assistance with Large Language Models .....   | 2642 |
| <i>Jimmy Wu, Rika Antonova, Adam Kan, Marion Lepert, Andy Zeng, Shuran Song, Jeannette Bohg, Szymon Rusinkiewicz, Thomas Funkhouser</i> |      |
| L3MVN: Leveraging Large Language Models for Visual Target Navigation .....  | 2650 |
| <i>Bangguo Yu, Hamidreza Kasaie, Ming Cao</i>   |      |
| TopSpark: A Timestep Optimization Methodology for Energy-Efficient Spiking Neural Networks on Autonomous Mobile Agents .....            | 2657 |
| <i>Rachmad Vidya Wicaksana Putra, Muhammad Shafique</i>   |      |
| Generating Executable Action Plans with Environmentally-Aware Language Models.....  | 2664 |
| <i>Maitrey Gramopadhye, Daniel Szafrir</i>  |      |
| Interaction-Aware and Hierarchically-Explainable Heterogeneous Graph-Based Imitation Learning for Autonomous Driving Simulation .....   | 2672 |
| <i>Mahan Tabatabaie, Suining He, Kang G. Shin</i>   |      |
| Zero-Shot Fault Detection for Manipulators Through Bayesian Inverse Reinforcement Learning.....   | 2678 |
| <i>Hanqing Zhao, Xue Liu, Gregory Dudek</i>   |      |
| Chat with the Environment: Interactive Multimodal Perception Using Large Language Models.....   | 2686 |
| <i>Xufeng Zhao, Mengdi Li, Cornelius Weber, Muhammad Burhan Hafez, Stefan Wermter</i>   |      |
| Reinforcement Learning for Robot Navigation with Adaptive Forward Simulation Time (AFST) in a Semi-Markov Model.....                    | 2693 |
| <i>Yu'An Chen, Ruosong Ye, Ziyang Tao, Hongjian Liu, Guangda Chen, Jie Peng, Jun Ma, Yu Zhang, Jianmin Ji, Yanyong Zhang</i>            |      |
| PACT: Perception-Action Causal Transformer for Autoregressive Robotics Pre-Training .....   | 2701 |
| <i>Rogerio Bonatti, Sai Vemprala, Shuang Ma, Felipe Frujeri, Shuhang Chen, Ashish Kapoor</i>  |      |
| Neural Field Movement Primitives for Joint Modelling of Scenes and Motions .....  | 2708 |
| <i>Ahmet Tekden, Marc Peter Deisenroth, Yasemin Bekiroglu</i>   |      |
| Augmentation Enables One-Shot Generalization in Learning from Demonstration for Contact-Rich Manipulation .....                         | 2716 |
| <i>Xing Li, Manuel Baurn, Oliver Brock</i>  |      |

|   |      |
|---|------|
| Using Single Demonstrations to Define Autonomous Manipulation Contact Tasks in Unstructured Environments Via Object Affordances ..... | 2724 |
| <i>Frank Regal, Adam Pettinger, John A. Duncan, Fabian Parra, Emmanuel Akita, Alex Navarro, Mitch Pryor</i>                           |      |
| Constrained Dynamic Movement Primitives for Collision Avoidance in Novel Environments.....  | 2732 |
| <i>Seiji Shaw, Devesh K. Jha, Arvind U. Raghunathan, Radu Corcodel, Diego Romeres, George Konidaris, Daniel Nikovski</i>              |      |
| Learning Constraints on Autonomous Behavior from Proactive Feedback.....  | 2740 |
| <i>Connor Basich, Saaduddin Mahmud, Shlomo Zilberstein</i>  |      |
| Learning Models of Adversarial Agent Behavior Under Partial Observability .....   | 2748 |
| <i>Sean Ye, Manisha Natarajan, Zixuan Wu, Rohan Paleja, Letian Chen, Matthew C. Gombolay</i>  |      |
| Robust Real-Time Motion Retargeting Via Neural Latent Prediction .....  | 2756 |
| <i>Tiantian Wang, Haodong Zhang, Lu Chen, Dongqi Wang, Yue Wang, Rong Xiong</i>   |      |
| Deep Probabilistic Movement Primitives with a Bayesian Aggregator.....  | 2764 |
| <i>Michael Przystupa, Faezeh Haghverd, Martin Jagersand, Samuele Tosatto</i>  |      |
| Self-Supervised Visual Motor Skills Via Neural Radiance Fields.....   | 2772 |
| <i>Paul Gesel, Noushad Sojib, Momotaz Begum</i>   |      |
| Autonomous Ultrasound Scanning Towards Standard Plane Using Interval Interaction Probabilistic Movement Primitives .....              | 2779 |
| <i>Yi Hu, Mahdi Tavakoli</i>  |      |
| Automated Key Action Detection for Closed Reduction of Pelvic Fractures by Expert Surgeons in Robot-Assisted Surgery .....            | 2785 |
| <i>Ming-Zhang Pan, Ya-Wen Deng, Zhen Li, Yuan Chen, Xiao-Lan Liao, Gui-Bin Bian</i>   |      |
| LAMP: Leveraging Language Prompts for Multi-Person Pose Estimation.....   | 2792 |
| <i>Shengnan Hu, Ce Zheng, Zixiang Zhou, Chen Chen, Gita Sukthankar</i>  |      |
| Detecting Changes in Functional State: A Comparative Analysis Using Wearable Sensors and a Sensorized Tip .....                       | 2800 |
| <i>Janire Otamendi, Asier Zubizarreta</i>   |      |
| DiffuPose: Monocular 3D Human Pose Estimation Via Denoising Diffusion Probabilistic Model.....  | 2806 |
| <i>Jeongjun Choi, Dongseok Shim, H. Jin Kim</i>   |      |
| BodySLAM++: Fast and Tightly-Coupled Visual-Inertial Camera and Human Motion Tracking.....  | 2814 |
| <i>Dorian F. Henning, Christopher Choi, Simon Schaefer, Stefan Leutenegger</i>  |      |
| Characterizing the Onset and Offset of Motor Imagery During Passive Arm Movements Induced by an Upper-Body Exoskeleton.....           | 2822 |
| <i>Kanishka Mitra, Frigyes Samuel Racz, Satyam Kumar, Ashish D. Deshpande, José Del R. Millán</i>                                     |      |
| CLiFF-LHMP: Using Spatial Dynamics Patterns for Long- Term Human Motion Prediction .....  | 2828 |
| <i>Yufei Zhu, Andrey Rudenko, Tomasz P. Kucner, Luigi Palmieri, Kai O. Arras, Achim J. Lilienthal, Martin Magnusson</i>               |      |
| GloPro: Globally-Consistent Uncertainty-Aware 3D Human Pose Estimation & Tracking in the Wild .....                                   | 2836 |
| <i>Simon Schaefer, Dorian F. Henning, Stefan Leutenegger</i>  |      |

|  |      |
|--|------|
| Anytime, Anywhere: Human Arm Pose from Smartwatch Data for Ubiquitous Robot Control and Teleoperation .....  | 2844 |
| <i>Fabian C Weigend, Shubham Sonawani, Michael Drolet, Heni Ben Amor</i>   |      |
| Recognizing Real-World Intentions Using a Multimodal Deep Learning Approach with Spatial-Temporal Graph Convolutional Networks.....  | 2852 |
| <i>Jiaqi Shi, Chaoran Liu, Carlos Toshinori Ishi, Bowen Wu, Hiroshi Ishiguro</i>   |      |
| VADER: Vector-Quantized Generative Adversarial Network for Motion Prediction.....  | 2860 |
| <i>Mohammad Samin Yasar, Tariq Iqbal</i>   |      |
| SG-LSTM: Social Group LSTM for Robot Navigation Through Dense Crowds .....   | 2868 |
| <i>Rashmi Bhaskara, Maurice Chiu, Aniket Bera</i>  |      |
| Online Continual Learning for Robust Indoor Object Recognition.....  | 2874 |
| <i>Umberto Michieli, Mete Ozay</i>   |      |
| PaintNet: Unstructured Multi-Path Learning from 3D Point Clouds for Robotic Spray Painting.....  | 2882 |
| <i>Gabriele Tiboni, Raffaello Camoriano, Tatiana Tommasi</i>   |      |
| Switching Head-Tail Funnel UNITER for Dual Referring Expression Comprehension with Fetch-And-Carry Tasks.....  | 2890 |
| <i>Ryosuke Korekata, Motonari Kambara, Yu Yoshida, Shintaro Ishikawa, Yosuke Kawasaki, Masaki Takahashi, Komei Sugiura</i>   |      |
| FeatDANet: Feature-Level Domain Adaptation Network for Semantic Segmentation.....  | 2898 |
| <i>Jiao Li, Wenjun Shi, Dongchen Zhu, Guanghui Zhang, Xiaolin Zhang, Jiamao Li</i>   |      |
| BlinkFlow: A Dataset to Push the Limits of Event-Based Optical Flow Estimation.....  | 2906 |
| <i>Yijin Li, Zhaoyang Huang, Shuo Chen, Xiaoyu Shi, Hongsheng Li, Hujun Bao, Zhaopeng Cui, Guofeng Zhang</i>   |      |
| Discovering Adaptable Symbolic Algorithms from Scratch.....  | 2914 |
| <i>Stephen Kelly, Daniel S. Park, Xingyou Song, Mitchell McIntire, Pranav Nashikkar, Ritam Guha, Wolfgang Banzhaf, Kalyanmoy Deb, Vishnu Naresh Boddeti, Jie Tan, Esteban Real</i> |      |
| Visual Pre-Training for Navigation: What Can We Learn from Noise? .....  | 2922 |
| <i>Yanwei Wang, Ching-Yun Ko, Pulkit Agrawal</i>   |      |
| Spatio-Temporal Attention Network for Persistent Monitoring of Multiple Mobile Targets.....  | 2928 |
| <i>Yizhuo Wang, Yutong Wang, Yuhong Cao, Guillaume Sartoretti</i>  |      |
| Subtask Aware End-To-End Learning for Visual Room Rearrangement.....   | 2936 |
| <i>Youngho Kim, Jong-Hwan Kim</i>  |      |
| Less than Human: How Different Users of Telepresence Robots Expect Different Social Norms .....  | 2944 |
| <i>Cheng Lin, Jimin Rhim, A Jung Moon</i>  |      |
| Do Hierarchies in a Robot Team Impact the Service Evaluation by Users?.....  | 2951 |
| <i>Soomin Shin, Sonya S. Kwak</i>  |      |
| Robot-Induced Group Conversation Dynamics: A Model to Balance Participation and Unify Communities .....  | 2959 |
| <i>Lucrezia Grassi, Carmine Tommaso Recchiuto, Antonio Sgorbissa</i>   |      |
| Read the Room: Adapting a Robot's Voice to Ambient and Social Contexts .....   | 2966 |
| <i>Paige Tuttosi, Emma Hughson, Akihiro Matsufuji, Chuxuan Zhang, Angelica Lim</i>   |      |

|   |      |
|---|------|
| Persuasive Polite Robots in Free-Standing Conversational Groups .....   | 2974 |
| <i>Sahba Zojaji, Adrian Benigno Latupeirissa, Iolanda Leite, Roberto Bresin, Christopher Peters</i>   |      |
| Social Triangles and Aggressive Lines: Multi-Robot Formations Impact Navigation and Approach .....  | 2982 |
| <i>Alexandra Bacula, Ethan Villalovoz, Deanna Flynn, Ankur Mehta, Heather Knight</i>  |      |
| How to Make a Robot Grumpy Teaching Social Robots to Stay in Character with Mood Steering .....   | 2989 |
| <i>Eric Nichols, Deborah Szapiro, Yurii Vasylkiv, Randy Gomez</i>   |      |
| Enhancing Teleoperated Robot Customer Service Through Speech Monitoring and Filtering .....   | 2997 |
| <i>Koki Yamada, Jani Even, Takayuki Kanda</i>   |      |
| T2FPV: Dataset and Method for Correcting First-Person View Errors in Pedestrian Trajectory Prediction .....   | 3005 |
| <i>Benjamin Stoler, Meghdeep Jana, Soonmin Hwang, Jean Oh</i>   |      |
| Interactive Task Learning for Social Robots: A Pilot Study .....  | 3013 |
| <i>Alexander Tyshka, Wing-Yue Geoffrey Louie</i>  |      |
| Proactive Opinion-Driven Robot Navigation Around Human Movers .....   | 3020 |
| <i>Charlotte Cathcart, Maria Santos, Shinkyu Park, Naomi Ehrich Leonard</i>   |      |
| Emotionally Specific Backchanneling in Social Human-Robot Interaction and Human-Human Interaction.....  | 3027 |
| <i>Pourya Shahverdi, Katelyn Rousso, Justin Klotz, Iman Bakhoda, Malek Zribi, Wing-Yue Geoffrey Louie</i>   |      |
| Impact of Imperfect Exoskeleton Algorithms on Step Characteristics, Task Performance, and Perception of Exoskeleton Performance.....  | 3033 |
| <i>Man I Wu, Leia Stirling</i>  |      |
| Can Quadruped Guide Robots Be Used as Guide Dogs? .....   | 3039 |
| <i>Luyao Wang, Qihe Chen, Yan Zhang, Ziang Li, Tingmin Yan, Fan Wang, Guyue Zhou, Jiangtao Gong</i>   |      |
| Investigating the Usability of Collaborative Robot Control Through Hands-Free Operation Using Eye Gaze and Augmented Reality .....  | 3046 |
| <i>Joosun Lee, Taeyhang Lim, Wansoo Kim</i>   |      |
| Development and Evaluation of Exploratory Experiences to Facilitate Reasoning About Robotic Systems.....  | 3052 |
| <i>Sogol Balali, Marisa Hudspeth, Ian Afflerbach, Hannah Helgesen, Jessica McCurry, Walid Abu Al-Afia, Kelton Bruslind, Kathryn Hays, Ross T. Sowell, Ruth West, Cindy M. Grimm</i> |      |
| Decoding sEMG Under Non-Ideal Conditions Toward Robust Muscle-Machine Interface Control .....   | 3060 |
| <i>C. D. Guerrero-Méndez, C. F. Blanco-Díaz, A. Lopez-Delis, T. Bastos-Filho, R. M. Andrade</i>   |      |
| From “Thumbs Up” to “10 Out of 10”: Reconsidering Scalar Feedback in Interactive Reinforcement Learning.....  | 3066 |
| <i>Hang Yu, Reuben M. Aronson, Katherine H. Allen, Elaine Schaertl Short</i>  |      |
| Towards Continuous Identification of Passive Human Joint Impedance Using Physical Human-Robot Interaction System .....  | 3074 |
| <i>Bilal Tout, Jason Chevrie, Antoine Dequidt, Laurent Vermeiren</i>  |      |

|   |      |
|---|------|
| The MyoPassivity Puzzle: How Does Muscle Fatigue Affect Energetic Behavior of the Human Upper-Limb During Physical Interaction with Robots? .....   | 3080 |
| <i>Suzanne Oliver, Peter Paik, Xingyuan Zhou, S. Farokh Atashzar</i>  |      |
| Harnessing the Power of Human Biomechanics in Force-Position Domain: A 3D Passivity Index Map for Upper Limb Physical Human-(Tele) Robot Interaction.....                                   | 3086 |
| <i>Xingyuan Zhou, Peter Paik, S. Farokh Atashzar</i>  |      |
| No Contact Needed: Humans Adapt Their Gait to Suit Legged Robot Companions .....  | 3092 |
| <i>Paul M. Riek, Amy R. Wu</i>  |      |
| Implications of Personality on Cognitive Workload, Affect, and Task Performance in Remote Robot Control.....  | 3098 |
| <i>Go-Eum Cha, Wonse Jo, Byung-Cheol Min</i>  |      |
| Optimizing Algorithms from Pairwise User Preferences.....   | 3106 |
| <i>Leonid Keselman, Katherine Shih, Martial Hebert, Aaron Steinfield</i>  |      |
| A Sensitivity Analysis of an Economic Value Metric for Quantifying the Success of Lower-Limb Exoskeletons and Their Assistance.....   | 3113 |
| <i>Nundini D. Rawal, Roberto L. Medrano, Gray C. Thomas, Elliott J. Rouse</i>   |      |
| Multi-Arm Robot Task Planning for Fruit Harvesting Using Multi-Agent Reinforcement Learning .....   | 3121 |
| <i>Tao Li, Feng Xie, Quan Qiu, Qingchun Feng</i>  |      |
| Design, Modeling, and Control of a Low-Cost and Rapid Response Soft-Growing Manipulator for Orchard Operations .....  | 3129 |
| <i>Ryan Dorosh, Justin Allen, Zixuan He, Christopher Ninatanta, Jack Coleman, Jack Spieker, Ethan Tuck, Jordan Kurtz, Qin Zhang, Matthew D. Whiting, Jiecai Luo, Manoj Karkee, Ming Luo</i> |      |
| Lightweight Real-Time Detection Model for Multi-Sheep Abnormal Behaviour Based on Yolov7-Tiny .....   | 3136 |
| <i>Haotian Zhang, Yuan Ma, Xiaobo Wang, Rui Mao, Meili Wang</i>   |      |
| NBV-SC: Next Best View Planning Based on Shape Completion for Fruit Mapping and Reconstruction.....   | 3142 |
| <i>Rohit Menon, Tobias Zaenker, Nils Dengler, Maren Bennewitz</i>   |      |
| Knowledge Distillation for Efficient Panoptic Semantic Segmentation: Applied to Agriculture .....   | 3149 |
| <i>Maohui Li, Michael Haslestad, Chris McCool</i>   |      |
| Estimating 4D Data Associations Towards Spatial-Temporal Mapping of Growing Plants for Agricultural Robots .....  | 3157 |
| <i>Luca Lobefaro, Meher V. R. Malladi, Olga Vysotska, Tiziano Guadagnino, Cyrill Stachniss</i>  |      |
| Graph-Based View Motion Planning for Fruit Detection .....  | 3164 |
| <i>Tobias Zaenker, Julius Rückin, Rohit Menon, Marija Popovic, Maren Bennewitz</i>  |      |
| Panoptic Mapping with Fruit Completion and Pose Estimation for Horticultural Robots .....   | 3171 |
| <i>Yue Pan, Federico Magistri, Thomas Läbe, Elias Marks, Claus Smitt, Chris McCool, Jens Behley, Cyrill Stachniss</i>   |      |
| Vision-Based Vineyard Navigation Solution with Automatic Annotation.....  | 3179 |
| <i>Ertai Liu, Josephine Monica, Kaitlin Gold, Lance Cadle-Davidson, David Combs, Yu Jiang</i>   |      |

|  |      |
|--|------|
| Detecting Olives with Synthetic Or Real Data? Olive the Above .....  | 3187 |
| <i>Yianni Karabatis, Xiaomin Lin, Nitin J. Sanket, Michail G. Lagoudakis, Yiannis Aloimonos</i>                                    |      |
| Grasp State Classification in Agricultural Manipulation .....  | 3195 |
| <i>Benjamin Walt, Girish Krishnan</i>  |      |
| Skirting Line Estimation Using Sparse to Dense Deformation .....   | 3201 |
| <i>Daniel Perez Banuelos, Raphael Falque, Timothy Patten, Alen Alempijevic</i>   |      |
| Bird-View 3D Reconstruction for Crops with Repeated Textures.....  | 3208 |
| <i>Guoyu Lu</i>  |      |
| Generalized Robot Dynamics Learning and Gen2Real Transfer.....   | 3216 |
| <i>Dengpeng Xing, Yiming Yang, Zechang Wang, Jiale Li, Bo Xu</i>   |      |
| Dynamic Modeling and Analysis of Impact-Resilient MAVs Undergoing High-Speed and Large-Angle Collisions with the Environment ..... | 3222 |
| <i>Zhichao Liu, Konstantinos Karydis</i>   |      |
| Legged Locomotion Control of an Under-Actuated Eccentric Paddle Mechanism with Torso Stabilization.....                            | 3230 |
| <i>Yanqiu Zheng, Longchuan Li, Shugen Ma</i>   |      |
| Improving Deep Dynamics Models for Autonomous Vehicles with Multimodal Latent Mapping of Surfaces .....                            | 3236 |
| <i>Johan Vertens, Nicolai Dorka, Tim Welschehold, Michael Thompson, Wolfram Burgard</i>  |      |
| Data-Based MHE for Agile Quadrotor Flight.....   | 3244 |
| <i>Wonoo Choo, Erkan Kayacan</i>   |      |
| A Novel Approximation for the Spring Loaded Inverted Pendulum Model of Locomotion .....  | 3252 |
| <i>Ali U. Kilic, David J. Braun</i>  |      |
| A Fast Steerable Soft Robot for Navigating a Pipe Network.....   | 3259 |
| <i>Ian Stewart, Phanindra Tallapragada</i>   |      |
| An Orthogonal Collocation Method for Static and Dynamic Cosserat Rods .....  | 3265 |
| <i>Radhouane Jilani, Pierre-Frédéric Villard, Erwan Kerrien</i>  |      |
| Design, Characterization and Control of a Whole-Body Grasping and Perching (WHOPPER) Drone.....                                    | 3271 |
| <i>Weijia Tao, Karishma Patnaik, Fuchen Chen, Yogesh Kumar, Wenlong Zhang</i>  |      |
| A Rotor Flywheel Robot: Land-Air Amphibious Design and Control .....   | 3278 |
| <i>Chunzheng Wang, Yunyi Zhang, Chuanzhao Li, Wei Wang, Yangmin Li</i>   |      |
| System Identification and Control of Front-Steered Ackermann Vehicles Through Differentiable Physics.....                          | 3284 |
| <i>Burak M. Gonultas, Pratik Mukherjee, O. Goktug Poyrazoglu, Volkan Isler</i>   |      |
| Hardware-In-The-Loop Simulation of Vehicle-Manipulator Systems for Physical Interaction Tasks .....                                | 3291 |
| <i>Hemjyoti Das, Bjørn Kåre Sæbø, Kristin Y. Pettersen, Christian Ott</i>  |      |
| Modeling and Workspace Characterization of Continuously Compliant Robotic Legs .....   | 3298 |
| <i>Robin Bendfeld, C. David Remy</i>   |      |

|   |      |
|---|------|
| Efficiency Estimation and Optimization of Multistage Compound Planetary Gearboxes and Application to the Design of the Active Skin Propulsion of EELS ..... | 3305 |
| <i>Nikola Georgiev</i>  |      |
| Impact-Friendly Object Catching at Non-Zero Velocity Based on Combined Optimization and Learning .....  | 3313 |
| <i>Jianzhuang Zhao, Gustavo J. G. Lahr, Francesco Tassi, Alessandro Santopaoolo, Elena De Momi, Arash Ajoudani</i>  |      |
| Online Estimation of 2D Human Arm Stiffness for Peg-In-Hole Tasks with Variable Impedance Control.....  | 3321 |
| <i>Huayang Wu, Hanwen Yang, Yanan Li</i>  |      |
| Workspace Force/Acceleration Disturbance Observer for Precise and Safe Motion Control.....  | 3328 |
| <i>Wooseok Han, Wonbum Yun, Sehoon Oh</i>   |      |
| Orientation Control with Variable Stiffness Dynamical Systems.....  | 3335 |
| <i>Youssef Michel, Matteo Saveriano, Fares J. Abu-Dakka, Dongheui Lee</i>   |      |
| UMIRobot: An Open-{Software, Hardware} Low-Cost Robotic Manipulator for Education .....   | 3342 |
| <i>Murilo M. Marinho, Hung-Ching Lin, Jiawei Zhao</i>   |      |
| I2impedance - A Passivity Based Integrative Impedance Controller for Precise and Compliant Manipulation and Interaction.....                                | 3350 |
| <i>Florian Voigt, Abdeldjallil Naceri, Sami Haddadin</i>  |      |
| Real is Better than Perfect: Sim-To-Real Robotic System in Secondary School Education .....   | 3358 |
| <i>Jiasi Gao, Haole Guo, Zhanxiang Cao, Pengfei Huang, Guyue Zhou</i>   |      |
| A Soft, Multi-Layer, Kirigami Inspired Robotic Gripper with a Compact, Compression-Based Actuation System .....   | 3366 |
| <i>Joao Buzzatto, Junbang Liang, Mojtaba Shahmohammadi, Saori Matsunaga, Rintaro Haraguchi, Toshisada Mariyama, Bruce A. Macdonald, Minas Liaropoulos</i>   |      |
| Visuotactile Sensor Enabled Pneumatic Device Towards Compliant Oropharyngeal Swab Sampling .....  | 3374 |
| <i>Shoujie Li, Mingshan He, Wenbo Ding, Linqi Ye, Xueqian Wang, Junbo Tan, Jinqui Yuan, Xiao-Ping Zhang</i>   |      |
| Mathematical Modelling and Experimental Validation of an Articulated Vacuum Gripper .....   | 3382 |
| <i>Matteo Maggi, Giulio Reina, Giacomo Mantriota</i>  |      |
| Lip-Inspired Passive Jamming Gripper with Teeth Structure .....   | 3388 |
| <i>Jooyoung Hong, Kazuki Shin, Dhruv C Mathur, Sankalp Yamsani, Joohee Yim, Joohyung Kim</i>  |      |
| Two-Fingered Hand with Gear-Type Synchronization Mechanism with Magnet for Improved Small and Offset Objects Grasping: F2 Hand.....                         | 3395 |
| <i>Naoki Fukaya, Avinash Ummadisingu, Kuniyuki Takahashi, Guilherme Maeda, Shin-Ichi Maeda</i>  |      |
| An Inflatable Eversible Finger Pad for Variable-Stiffness Grasping with Parallel-Jaw Grippers .....   | 3403 |
| <i>Raphael Deimel, Andreas Kugi</i>   |      |
| D-PALI: A Low-Cost Open Source Robotic Gripper Platform for Planar In-Hand-Manipulation.....  | 3410 |
| <i>Arunansu Patra, Adam J. Spiers</i>   |      |
| Adaptive and Fail-Safe Magnetic Gripper with Charging Function for Drones on Power Lines.....   | 3417 |
| <i>Viet Duong Hoang, Aljaz Kramberger, Emad Ebeid</i>   |      |

|  |      |
|--|------|
| InstaGrasp: An Entirely 3D Printed Adaptive Gripper with TPU Soft Elements and Minimal Assembly Time .....   | 3425 |
| <i>Xin Zhou, Adam J. Spiers</i>  |      |
| A Bio-Inspired Robotic Finger: Mechanics and Control .....   | 3432 |
| <i>Worathris Chungsangsatiporn, Ratchatin Chancharoen</i>  |      |
| Autonomous Robotic Drilling System for Mice Cranial Window Creation: An Evaluation with an Egg Model.....  | 3438 |
| <i>Enduo Zhao, Murilo M. Marinho, Kanako Harada</i>  |      |
| Towards an Accurate Augmented-Reality-Assisted Orthopedic Surgical Robotic System Using Bidirectional Generalized Point Set Registration .....       | 3446 |
| <i>Ang Zhang, Zhe Min, Yingying Wang, Max Q.-H. Meng</i>   |      |
| Generalizing Surgical Instruments Segmentation to Unseen Domains with One-To-Many Synthesis .....  | 3454 |
| <i>An Wang, Mobarakol Islam, Mengya Xu, Hongliang Ren</i>  |      |
| Reducing Workload During Brain Surgery with Robot-Assisted Autonomous Exoscope .....   | 3461 |
| <i>Elisa Iovene, Alessandro Casella, Junling Fu, Federico Pessina, Marco Riva, Giancarlo Ferrigno, Elena De Momi</i>                                 |      |
| Augmented Reality Navigation in Robot-Assisted Surgery with a Teleoperated Robotic Endoscope .....   | 3467 |
| <i>Veronica Penza, Alberto Neri, Maria Koskinopoulou, Enrico Turco, Domenico Soriero, Stefano Scabini, Domenico Prattichizzo, Leonardo S. Mattos</i> |      |
| See What a Strabismus Patient Sees Using Eye Robots.....   | 3473 |
| <i>Yidi Huang, Qi Wei, Joseph L. Demer, Ningshi Yao</i>  |      |
| Visual-Kinematics Graph Learning for Procedure-Agnostic Instrument Tip Segmentation in Robotic Surgeries .....                                       | 3479 |
| <i>Jiaqi Liu, Yonghao Long, Kai Chen, Cheuk Hei Leung, Zerui Wang, Qi Dou</i>  |      |
| Dynamic Heart Simulator for Ultrasound-Guided Pericardiocentesis.....  | 3486 |
| <i>Kim Yan, Wanquan Yan, Shing Shin Cheng</i>  |      |
| Method for Robotic Motion Compensation During PET Imaging of Mobile Subjects.....  | 3494 |
| <i>Junxiang Wang, Iulian Iordachita, Peter Kazanzides</i>  |      |
| On the Potentials of Surface Tactile Imaging and Dilated Residual Networks for Early Detection of Colorectal Cancer Polyps .....                     | 3501 |
| <i>Nethra Venkatayogi, Qin Hu, Ozdemir Can Kara, Tarunraj G. Mohanraj, S. Farokh Atashzar, Farshid Alambeigi</i>                                     |      |
| A Smart Handheld Edge Device for on-Site Diagnosis and Classification of Texture and Stiffness of Excised Colorectal Cancer Polyps.....              | 3508 |
| <i>Ozdemir Can Kara, Jiaqi Xue, Nethra Venkatayogi, Tarunraj G. Mohanraj, Yuki Hirata, Naruhiko Ikoma, S. Farokh Atashzar, Farshid Alambeigi</i>     |      |
| Underwater and Surface Aquatic Locomotion of Soft Biomimetic Robot Based on Bending Rolled Dielectric Elastomer Actuators.....                       | 3515 |
| <i>Chenyu Zhang, Chen Zhang, Juntian Qu, Xiang Qian</i>  |      |
| Swarm of One: Bottom-Up Emergence of Stable Robot Bodies from Identical Cells .....  | 3521 |
| <i>Trevor Smith, R. Michael Butts, Nathan Adkins, Yu Gu</i>  |      |

|  |      |
|--|------|
| Real-Time Pose Estimation of Rats Based on Stereo Vision Embedded in a Robotic Rat .....   | 3528 |
| <i>Xiaowen Guo, Guanglu Jia, Mohamed Al-Khulaqui, Zhe Chen, Toshio Fukuda, Qing Shi</i>  |      |
| Design and Development of a Rapidly Deployable Low-Cost Tensegrity In-Pipe Robot.....  | 3534 |
| <i>Xixiang Liu, Xiaolin Dai, Kai Guo, Jiang Wu, Rui Song, Jie Zhao, Yibin Li</i>   |      |
| Reinforcement Learning Based Multi-Layer Bayesian Control for Snake Robots in Cluttered<br>Scenes.....                             | 3540 |
| <i>Jessica Ziyu Qu, William Ziming Qu, Li Li, Yuanyuan Jia</i>   |      |
| Roblets: Robotic Tablets that Self-Assemble and Self-Fold into a Robot.....  | 3547 |
| <i>Junyi Han, Daniela Rus, Shuhei Miyashita</i>  |      |
| Output Feedback Formation Control of a School of Robotic Fish with Artificial Lateral Line<br>Sensing .....                        | 3553 |
| <i>Artur Wolek, Derek A. Paley</i>   |      |
| An Origami-Based Miniature Jumping Robot with Adjustable Jumping Trajectory and Enhanced<br>Intermittent Jumps.....                | 3559 |
| <i>Zhipeng Xiong, Lingqi Tang, Longlong Hu, Songlin Yang, Xiaojun Yang, Yao Li, Bing Li</i>  |      |
| Finding the Goal: Insect-Inspired Spiking Neural Network for Heading Error Estimation .....  | 3565 |
| <i>Thorben Schoepe, Elisabetta Chicca</i>  |      |
| Motion Control and Planning of a Bio-Inspired Aerial Vehicle with an Actively Controlled<br>Abdomen-Like Appendage.....            | 3572 |
| <i>Berrin Güney, Mustafa Mert Ankarali</i>   |      |
| A Tailsitter UAV Based on Bioinspired, Tendon-Driven, Shape-Morphing Wings with Aerofoil-<br>Shaped Artificial Feathers .....      | 3580 |
| <i>Junbang Liang, Joao Buzzatto, Minas Liarokapis</i>  |      |
| How to Achieve Maneuverability and Adaptability in an Underactuated Robotic Fish by Using a<br>Bio-Inspired Control Approach ..... | 3587 |
| <i>Gianluca Manduca, Gaspare Santaera, Paolo Dario, Cesare Stefanini, Donato Romano</i>  |      |
| An Energy-Efficient Lane-Keeping System Using 3D LiDAR Based on Spiking Neural Network .....                                       | 3593 |
| <i>Genghang Zhuang, Zhenshan Bing, Zhen Zhou, Xiangtong Yao, Yuhong Huang, Kai Huang,<br/>Alois Knoll</i>                          |      |
| Approximation Algorithms for Charging Station Placement for Mobile Robots .....  | 3600 |
| <i>Tanmoy Kundu, Indranil Saha</i>   |      |
| LQR-Trees with Sampling Based Exploration of the State Space.....  | 3607 |
| <i>Jirí Fejlek, Stefan Ratschan</i>  |      |
| Simultaneous Survey and Inspection with Autonomous Underwater Vehicles .....   | 3613 |
| <i>James McMahon, Riley Parker, Philip Baldoni, Stuart Anstee, Erion Plaku</i>   |      |
| Relative Roughness Measurement Based Real-Time Speed Planning for Autonomous Vehicles on<br>Rugged Road .....                      | 3620 |
| <i>Liang Wang, Tianwei Niu, Shoukun Wang, Shuai Wang, Junzheng Wang</i>  |      |
| Real-Time Motion Planning Framework for Autonomous Vehicles with Learned Committed<br>Trajectory Distribution .....                | 3627 |
| <i>Minsoo Kim, Seho Shin, Joonwoo Ahn, Jaeheung Park</i>   |      |

|  |      |
|--|------|
| A Visibility-Based Escort Problem.....   | 3634 |
| <i>Lance G. Fletcher, Priyankari Perali, Andrew Beathard, Jason M. O'Kane</i>  |      |
| Enhancing Value Estimation Policies by Post-Hoc Symmetry Exploitation in Motion Planning<br>Tasks.....   | 3642 |
| <i>Yazied Hasan, Ariana M. Villegas-Suarez, Evan C. Carter, Aleksandra Faust, Lydia Tapia</i>  |      |
| Risk-Aware Emergency Landing Planning for Gliding Aircraft Model in Urban Environments .....   | 3650 |
| <i>Jakub Sláma, Jáchym Herynek, Jan Faigl</i>  |      |
| SCTOMP: Spatially Constrained Time-Optimal Motion Planning .....   | 3657 |
| <i>Jon Arrizabalaga, Markus Ryll</i>   |      |
| Consecutive Inertia Drift of Autonomous RC Car Via Primitive-Based Planning and Data-Driven<br>Control.....  | 3665 |
| <i>Yiwen Lu, Bo Yang, Jiayun Li, Yihan Zhou, Hongshuai Chen, Yilin Mo</i>  |      |
| A Hybrid-State Path Planner for ASV Formations with Full-Scale Experiments.....  | 3671 |
| <i>Else-Line M. Ruud, Marius S. Rundhovde, Jarle Sandrib, Glenn Bitar</i>  |      |
| CAT-RRT: Motion Planning that Admits Contact One Link at a Time.....   | 3679 |
| <i>Nataliya Nechyporenko, Caleb Escobedo, Shreyas Kadekodi, Alessandro Roncone</i>   |      |
| Novel Gripper with Rotatable Distal Joints for Home Robots: Picking and Placing Tableware .....  | 3687 |
| <i>Sung-Woo Kim, Cheog Gyu Hwang, Sunkyun Yoo, Youngdae Ko, Sungchul Kang</i>  |      |
| Prioritized Planning for Target-Oriented Manipulation Via Hierarchical Stacking Relationship<br>Prediction .....   | 3695 |
| <i>Zewen Wu, Jian Tang, Xingyu Chen, Chengzhong Ma, Xuguang Lan, Nanning Zheng</i>   |      |
| Task-Oriented Grasp Prediction with Visual-Language Inputs .....   | 3703 |
| <i>Chao Tang, Dehao Huang, Lingxiao Meng, Weiyu Liu, Hong Zhang</i>  |      |
| Learning to Grasp Clothing Structural Regions for Garment Manipulation Tasks.....  | 3711 |
| <i>Wei Chen, Dongmyoung Lee, Digby Chappell, Nicolas Rojas</i>   |      |
| External Sensor-Less in-Hand Object Position Manipulation for an Under-Actuated Hand Using<br>Data-Driven-Based Methods to Compensate for the Nonlinearity of Self-Locking Mechanism ..... | 3718 |
| <i>Ha Thang Long Doan, Hikaru Arita, Kenji Tahara</i>  |      |
| Contact-Aware Shaping and Maintenance of Deformable Linear Objects with Fixtures .....   | 3726 |
| <i>Kejia Chen, Zhenshan Bing, Fan Wu, Yuan Meng, Andre Kraft, Sami Haddadin, Alois Knoll</i>   |      |
| An Evaluation of Action Segmentation Algorithms on Bimanual Manipulation Datasets .....  | 3734 |
| <i>Andre Meixner, Franziska Krebs, Noémie Jaquier, Tamim Asfour</i>  |      |
| SoftGPT: Learn Goal-Oriented Soft Object Manipulation Skills by Generative Pre-Trained<br>Heterogeneous Graph Transformer .....  | 3742 |
| <i>Junjia Liu, Zhihao Li, Wanyu Lin, Sylvain Calinon, Kay Chen Tan, Fei Chen</i>   |      |
| Geometric Fault-Tolerant Control of Quadrotors in Case of Rotor Failures: An Attitude Based<br>Comparative Study .....   | 3748 |
| <i>Jennifer Yeom, Guanrui Li, Giuseppe Loianno</i>   |      |
| UAV-Based Trilateration System for Localization and Tracking of Radio-Tagged Flying Insects:<br>Development and Field Evaluation .....   | 3755 |
| <i>Jeonghyeon Pak, Bosung Kim, Chanyoung Ju, Sung Hyun You, Hyoung Il Son</i>  |      |

|  |      |
|--|------|
| Canfly: A Can-Sized Autonomous Mini Coaxial Helicopter.....  | 3763 |
| <i>Neng Pan, Rui Jin, Chao Xu, Fei Gao</i>   |      |
| Aerial Manipulator Systems Gain a New Skill: Achieve Contact-Based Landing on a Mobile Platform.....   | 3771 |
| <i>Xiangdong Meng, Yuqing He, Haoyang Xi, Jianda Han, Aiguo Song</i>   |      |
| AOSoar: Autonomous Orographic Soaring of a Micro Air Vehicle .....   | 3777 |
| <i>Sunyou Hwang, Bart D. W. Remes, Guido C. H. E. De Croon</i>   |      |
| Error-State Kalman Filter Based External Wrench Estimation for MAVs Under a Cascaded Architecture.....                                       | 3785 |
| <i>Yuhan Yin, Qingkai Yang, Hao Fang</i>   |      |
| Minimally Actuated Tiltrotor for Perching and Normal Force Exertion .....  | 3793 |
| <i>Dongjae Lee, Sunwoo Hwang, Changhyeon Kim, Seung Jae Lee, H. Jin Kim</i>  |      |
| Nonlinear Model Predictive Control for Cooperative Transportation and Manipulation of Cable Suspended Payloads with Multiple Quadrotors..... | 3800 |
| <i>Guanrui Li, Giuseppe Loianno</i>  |      |
| Image-Based Visual Servo Control for Aerial Manipulation Using a Fully-Actuated UAV .....  | 3808 |
| <i>Guanqi He, Yash Jangir, Junyi Geng, Mohammadreza Mousaei, Dongwei Bai, Sebastian Scherer</i>  |      |
| DroNeRF: Real-Time Multi-Agent Drone Pose Optimization for Computing Neural Radiance Fields .....  | 3816 |
| <i>Dipam Patel, Phu Pham, Aniket Bera</i>  |      |
| Generation of Time-Varying Impedance Attacks Against Haptic Shared Control Steering Systems .....  | 3822 |
| <i>Alireza Mohammadi, Hafiz Malik</i>  |      |
| Haptic Dataset Augmentation with Subjective QoE Labels Using Conditional Generative Adversarial Network .....                                | 3830 |
| <i>Zican Wang, Xiao Xu, Dong Yang, Zhenyu Wang, Sarah Shtaierman, Eckehard Steinbach</i>   |      |
| A Physically Based Deformable Model with Haptic Feedback for Real-Time Robotic Surgery Simulation .....                                      | 3837 |
| <i>Saul Heredia, Hiromasa Masuda, Atsushi Miyamoto, Yohei Kuroda</i>   |      |
| Learning Contact-Based State Estimation for Assembly Tasks.....  | 3845 |
| <i>Johannes Pankert, Marco Hutter</i>  |      |
| Evaluation of a 7-DoFs Robotic Manipulator as Haptic Interface During Planar Reaching Tasks .....  | 3853 |
| <i>Alessia Noccaro, Silvia Buscaglione, Mattia Pinardi, Giovanni Di Pino, Domenico Formica</i>   |      |
| Soft, Modular, Shape-Changing Displays with Hyperelastic Bubble Arrays .....   | 3859 |
| <i>Matthew R. Devlin, Tianshu Liu, Mengjia Zhu, Nathan S. Usevitch, Nicholas Colonnese, Amirhossein H. Memar</i>                             |      |
| Soft Optical Sensor and Haptic Feedback System for Remote and Robot-Assisted Palpation .....   | 3865 |
| <i>Arincheyan Gerald, Jonathan Ye, Rukaiya Batliwala, Patra Hsu, Johann Pang, Sheila Russo</i>   |      |
| TIMS: A Tactile Internet-Based Micromanipulation System with Haptic Guidance for Surgical Training .....                                     | 3872 |
| <i>Jialin Lin, Xiaoqing Guo, Wen Fan, Wei Li, Yuanyi Wang, Jiaming Liang, Jindong Liu, Weiru Liu, Lei Wei, Dandan Zhang</i>                  |      |

|   |      |
|---|------|
| A Teleoperated MR-Safe Haptic System for Magnetic Resonance Imaging-Guided Prostate Needle Biopsies .....   | 3880 |
| <i>Evelyn Mendoza, John P. Whitney</i>  |      |
| Symmetry-Based Modeling and Hybrid Orientation-Force Control of Wearable Cutaneous Haptic Device.....   | 3886 |
| <i>Somang Lee, Hyunsu Kim, Dongjun Lee</i>  |      |
| Learning-Augmented Model-Based Planning for Visual Exploration.....   | 3893 |
| <i>Yimeng Li, Arnab Debnath, Gregory J. Stein, Jana Košeká</i>  |      |
| DMCL: Robot Autonomous Navigation Via Depth Image Masked Contrastive Learning.....  | 3900 |
| <i>Jiahao Jiang, Ping Li, Xudong Lv, Yuxiang Yang</i>   |      |
| Image-Based Regularization for Action Smoothness in Autonomous Miniature Racing Car with Deep Reinforcement Learning.....                                       | 3907 |
| <i>Hoang-Giang Cao, I Lee, Bo-Jiun Hsu, Zheng- Yi Lee, Yu-Wei Shih, Hsueh-Cheng Wang, I-Chen Wu</i>   |      |
| UnLoc: A Universal Localization Method for Autonomous Vehicles Using LiDAR, Radar And/or Camera Input .....   | 3915 |
| <i>Muhammad Ibrahim, Naveed Akhtar, Saeed Anwar, Ajmal Mian</i>   |      |
| A Complementarity-Based Switch-Fuse System for Improved Visual Place Recognition.....   | 3923 |
| <i>Maria Waheed, Sania Waheed, Michael Milford, Klaus McDonald-Maier, Shoaib Ehsan</i>  |      |
| RREx-BoT: Remote Referring Expressions with a Bag of Tricks.....  | 3931 |
| <i>Gunnar A. Sigurdsson, Jesse Thomason, Gaurav S. Sukhatme, Robinson Piramuthu</i>   |      |
| PLPL-VIO: A Novel Probabilistic Line Measurement Model for Point-Line-Based Visual-Inertial Odometry.....   | 3939 |
| <i>Zewen Xu, Hao Wei, Fulin Tang, Yidi Zhang, Yihong Wu, Gang Ma, Shuzhe Wu, Xin Jin</i>  |      |
| Multi-Goal Audio-Visual Navigation Using Sound Direction Map .....  | 3947 |
| <i>Haru Kondoh, Asako Kanezaki</i>  |      |
| Directed Real-World Learned Exploration .....   | 3955 |
| <i>Matthias Hutsebaut-Buyssse, Ferran Gebelli Guinjoan, Erwin Rademakers, Steven Latré, Abdellatif Bey Temsamani, Kevin Mets, Erik Mannens, Tom De Schepper</i> |      |
| Learning Whom to Trust in Navigation: Dynamically Switching Between Classical and Neural Planning.....  | 3963 |
| <i>Sombit Dey, Assem Sadek, Gianluca Monaci, Boris Chidlovskii, Christian Wolf</i>  |      |
| Learning Deep Sensorimotor Policies for Vision-Based Autonomous Drone Racing .....  | 3971 |
| <i>Jiawei Fu, Yunlong Song, Yan Wu, Fisher Yu, Davide Scaramuzza</i>  |      |
| Magnetic Navigation Using Attitude-Invariant Magnetic Field Information for Loop Closure Detection .....  | 3979 |
| <i>Natalia Pavlasek, Charles Champagne Cossette, David Roy-Guay, James Richard Forbes</i>   |      |
| Locking On: Leveraging Dynamic Vehicle-Imposed Motion Constraints to Improve Visual Localization.....   | 3986 |
| <i>Stephen Hausler, Sourav Garg, Punarjay Chakravarty, Shubham Shrivastava, Ankit Vora, Michael Milford</i>   |      |

|  |      |
|--|------|
| Uncertainty-Aware Gaussian Mixture Model for UWB Time Difference of Arrival Localization in Cluttered Environments.....                        | 3994 |
| <i>Wenda Zhao, Abhishek Goudar, Mingliang Tang, Xinyuan Qiao, Angela P. Schoellig</i>  |      |
| CREPES: Cooperative RElative Pose Estimation System.....   | 4002 |
| <i>Zhiren Xun, Jian Huang, Zhehan Li, Zhenjun Ying, Yingjian Wang, Chao Xu, Fei Gao, Yanjun Cao</i>  |      |
| Navlie: A Python Package for State Estimation on Lie Groups.....   | 4010 |
| <i>Charles Champagne Cossette, Mitchell Cohen, Vassili Korotkine, Arturo Del Castillo Bernal, Mohammed Ayman Shalaby, James Richard Forbes</i> |      |
| A Relative Infrastructure-Less Localization Algorithm for Decentralized and Autonomous Swarm Formation .....                                   | 4016 |
| <i>Dominik Schindler, Vlad Niculescu, Tommaso Polonelli, Daniele Palossi, Luca Benini, Michele Magno</i>                                       |      |
| RaSpectLoc: RAman SPECTroscopy-Dependent Robot LOCalisation .....  | 4024 |
| <i>Christopher Thirgood, Oscar Mendez, Erin Chao Ling, Jon Storey, Simon Hadfield</i>  |      |
| Need for Speed: Fast Correspondence-Free Lidar-Inertial Odometry Using Doppler Velocity .....  | 4032 |
| <i>David J. Yoon, Keenan Burnett, Johann Laconte, Yi Chen, Heethesh Vhayle, Soeren Kammler, James Reuther, Timothy D. Barfoot</i>              |      |
| Uncertainty Analysis for Accurate Ground Truth Trajectories with Robotic Total Stations .....  | 4040 |
| <i>Maxime Vaidis, William Dubois, Effie Daum, Damien Larocque, Francois Pomerleau</i>  |      |
| Graph Matching Optimization Network for Point Cloud Registration.....  | 4048 |
| <i>Qianliang Wu, Yaqi Shen, Haobo Jiang, Guofeng Mei, Yaqing Ding, Lei Luo, Jin Xie, Jian Yang</i>   |      |
| SEAL: Simultaneous Exploration and Localization for Multi-Robot Systems .....  | 4054 |
| <i>Ehsan Latif, Ramviyas Parasuraman</i>   |      |
| Discrete-Time Adaptive Control Algorithm for Coordination of Multiagent Systems in the Presence of Coupled Dynamics.....                       | 4062 |
| <i>Islam A. Aly, K. Merve Dogan</i>  |      |
| Risk-Tolerant Task Allocation and Scheduling in Heterogeneous Multi-Robot Teams.....   | 4068 |
| <i>Jinwoo Park, Andrew Messing, Harish Ravichandar, Seth Hutchinson</i>  |      |
| PuSHR: A Multirobot System for Nonprehensile Rearrangement.....  | 4076 |
| <i>Sidharth Talia, Arnav Thareja, Christoforos Mavrogiannis, Matt Schmittie, Siddhartha S. Srinivasa</i>                                       |      |
| Game-Theoretical Approach to Multi-Robot Task Allocation Using a Bio-Inspired Optimization Strategy.....                                       | 4084 |
| <i>Shengkang Chen, Tony X. Lin, Fumin Zhang</i>  |      |
| Multi-Robot Planning on Dynamic Topological Graphs Using Mixed- Integer Programming.....   | 4090 |
| <i>Cora A. Dimmig, Kevin C. Wolfe, Joseph Moore</i>  |      |
| Heterogeneous Coalition Formation and Scheduling with Multi-Skilled Robots.....  | 4098 |
| <i>Ashay Aswale, Carlo Pinciroli</i>   |      |
| Measuring Human-Robot Team Benefits Under Time Pressure in a Virtual Reality Testbed .....   | 4106 |
| <i>Katarina Popovic, Millicent Schlaflay, Ahalya Prabhakar, Christopher Kim, Todd D. Murphrey</i>  |      |

|   |      |
|---|------|
| Robust Electric Vehicle Balancing of Autonomous Mobility-On-Demand System: A Multi-Agent Reinforcement Learning Approach..... | 4114 |
| <i>Sihong He, Shuo Han, Fei Miao</i>  |      |
| Quantized Distillation: Optimizing Driver Activity Recognition Models for Resource-Constrained Environments.....              | 4122 |
| <i>Calvin Tanama, Kunyu Peng, Zdravko Marinov, Rainer Stiefelhagen, Alina Roitberg</i>  |      |
| Joint Out-Of-Distribution Detection and Uncertainty Estimation for Trajectory Prediction.....                                 | 4130 |
| <i>Julian Wiederer, Julian Schmidt, Ulrich Kressel, Klaus Dietmayer, Vasileios Belagiannis</i>                                |      |
| Deep Reinforcement Learning-Based Intelligent Traffic Signal Controls with Optimized CO2 Emissions .....                      | 4138 |
| <i>Pedram Agand, Alexey Iskrov, Mo Chen</i>   |      |
| Hierarchical Attention Network for Planning-Informed Multi-Agent Trajectory Prediction .....                                  | 4144 |
| <i>Wenyi Xiong, Jian Chen, Xinfang Zhang, Qi Wang, Ziheng Qi</i>  |      |
| A Two-Stage Based Social Preference Recognition in Multi-Agent Autonomous Driving System.....                                 | 4150 |
| <i>Jintao Xue, Dongkun Zhang, Rong Xiong, Yue Wang, Eryun Liu</i>   |      |
| RLPG: Reinforcement Learning Approach for Dynamic Intra-Platoon Gap Adaptation for Highway On-Ramp Merging.....               | 4157 |
| <i>Sushma Reddy Yadavalli, Lokesh Chandra Das, Myounggyu Won</i>  |      |
| P4P: Conflict-Aware Motion Prediction for Planning in Autonomous Driving .....  | 4165 |
| <i>Qiao Sun, Xin Huang, Brian C. Williams, Hang Zhao</i>  |      |
| A Thousand Worlds: Scenery Specification and Generation for Simulation-Based Testing of Mobile Robot Navigation Stacks .....  | 4172 |
| <i>Samuel Parra, Argentina Ortega, Sven Schneider, Nico Hochgeschwender</i>   |      |
| RAIST: Learning Risk Aware Traffic Interactions Via Spatio-Temporal Graph Convolutional Networks .....                        | 4180 |
| <i>Videsh Suman, Phu Pham, Aniket Bera</i>  |      |
| Look Before You Drive: Boosting Trajectory Forecasting Via Imagining Future .....   | 4186 |
| <i>Yixuan Fan, Xin Liu, Yali Li, Shengjin Wang</i>  |      |
| Leveraging Cloud Computing to Make Autonomous Vehicles Safer .....  | 4194 |
| <i>Peter Schafhalter, Sukrit Kalra, Le Xu, Joseph E. Gonzalez, Ion Stoica</i>   |      |
| Effective Traffic Signal Control with Offline-To-Online Reinforcement Learning .....  | 4202 |
| <i>Jinming Ma, Feng Wu</i>  |      |
| Learning from Symmetry: Meta-Reinforcement Learning with Symmetrical Behaviors and Language Instructions .....                | 4209 |
| <i>Xiangtong Yao, Zhenshan Bing, Genghang Zhuang, Kejia Chen, Hongkuan Zhou, Kai Huang, Alois Knoll</i>                       |      |
| A Multiplicative Value Function for Safe and Efficient Reinforcement Learning.....  | 4217 |
| <i>Nick Bührer, Zhejun Zhang, Alexander Liniger, Fisher Yu, Luc Van Gool</i>  |      |
| Energy Constrained Multi-Agent Reinforcement Learning for Coverage Path Planning.....   | 4225 |
| <i>Chenyang Zhao, Juan Liu, Suk-Un Yoon, Xinde Li, Heqing Li, Zhentong Zhang</i>  |      |

|   |      |
|---|------|
| Air-M: A Visual Reality Many-Agent Reinforcement Learning Platform for Large-Scale Aerial Unmanned System.....                        | 4233 |
| <i>Jiabin Lou, Wenjun Wu, Shuhao Liao, Rongye Shi</i>   |      |
| Nonprehensile Planar Manipulation Through Reinforcement Learning with Multimodal Categorical Exploration .....                        | 4241 |
| <i>Juan Del Aguila Ferrandis, João Moura, Sethu Vijayakumar</i>   |      |
| Efficient Domain Coverage for Vehicles with Second-Order Dynamics Via Multi-Agent Reinforcement Learning.....                         | 4249 |
| <i>Xinyu Zhao, Razvan C. Fetecau, Mo Chen</i>   |      |
| Domains as Objectives: Multi-Domain Reinforcement Learning with Convex-Coverage Set Learning for Domain Uncertainty Awareness.....    | 4257 |
| <i>Wendyam Eric Lionel Ilboudo, Taisuke Kobayashi, Takamitsu Matsubara</i>  |      |
| PIMbot: Policy and Incentive Manipulation for Multi-Robot Reinforcement Learning in Social Dilemmas .....                             | 4265 |
| <i>Shahab Nikkhoo, Zixin Li, Aritra Samanta, Yufei Li, Cong Liu</i>   |      |
| A Robust and Constrained Multi-Agent Reinforcement Learning Electric Vehicle Rebalancing Method in AMoD Systems .....                 | 4272 |
| <i>Sihong He, Yue Wang, Shuo Han, Shaofeng Zou, Fei Miao</i>  |      |
| Real-Time Model-Free Deep Reinforcement Learning for Force Control of a Series Elastic Actuator .....                                 | 4280 |
| <i>Ruturaj Sambhus, Aydin Gokce, Stephen Welch, Connor W. Herron, Alexander Leonessa</i>  |      |
| An Approach to Design a Biomechanically-Inspired Reward Function to Solve a Patience Cube Under Reinforcement Learning Framework..... | 4288 |
| <i>Janghyeon Kim, Ho-Jin Jung, Dae Han Sim, Ji-Hyeon Yoo, Song Woo Kim, Han Ul Yoon</i>   |      |
| MaskBEV: Joint Object Detection and Footprint Completion for Bird's-Eye View 3D Point Clouds .....                                    | 4296 |
| <i>William Guimont-Martin, Jean-Michel Fortin, François Pomerleau, Philippe Giguère</i>   |      |
| Disentangled Discriminator for Unsupervised Domain Adaptation on Object Detection .....   | 4304 |
| <i>Yangguang Zhu, Ping Guo, Haoran Wei, Xin Zhao, Xiangbin Wu</i>   |      |
| Open-Vocabulary Affordance Detection in 3D Point Clouds .....   | 4311 |
| <i>Toan Nguyen, Minh Nhat Vu, An Vuong, Dzung Nguyen, Thieu Vo, Ngan Le, Anh Nguyen</i>   |      |
| EvCenterNet: Uncertainty Estimation for Object Detection Using Evidential Learning .....  | 4318 |
| <i>Monish R. Nallapareddy, Kshitij Sirohi, Paulo L. J. Drews, Wolfram Burgard, Chih-Hong Cheng, Abhinav Valada</i>                    |      |
| SemanticBEVFusion: Rethinking LiDAR-Camera Fusion in Unified Bird's-Eye View Representation for 3D Object Detection.....              | 4326 |
| <i>Qi Jiang, Hao Sun</i>  |      |
| RFDNet: Real-Time 3D Object Detection Via Range Feature Decoration.....   | 4334 |
| <i>Hongda Chang, Lu Wang, Jun Cheng</i>   |      |
| Object-Level Unknown Obstacle Detection.....  | 4341 |
| <i>Chuan-Yuan Huang, Cheng-Tsung Chen, Yu-An Chen, Kuan-Wen Chen</i>  |      |

|  |      |
|--|------|
| BSH-Det3D: Improving 3D Object Detection with BEV Shape Heatmap.....   | 4349 |
| <i>You Shen, Yunzhou Zhang, Yanmin Wu, Zhenyu Wang, Linghao Yang, Sonya Coleman, Dermot Kerr</i>   |      |
| I3DOD: Towards Incremental 3D Object Detection Via Prompting .....   | 4357 |
| <i>Wenqi Liang, Gan Sun, Chenxi Liu, Jiahua Dong, Kangru Wang</i>  |      |
| SpinDOE: A Ball Spin Estimation Method for Table Tennis Robot .....  | 4363 |
| <i>Thomas Gossard, Jonas Tebbe, Andreas Ziegler, Andreas Zell</i>  |      |
| Enhancing Fine-Grained 3D Object Recognition Using Hybrid Multi-Modal Vision Transformer-CNN Models.....   | 4370 |
| <i>Songsong Xiong, Georgios Tzafas, Hamidreza Kasaie</i>   |      |
| ScAR: Scaling Adversarial Robustness for LiDAR Object Detection .....  | 4377 |
| <i>Xiaohu Lu, Hayder Radha</i>   |      |
| MDT3D: Multi-Dataset Training for LiDAR 3D Object Detection Generalization.....  | 4384 |
| <i>Louis Soum-Fontez, Jean-Emmanuel Deschaud, François Fleuret</i>   |      |
| Addressing the Scale Shrinkage Problem in Learning-Based Binocular Depth Estimation.....   | 4392 |
| <i>Gang Guo, Yixu Song, Fuchun Sun</i>   |      |
| Holistic Parking Slot Detection with Polygon-Shaped Representations.....   | 4400 |
| <i>Lihao Wang, Antonyo Musabini, Christel Leonet, Rachid Benmokhtar, Amaury Breheret, Chaima Yedes, Fabian Bürger, Thomas Boulay, Xavier Perrotton</i> |      |
| End-To-End Point Cloud Registration Via Rotation Equivariant Descriptors .....   | 4407 |
| <i>Yue Cao, Yujiao Shi, Ziang Cheng, Hongdong Li</i>   |      |
| The Audio-Visual BatVision Dataset for Research on Sight and Sound .....   | 4415 |
| <i>Amandine Brunetto, Sascha Hornauer, Stella X. Yu, Fabien Moutarde</i>   |      |
| Long-Range UAV Thermal Geo-Localization with Satellite Imagery.....  | 4423 |
| <i>Jiuhong Xiao, Daniel Tortei, Eloy Roura, Giuseppe Loianno</i>   |      |
| Sonar2Depth: Acoustic-Based 3D Reconstruction Using cGANs.....   | 4431 |
| <i>Nael Jaber, Bilal Wehbe, Frank Kirchner</i>   |      |
| Depth Self-Supervision for Single Image Novel View Synthesis.....  | 4439 |
| <i>Giovanni Minelli, Matteo Poggi, Samuele Salti</i>   |      |
| Skill Generalization with Verbs.....   | 4447 |
| <i>Rachel Ma, Lyndon Lam, Benjamin A. Spiegel, Aditya Ganeshan, Roma Patel, Ben Abatematteo, David Paulius, Stefanie Tellex, George Konidaris</i>      |      |
| Multi-Source Soft Pseudo-Label Learning with Domain Similarity-Based Weighting for Semantic Segmentation .....   | 4455 |
| <i>Shigemichi Matsuzaki, Hiroaki Masuzawa, Jun Miura</i>   |      |
| 3D-Aware Object Localization Using Gaussian Implicit Occupancy Function .....  | 4461 |
| <i>Vincent Gaudillière, Leo Pauly, Arunkumar Rathinam, Albert Garcia Sanchez, Mohamed Adel Musallam, Djamil Aouada</i>                                 |      |

|  |      |
|--|------|
| TransUPR: A Transformer-Based Plug-And-Play Uncertain Point Refiner for LiDAR Point Cloud Semantic Segmentation .....                            | 4467 |
| <i>Zifan Yu, Meida Chen, Zhikang Zhang, Suya You, Raghuveer Rao, Sanjeev Agarwal, Fengbo Ren</i>   |      |
| Null-Space Compliance Variation for Safe Human-Robot Collaboration in Redundant Manipulators Using Safety Control Barrier Functions .....        | 4473 |
| <i>Julian M. Salt Ducaju, Björn Olofsson, Anders Robertsson, Rolf Johansson</i>  |      |
| Collision Isolation and Identification Using Proprioceptive Sensing for Parallel Robots to Enable Human-Robot Collaboration .....                | 4480 |
| <i>Aran Mohammad, Moritz Schappler, Tobias Ortmaier</i>  |      |
| Interpretable Trajectory Prediction for Autonomous Vehicles Via Counterfactual Responsibility.....   | 4488 |
| <i>Kai-Chieh Hsu, Karen Leung, Yuxiao Chen, Jaime F. Fisac, Marco Pavone</i>   |      |
| Time-Optimal Path Tracking with ISO Safety Guarantees.....   | 4496 |
| <i>Shohei Fujii, Quang-Cuong Pham</i>  |      |
| Upper Bounds for Localization Errors in 2D Human Pose Estimation .....   | 4504 |
| <i>Patrick Schlosser, Christoph Ledermann, Tamim Asfour</i>  |      |
| Enhanced Performance of Human-Robot Collaboration Using Braking Surfaces and Trajectory Scaling.....   | 4512 |
| <i>Bakir Lacevic, Abdalla Reda Sobhy Ellithy Newishy, Andrea Maria Zanchettin, Paolo Rocco</i>   |      |
| Active Electric Perception-Based Haptic Modality with Applications to Robotics.....  | 4520 |
| <i>Michael Zechmair, Yannick Morel</i>   |      |
| Perirobot Space Representation for HRI: Measuring and Designing Collaborative Workspace Coverage by Diverse Sensors.....                         | 4528 |
| <i>Jakub Rozlivek, Petr Sváry, Matej Hoffmann</i>  |      |
| Safe Collision and Clamping Reaction for Parallel Robots During Human-Robot Collaboration .....  | 4536 |
| <i>Aran Mohammad, Moritz Schappler, Tim-Lukas Habich, Tobias Ortmaier</i>  |      |
| AmbiSense: Acoustic Field Based Blindspot-Free Proximity Detection and Bearing Estimation .....  | 4544 |
| <i>Siddharth Rupavatharam, Xiaoran Fan, Caleb Escobedo, Daewon Lee, Larry Jackel, Richard Howard, Colin Prepscious, Daniel Lee, Volkan Isler</i> |      |
| Extensions to Dynamically-Consistent Collision Reaction Control for Collaborative Robots.....  | 4552 |
| <i>Marie Harder, Maged Iskandar, Jinoh Lee, Alexander Dietrich</i>   |      |
| All Aware Robot Navigation in Human Environments Using Deep Reinforcement Learning.....  | 4559 |
| <i>Xiaojun Lu, Angela Faragasso, Atsushi Yamashita, Hajime Asama</i>   |      |
| Relationship Between Ankle Assistive Torque and Biomechanical Gait Metrics in Individuals After Stroke .....                                     | 4567 |
| <i>Jesús De Miguel-Fernández, Camille Pescatore, Alba Mesa-Garrido, Cindy Rikhof, Erik Prinsen, Josep M. Font-Llagunes, Joan Lobo-Prat</i>       |      |
| Experimental Evaluation of a Transparent Operation Mode for a Lower-Limb Exoskeleton Designed for Children with Cerebral Palsy .....             | 4575 |
| <i>Rafael M. Andrade, Stefano Sapienza, Abolfazl Mohebbi, Eric E. Fabara, Paolo Bonato</i>   |      |

|   |      |
|---|------|
| Effects of Personalization on Gait-State Tracking Performance Using Extended Kalman Filters .....   | 4581 |
| <i>José A. Montes-Pérez, Gray Cortright Thomas, Robert D. Gregg</i>   |      |
| State- Based Control for an Actuated Reciprocal Gait Orthosis.....  | 4588 |
| <i>Simon Eckstein, Bent Leudesdorff, Christophe Maufroy, Urs Schneider, C. David Remy</i>   |      |
| An Energetic Approach to Task-Invariant Ankle Exoskeleton Control .....   | 4595 |
| <i>Katharine Walters, Gray C. Thomas, Jianping Lin, Robert D. Gregg</i>   |      |
| Human-In-The-Loop Optimization of Active Back-Support Exoskeleton Assistance Via<br>Lumbosacral Joint Torque Estimation .....                 | 4603 |
| <i>Andreas Sochopoulos, Tommaso Poliero, Darwin Caldwell, Jesús Ortiz, Christian Di Natale</i>  |      |
| Closed-Loop Feedback Control of Human Step Width During Walking by Mediolaterally Acting<br>Robotic Hip Exoskeleton.....                      | 4610 |
| <i>Abbas Alili, Varun Nalam, Aaron Fleming, Ming Liu, Jesse Dean, Helen He Huang</i>  |      |
| Comparing the Effectiveness of Control Methodologies of a Hip-Knee-Ankle Exoskeleton During<br>Squatting.....                                 | 4616 |
| <i>Jared M. Li, Owen Winship, Stefan Fasano, Bridget Longo, Nicole M. Esposito, Gregory S. Sawicki, Robert J. Griffin, Gwendolyn M. Bryan</i> |      |
| A Novel Control Law for Multi-Joint Human-Robot Interaction Tasks While Maintaining Postural<br>Coordination.....                             | 4623 |
| <i>Keya Ghonasgi, Reuth Mirsky, Adrian M. Haith, Peter Stone, Ashish D. Deshpande</i>   |      |
| Investigations into Customizing Bilateral Ankle Exoskeletons to Increase Vertical Jumping<br>Performance.....                                 | 4630 |
| <i>Emily A. Bywater, Roberto Leo, Elliott J. Rouse</i>  |      |
| A Robotic Assistance Personalization Control Approach of Hip Exoskeletons for Gait Symmetry<br>Improvement .....                              | 4638 |
| <i>Qiang Zhang, Xikai Tu, Jennie Si, Michael D. Lewek, He Huang</i>   |      |
| Motion Degeneracy in Self-Supervised Learning of Elevation Angle Estimation for 2D Forward-<br>Looking Sonar .....                            | 4646 |
| <i>Yusheng Wang, Yonghoon Ji, Chujie Wu, Hiroshi Tsuchiya, Hajime Asama, Atsushi Yamashita</i>  |      |
| MIMIR-UW: A Multipurpose Synthetic Dataset for Underwater Navigation and Inspection.....  | 4654 |
| <i>Olaya Álvarez-Tuñón, Hemanth Kanner, Luiza Ribeiro Marnet, Huy Xuan Pham, Jonas Le Fevre Sejersen, Yury Brodskiy, Erdal Kayacan</i>        |      |
| Marine Vessel Attitude Estimation from Coastline and Horizon.....   | 4662 |
| <i>Shobhit Singhal, Yunke Ao, Deran Maas, Bruno Arsenali, Stefano Maranò</i>  |      |
| DANDELION: An ASV Deployed Micro-Profiler Array for Air-Sea Observation .....   | 4668 |
| <i>Zhihao Fan, Chenxin Lyu, Zheng Zeng</i>  |      |
| Long-Endurance Optical Seafloor Imaging Using Underwater Gliders: Concept, Development and<br>Initial Trials .....                            | 4675 |
| <i>Daniel Gregorek, Abraham Tibebu, Eduardo Caudet, Carlos Barrera, Ralf Bachmayer</i>  |      |
| Disturbance Preview for Non-Linear Model Predictive Trajectory Tracking of Underwater Vehicles<br>in Wave Dominated Environments .....        | 4682 |
| <i>Kyle L. Walker, Francesco Giorgio-Serchi</i>   |      |

|  |      |
|--|------|
| An Ensemble of Online Estimation Methods for One Degree-Of-Freedom Models of Unmanned Surface Vehicles: Applied Theory and Preliminary Field Results with Eight Vehicles ..... | 4690 |
| <i>Tyler M. Paine, Michael R. Benjamin</i>   |      |
| Robust Unmanned Surface Vehicle Navigation with Distributional Reinforcement Learning .....  | 4698 |
| <i>Xi Lin, John McConnell, Brendan Englot</i>  |      |
| Towards Full Actuation: Reconfigurable Micro Underwater Robots .....   | 4705 |
| <i>Nathalie Bauschmann, Daniel A Duecker, Thies L Alff, Rene C Hochdahl, Robert Seifried</i>   |      |
| Water Surface Walking of Six-Legged Robot by Controlling Attitude of Feet When it Enter Water .....  | 4713 |
| <i>Yuetong He, Yanqiu Zheng, Fumihiko Asano</i>  |      |
| Perseus AUV: Towards Linear Convoying of Agile A-Sized AUVs Through Acoustic Track-And-Trail .....   | 4719 |
| <i>Nicholas R. Rypkema, Supun Randeni, Michael Sacarny, Michael Benjamin, Michael Triantafyllou</i>  |      |
| An Open-Source Robotic Chinese Chess Player .....  | 4727 |
| <i>Shan An, Guangfu Che, Jinghao Guo, Yanjie Xu, Guoxin Wang, Konstantinos A. Tsintotas, Fukai Zhang, Junjie Ye, Changhong Fu, Haogang Zhu, Hong Zhang</i>                     |      |
| ETAUS: An Edge and Trustworthy AI UAV System with Self-Adaptivity for Air Quality Monitoring .....   | 4735 |
| <i>Chun-Hsian Huang, Wen-Tung Chen, Yi-Chun Chang, Kuan-Ting Wu, Ren-Hong Wang</i>   |      |
| fpgaDDS: An Intra-FPGA Data Distribution Service for ROS 2 Robotics Applications .....   | 4743 |
| <i>Christian Lienen, Sorel Horst Middeke, Marco Platzner</i>   |      |
| Enhancing 5G-Enabled Robots Autonomy by Radio-Aware Semantic Maps .....  | 4749 |
| <i>Adrian Lendinez, Lanfranco Zanzi, Sandra Moreno, Guillem Gari, Xi Li, Renxi Qiu, Xavier Costa-Pérez</i>   |      |
| SkiROS2: A Skill-Based Robot Control Platform for ROS .....  | 4755 |
| <i>Matthias Mayr, Francesco Rovida, Volker Krueger</i>   |      |
| Soy: An Efficient MILP Solver for Piecewise-Affine Systems .....   | 4763 |
| <i>Haoze Wu, Min Wu, Dorsa Sadigh, Clark Barrett</i>   |      |
| A Small Form Factor Aerial Research Vehicle for Pick-And-Place Tasks with Onboard Real-Time Object Detection and Visual Odometry .....   | 4771 |
| <i>Cora A. Dimmig, Anna Goodridge, Gabriel Baraban, Pupei Zhu, Joyraj Bhowmick, Marin Kobilarov</i>  |      |
| Ungar - A C++ Framework for Real-Time Optimal Control Using Template Metaprogramming .....   | 4779 |
| <i>Flavio De Vincenti, Stelian Coros</i>   |      |
| VaPr: Variable-Precision Tensors to Accelerate Robot Motion Planning .....   | 4786 |
| <i>Yu-Shun Hsiao, Siva Kumar Sastry Hari, Balakumar Sundaralingam, Jason Yik, Thierry Tambe, Charbel Sakr, Stephen W. Keckler, Vijay Janapa Reddi</i>                          |      |
| Scalable. Intuitive Human to Robot Skill Transfer with Wearable Human Machine Interfaces: On Complex, Dexterous Tasks .....  | 4792 |
| <i>Felipe Sanches, Geng Gao, Nathan Elangovan, Ricardo V. Godoy, Jayden Chapman, Ke Wang, Patrick Jarvis, Minas Liarokapis</i>   |      |

|  |      |
|--|------|
| Towards Cooperative Flight Control Using Visual-Attention .....  | 4800 |
| <i>Lianhao Yin, Makram Chahine, Tsun-Hsuan Wang, Tim Seyde, Chao Liu, Mathias Lechner, Ramin Hasani, Daniela Rus</i>   |      |
| Cyber-Attacks on Wheeled Mobile Robotic Systems with Visual Servoing Control.....  | 4808 |
| <i>Aleksandar Jokic, Amir Khazraei, Milica Petrovic, Zivana Jakovljevic, Miroslav Pajic</i>  |      |
| An Event-Based Tracking Control Framework for Multirotor Aerial Vehicles Using a Dynamic Vision Sensor and Neuromorphic Hardware .....                           | 4815 |
| <i>Sotirios N. Aspragkathos, Evangelos Ntouros, George C. Karras, B. Linares-Barranco, T. Serrano-Gotarredona, Kostas J. Kyriakopoulos</i>                       |      |
| Shape Servoing of a Soft Object Using Fourier Series and a Physics-Based Model.....  | 4822 |
| <i>Fouad Makiyeh, Fran ois Chaumette, Maud Marchal, Alexandre Krupa</i>  |      |
| Visual Servoing on Wheels: Robust Robot Orientation Estimation in Remote Viewpoint Control .....   | 4830 |
| <i>Luke Robinson, Daniele De Martini, Matthew Gadd, Paul Newman</i>  |      |
| Maintaining Visibility of Dynamic Objects in Cluttered Environments Using Mobile Manipulators and Vector Field Inequalities .....                                | 4837 |
| <i>Fatih Dursun, Bruno Vilhena Adorno, Simon Watson, Wei Pan</i>   |      |
| Shape Control of Variable Length Continuum Robots Using Clothoid-Based Visual Servoing.....  | 4845 |
| <i>Abhinav Gandhi, Shou-Shan Chiang, Cagdas D. Onal, Berk Calli</i>  |      |
| Keypoints-Based Adaptive Visual Servoing for Control of Robotic Manipulators in Configuration Space .....  | 4853 |
| <i>Sreejani Chatterjee, Abhay C. Karade, Abhinav Gandhi, Berk Calli</i>  |      |
| Autonomous Marker-Less Rapid Aerial Grasping .....   | 4861 |
| <i>Erik Bauer, Barnabas Gavin Cangan, Robert K. Katzschmann</i>  |      |
| Vision-Based Oxy-Fuel Torch Control for Robotic Metal Cutting.....   | 4869 |
| <i>James Akl, Yash Patil, Chinmay Todankar, Berk Calli</i>   |      |
| Kinematically-Decoupled Impedance Control for Fast Object Visual Servoing and Grasping on Quadruped Manipulators .....   | 4877 |
| <i>Riccardo Parosi, Mattia Risiglione, Darwin G. Caldwell, Claudio Semini, Victor Barasuol</i>   |      |
| Lyapunov Constrained Safe Reinforcement Learning for Multicopter Visual Servoing .....   | 4885 |
| <i>Dafang Yu, Mengxin Xu, Zhe Liu, Hesheng Wang</i>  |      |
| Employing Multi-Layer, Sensorised Kirigami Grippers for Single-Grasp Based Identification of Objects and Force Exertion Estimation .....                         | 4891 |
| <i>Junbang Liang, Joao Buzzatto, Bryan Busby, Ricardo V. Godoy, Saori Matsunaga, Rintaro Haraguchi, Toshisada Mariyama, Bruce A. Macdonald, Minas Liarokapis</i> |      |
| A Finite-Time State-Dependent Differential Riccati Equation Control Design for Closed-Loop SMA-Actuated Hip Joint.....   | 4899 |
| <i>V. Perez-Sanchez, S. R. Nekoo, B. Arrue, A. Ollero</i>  |      |
| Rapid Grasping of Fabric Using Bionic Soft Grippers with Elastic Instability .....   | 4907 |
| <i>Zechen Xiong, Zihan Guo, Li Yuan, Yufeng Su, Yitong Liu, Hod Lipson</i>   |      |
| Design of a Cable Driven Wearable Fitness Device for Upper Limb Exercise .....   | 4914 |
| <i>Junghoon Park, Dong Hyun Kim, Seungyong Hyung, Gyowook Shin, Youngtae G. Kim, Sang-Hun Kim, Chiyul Yoon, Sungchan Ko, Kyoungsoon Hahn, Minhyung Lee</i>       |      |

|   |      |
|---|------|
| Soft Cap for Vine Robots.....   | 4920 |
| <i>Cem Suulker, Sophie Skach, Danyaal Kaleel, Taqi Abrar, Zain Murtaza, Dilara Suulker, Kaspar Althoefer</i>                              |      |
| Learning Robotic Assembly by Leveraging Physical Softness and Tactile Sensing .....   | 4927 |
| <i>Joaquín Royo-Miquel, Masashi Hamaya, Cristian C. Beltran-Hernandez, Kazutoshi Tanaka</i>   |      |
| High-Curvature Consecutive Tip Steering of a Soft Growing Robot for Improved Target Reachability.....                                     | 4935 |
| <i>Dong-Geol Lee, Nam Gyun Kim, Jee-Hwan Ryu</i>  |      |
| Single Channel Soft Robotic Actuator Leveraging Switchable Strain-Limiting Structures for Deep-Sea Suction Sampling.....                  | 4942 |
| <i>Jan Peters, Cora Maria Sourkounis, Mats Wiese, Tom Kwasnitschka, Annika Raatz</i>  |      |
| Locomotion and Obstacle Avoidance of a Worm-Like Soft Robot .....   | 4949 |
| <i>Sean Even, Yasemin Ozkan-Aydin</i>   |      |
| EasyGaze3D: Towards Effective and Flexible 3D Gaze Estimation from a Single RGB Camera .....  | 4955 |
| <i>Jinkai Li, Jianxin Yang, Yuxuan Liu, Zhen Li, Guang-Zhong Yang, Yao Guo</i>  |      |
| Efficient Visual Perception of Human-Robot Walking Environments Using Semi-Supervised Learning .....                                      | 4962 |
| <i>Dmytro Kuzmenko, Oleksii Tsepa, Andrew Garrett Kurbis, Alex Mihailidis, Brokoslav Laschowski</i>                                       |      |
| Contactless Weight Estimation of Human Body and Body Parts for Safe Robotics-Assisted Casualty Extraction .....                           | 4968 |
| <i>Jaeyeon Lee, Ethan Quist, Jonathan Chambers, Michael Yip, Nathan Fisher</i>  |      |
| Feature-Based Visual Odometry for Bronchoscopy: A Dataset and Benchmark.....  | 4975 |
| <i>Jianning Deng, Peize Li, Kevin Dhaliwal, Chris Xiaoxuan Lu, Mohsen Khadem</i>  |      |
| Motion Magnification in Robotic Sonography: Enabling Pulsation-Aware Artery Segmentation .....  | 4983 |
| <i>Dianye Huang, Yuan Bi, Nassir Navab, Zhongliang Jiang</i>  |      |
| Compact and Accurate Adaptive Width Radial Basis Function Neural Network with Discriminative Features for Thyroid Gland Segmentation..... | 4989 |
| <i>Haijun You, Junying Chen</i>   |      |
| Unsupervised Deformable Ultrasound Image Registration and Its Application for Vessel Segmentation.....                                    | 4997 |
| <i>FNU Abhimanyu, Andrew L. Orekhov, Ananya Bal, John Galeotti, Howie Choset</i>  |      |
| Thoracic Cartilage Ultrasound-CT Registration Using Dense Skeleton Graph.....   | 5004 |
| <i>Zhongliang Jiang, Chenyang Li, Xuesong Li, Nassir Navab</i>  |      |
| Landmark Based Bronchoscope Localization for Needle Insertion Under Respiratory Deformation.....  | 5011 |
| <i>Inbar Fried, Janine Hoelscher, Jason A. Akulian, Stephen Pizer, Ron Alterovitz</i>   |      |
| Robotic Scene Segmentation with Memory Network for Runtime Surgical Context Inference .....   | 5019 |
| <i>Zongyu Li, Ian Reyes, Homa Alemzadeh</i>   |      |
| Modeling, Characterization, and Control of Bacteria-Inspired Bi-Flagellated Mechanism with Tumbling .....                                 | 5026 |
| <i>Zhuonan Hao, Sangmin Lim, Mohammad Khalid Jawed</i>  |      |

|  |      |
|--|------|
| Evolving Physical Instinct for Morphology and Control Co-Adaption.....   | 5034 |
| <i>Xinglin Chen, Da Huang, Minglong Li, Yishuai Cai, Zhuoer Wen, Zhongxuan Cai, Wenjing Yang</i>   |      |
| Development of a Five-Fingered Biomimetic Soft Robotic Hand by 3D Printing the Skin and Skeleton as One Unit.....  | 5042 |
| <i>Kazuhiro Miyama, Kento Kawaharazuka, Kei Okada, Masayuki Inaba</i>  |      |
| Design Method of a Kangaroo Robot with High Power Legs and an Articulated Soft Tail .....  | 5049 |
| <i>Shunnosuke Yoshimura, Temma Suzuki, Masahiro Bando, Sota Yuzaki, Kento Kawaharazuka, Kei Okada, Masayuki Inaba</i>                                      |      |
| Hovering Control of Flapping Wings in Tandem with Multi-Rotors.....  | 5057 |
| <i>Aniket Dhole, Bibek Gupta, Adarsh Salagame, Xuejian Niu, Yizhe Xu, Kaushik Venkatesh, Paul Ghanem, Ioannis Mandralis, Eric Sihite, Alireza Ramezani</i> |      |
| Development of an Autonomous Modular Swimming Robot with Disturbance Rejection and Path Tracking.....  | 5063 |
| <i>Hankun Deng, Colin Nitroy, Kundan Panta, Donghao Li, Shashank Priya, Bo Cheng</i>   |      |
| A Highly Maneuverable Flying Squirrel Drone with Controllable Foldable Wings.....  | 5070 |
| <i>Jun-Gill Kang, Dohyeon Lee, Soohee Han</i>  |      |
| Programable On-Chip Fabrication of Magnetic Soft Micro-Robot.....  | 5078 |
| <i>Yuke Li, Xiaoqing Tang, Xiaoming Liu, Dan Liu, Zhuo Chen, Masaru Kojima, Qiang Huang, Tatsuo Arai</i>   |      |
| Forward/Inverse Kinematics Modeling for Tensegrity Manipulator Based on Goal-Conditioned Variational Autoencoder.....                                      | 5086 |
| <i>Yuhei Yoshimitsu, Takayuki Osa, Shuhei Ikemoto</i>  |      |
| Nematode-Inspired Cable Routing Method for Cable Driven Redundant Manipulator.....   | 5092 |
| <i>Hoyoung Kim, Hosu Lee, Jungwon Yoon</i>   |      |
| Spiking Reinforcement Learning with Memory Ability for Mapless Navigation .....  | 5099 |
| <i>Bo Yang, Mengwen Yuan, Chengjun Zhang, Chaofei Hong, Gang Pan, Huajin Tang</i>  |      |
| Lightweight Neural Path Planning .....   | 5107 |
| <i>Jinsong Li, Shaochen Wang, Ziyang Chen, Zhen Kan, Jun Yu</i>  |      |
| Modeling Action Spatiotemporal Relationships Using Graph-Based Class-Level Attention Network for Long-Term Action Detection .....                          | 5113 |
| <i>Yuankai Wu, Xin Su, Driton Salihu, Hao Xing, Marsil Zakour; Constantin Patsch</i>   |      |
| Formal Composition of Robotic Systems as Contract Programs.....  | 5121 |
| <i>Mason Nakamura, Justin Svegliato, Samer B. Nashed, Shlomo Zilberstein, Stuart Russell</i>   |      |
| Competitive Ant Coverage: The Value of Pursuit.....  | 5127 |
| <i>Alon Shats, Michael Amir; Noa Agmon</i>   |      |
| Human-Aware Navigation in Crowded Environments Using Adaptive Proxemic Area and Group Detection .....  | 5135 |
| <i>Carlos Medina-Sánchez, Simon Janzon, Matteo Zella, Jesús Capitán, Pedro J. Marrón</i>   |      |
| Efficient Heuristics for Multi-Robot Path Planning in Crowded Environments .....   | 5143 |
| <i>Teng Guo, Jingjin Yu</i>  |      |

|   |      |
|---|------|
| Learning Depth Vision-Based Personalized Robot Navigation from Dynamic Demonstrations in Virtual Reality .....                        | 5151 |
| <i>Jorge De Heuvel, Nathan Corral, Benedikt Kreis, Jacobus Conradi, Anne Driemel, Maren Bennewitz</i>                                 |      |
| From Crowd Motion Prediction to Robot Navigation in Crowds.....   | 5159 |
| <i>Sriyash Poddar, Christoforos Mavrogiannis, Siddhartha S. Srinivasa</i>   |      |
| A Game-Theoretic Framework for Joint Forecasting and Planning .....   | 5167 |
| <i>Kushal Kedia, Prithwish Dan, Sanjiban Choudhury</i>  |      |
| Coordination of Bounded Rational Drones Through Informed Prior Policy.....  | 5173 |
| <i>Durgakant Pushp, Junhong Xu, Lantao Liu</i>  |      |
| Mapless Urban Robot Navigation by Following Pedestrians .....   | 5181 |
| <i>Sophie Buckeridge, Pamela Carreno-Medrano, Akansel Cosgun, Elizabeth Croft, Wesley P. Chan</i>                                     |      |
| Control of Cart-Like Nonholonomic Systems Using a Mobile Manipulator.....   | 5187 |
| <i>Sergio Aguilera, Seth Hutchinson</i>   |      |
| FRoGGeR: Fast Robust Grasp Generation Via the Min-Weight Metric.....  | 5195 |
| <i>Albert H. Li, Preston Culbertson, Joel W. Burdick, Aaron D. Ames</i>   |      |
| A Minimal Collision Strategy of Synergy Between Pushing and Grasping for Large Clusters of Objects.....                               | 5203 |
| <i>Chong Chen, Shijun Yan, Miaolong Yuan, Chiatpin Tay, Dongkyu Choi, Quang Dan Le</i>  |      |
| Towards Flexible Biolaboratory Automation: Container Taxonomy-Based, 3D-Printed Gripper Fingers* .....                                | 5209 |
| <i>Henning Zwirnmann, Dennis Knobbe, Utku Culha, Sami Haddadin</i>  |      |
| A Pretouch Perception Algorithm for Object Material and Structure Mapping to Assist Grasp and Manipulation Using a DMDSM Sensor ..... | 5217 |
| <i>Fengzhi Guo, Shuangyu Xie, Di Wang, Cheng Fang, Jun Zou, Dezheng Song</i>  |      |
| PoseFusion: Robust Object-In-Hand Pose Estimation with SelectLSTM .....   | 5225 |
| <i>Yuyang Tu, Junnan Jiang, Shuang Li, Norman Hendrich, Miao Li, Jianwei Zhang</i>  |      |
| MOMA-Force: Visual-Force Imitation for Real-World Mobile Manipulation.....  | 5233 |
| <i>Taozheng Yang, Ya Jing, Hongtao Wu, Jiafeng Xu, Kuankuan Sima, Guangzeng Chen, Qie Sima, Tao Kong</i>                              |      |
| Task-Oriented Grasping with Point Cloud Representation of Objects .....   | 5239 |
| <i>Aditya Patankar, Khiem Phi, Dasharadhan Mahalingam, Nilanjan Chakraborty, Iv Ramakrishnan</i>                                      |      |
| Refining 6-DoF Grasps with Context-Specific Classifiers.....  | 5247 |
| <i>Tasbolat Taunyazov, Heng Zhang, John Patrick Eala, Na Zhao, Harold Soh</i>   |      |
| Sequential Manipulation Planning for Over-Actuated Unmanned Aerial Manipulators .....   | 5254 |
| <i>Yao Su, Jiarui Li, Ziyuan Jiao, Meng Wang, Chi Chu, Hang Li, Yixin Zhu, Hangxin Liu</i>  |      |
| Force-Based Pose Regulation of a Cable-Suspended Load Using UAVs with Force Bias.....   | 5261 |
| <i>C. Gabellieri, M. Tognon, D. Sanalitro, A. Franchi</i>   |      |

|   |      |
|---|------|
| Roller-Quadrotor: A Novel Hybrid Terrestrial/Aerial Quadrotor with Unicycle-Driven and Rotor-Assisted Turning.....  | 5268 |
| <i>Zhi Zheng, Jin Wang, Yuze Wu, Qifeng Cai, Huan Yu, Ruibin Zhang, Jie Tu, Jun Meng, Guodong Lu, Fei Gao</i>   |      |
| HALO: A Safe, Coaxial, and Dual-Ducted UAV Without Servo.....   | 5276 |
| <i>Haotian Li, Nan Chen, Fanze Kong, Yuying Zou, Shenji Zhou, Dongjiao He, Fu Zhang</i>   |      |
| Learning to Open Doors with an Aerial Manipulator.....  | 5283 |
| <i>Eugenio Cuniato, Ismail Geles, Weixuan Zhang, Olov Andersson, Marco Tognon, Roland Siegwart</i>  |      |
| Planning and Control for a Dynamic Morphing-Wing UAV Using a Vortex Particle Model.....   | 5290 |
| <i>Gino Perrotta, Luca Scheuer, Yocheved Kopel, Max Basescu, Adam Polevoy, Kevin Wolfe, Joseph Moore</i>  |      |
| Physical Contact with Wall Using a Multirotor UAV Equipped with Add-On Thruster for Inspection Work .....   | 5296 |
| <i>Takamasa Kominami, Zou Liang, Ricardo Rosales Martinez, Hannibal Paul, Kazuhiro Shimonomura</i>  |      |
| DoubleBee: A Hybrid Aerial-Ground Robot with Two Active Wheels .....  | 5303 |
| <i>Muqing Cao, Xinhang Xu, Shenghai Yuan, Kun Cao, Kangcheng Liu, Lihua Xie</i>   |      |
| Swashplateless-Elevon Actuation for a Dual-Rotor Tail-Sitter VTOL UAV .....   | 5311 |
| <i>Nan Chen, Fanze Kong, Haotian Li, Jiayuan Liu, Ziwei Ye, Wei Xu, Fangcheng Zhu, Ximin Lyu, Fu Zhang</i>  |      |
| SBLimp: Design, Model, and Translational Motion Control for a Swing-Blimp .....   | 5318 |
| <i>Jiawei Xu, Diego S. D'Antonio, Dominic J. Ammirato, David Saldaña</i>  |      |
| On Semi-Autonomous Robotic Telemanipulation Employing Electromyography Based Motion Decoding and Potential Fields.....                                      | 5324 |
| <i>Bonnie Guan, Ricardo V. Godoy, Felipe Sanches, Anany Dwivedi, Minas Liarokapis</i>   |      |
| An Affordances and Electromyography Based Telemanipulation Framework for Control of Robotic Arm-Hand Systems .....  | 5331 |
| <i>Ricardo V. Godoy, Bonnie Guan, Anany Dwivedi, Minas Liarokapis</i>   |      |
| Orbital Head-Mounted Display: A Novel Interface for Viewpoint Control During Robot Teleoperation in Cluttered Environments .....                            | 5338 |
| <i>Sjoerd Kuitert, Jelle Hofland, Cock J. M. Heemskerk, David A. Abbink, Luka Peternel</i>  |      |
| Exploiting Task Tolerances in Mimicry-Based Telemanipulation .....  | 5345 |
| <i>Yeping Wang, Carter Sifferman, Michael Gleicher</i>  |      |
| Light-Field Visual System for the Remote Robot Operation Interface.....   | 5353 |
| <i>Tetsuro Morimoto, Masakazu Hirota, Kakeru Sasaki, Kanako Kato, Ryusei Takigawa, Shigenobu Yoneyama, Takao Hayashi, Takeshi Fujikado, Satoru Tokuhisa</i> |      |
| Performance Comparison of Teleoperation Interfaces for Ultra-Lightweight Anthropomorphic Arms .....   | 5359 |
| <i>Filip Zoric, Alejandro Suarez, Goran Vasiljevic, Matko Orsag, Zdenko Kovacic, Anibal Ollero</i>  |      |
| Human Preferred Augmented Reality Visual Cues for Remote Robot Manipulation Assistance: From Direct to Supervisory Control.....                             | 5367 |
| <i>Achyuthan Unni Krishnan, Tsung-Chi Lin, Zhi Li</i>   |      |

|   |      |
|---|------|
| A Shared Autonomous Nursing Robot Assistant with Dynamic Workspace for Versatile Mobile Manipulation .....  | 5373 |
| <i>Nikita Boguslavskii, Zhuoyun Zhong, Lorena Maria Genua, Zhi Li</i>   |      |
| Adaptive PD Control Using Deep Reinforcement Learning for Local-Remote Teleoperation with Stochastic Time Delays .....                            | 5379 |
| <i>Luc McCutcheon, Saber Fallah</i>   |      |
| Team Northeastern's Approach to ANA XPRIZE Avatar Final Testing: A Holistic Approach to Telepresence and Lessons Learned.....                     | 5387 |
| <i>Rui Luo, Chunpeng Wang, Colin Keil, David Nguyen, Henry Mayne, Stephen Alt, Eric Schwarm, Evelyn Mendoza, Taskin Padir, John Peter Whitney</i> |      |
| An Avatar Robot Overlaid with the 3D Human Model of a Remote Operator.....  | 5394 |
| <i>Ravi Tejwani, Chengyuan Ma, Paolo Bonato, H. Harry Asada</i>   |      |
| Adaptive Robust Model Predictive Control for Bilateral Teleoperation .....  | 5402 |
| <i>Fadi Alyousef Almasalmah, Hassan Omran, Chao Liu, Bernard Bayle</i>  |      |
| Augmented Avatar Toward Both Remote Communication and Manipulation Tasks .....  | 5408 |
| <i>Masaki Haruna, Masaki Ogino, Shigeaki Tagashira, Susumu Morita</i>   |      |
| MapNeRF: Incorporating Map Priors into Neural Radiance Fields for Driving View Simulation.....  | 5415 |
| <i>Chenming Wu, Jiadai Sun, Zhelun Shen, Liangjun Zhang</i>   |      |
| Object Goal Navigation with Recursive Implicit Maps.....  | 5422 |
| <i>Shizhe Chen, Thomas Chabal, Ivan Laptev, Cordelia Schmid</i>   |      |
| Vision-Based Autonomous Navigation for Unmanned Surface Vessel in Extreme Marine Conditions .....   | 5430 |
| <i>Muhayuddin Ahmed, Ahsan Baidar Bakht, Taimur Hassan, Waseem Akram, Ahmed Humais, Lakmal Seneviratne, Shaoming He, Defu Lin, Irfan Hussain</i>  |      |
| A Framework for Few-Shot Policy Transfer Through Observation Mapping and Behavior Cloning .....   | 5437 |
| <i>Yash Shukla, Bharat Kesari, Shivam Goel, Robert Wright, Jivko Sinapov</i>  |      |
| UVIO: An UWB-Aided Visual-Inertial Odometry Framework with Bias-Compensated Anchors Initialization.....   | 5444 |
| <i>Giulio Delama, Farhad Shamsfakhr, Stephan Weiss, Daniele Fontanelli, Alessandro Fomasier</i>   |      |
| Self-Supervised Object Goal Navigation with In-Situ Finetuning .....  | 5452 |
| <i>So Yeon Min, Yao-Hung Hubert Tsai, Wei Ding, Ali Farhadi, Ruslan Salakhutdinov, Yonatan Bisk, Jian Zhang</i>                                   |      |
| Tightly-Coupled Visual- DVL- Inertial Odometry for Robot-Based Ice-Water Boundary Exploration .....   | 5460 |
| <i>Lin Zhao, Mingxi Zhou, Brice Loose</i>   |      |
| ProxMaP: Proximal Occupancy Map Prediction for Efficient Indoor Robot Navigation .....  | 5468 |
| <i>Vishnu D. Sharma, Jingxi Chen, Pratap Tokekar</i>  |      |
| USA-Net: Unified Semantic and Affordance Representations for Robot Memory .....   | 5474 |
| <i>Ben Bolte, Austin Wang, Jimmy Yang, Mustafa Mukadam, Mrinal Kalakrishnan, Chris Paxton</i>   |      |
| Pred-NBV: Prediction-Guided Next-Best-View Planning for 3D Object Reconstruction.....   | 5482 |
| <i>Harnaik Dhami, Vishnu D. Sharma, Pratap Tokekar</i>  |      |

|   |      |
|---|------|
| Active Visual SLAM Based on Hierarchical Reinforcement Learning .....   | 5488 |
| <i>Wensong Chen, Wei Li, Andong Yang, Yu Hu</i>   |      |
| Robust Point Cloud Registration with Geometry-Based Transformation Invariant Descriptor.....  | 5496 |
| <i>Jianjie Lin, Markus Rickert, Long Wen, Yingbai Hu, Alois Knoll</i>   |      |
| Online Monocular Lane Mapping Using Catmull-Rom Spline.....   | 5504 |
| <i>Zhijian Qiao, Zehuan Yu, Huan Yin, Shaojie Shen</i>  |      |
| VDBblobx: Accurate and Efficient Distance Fields for Path Planning and Mesh Reconstruction.....                                       | 5512 |
| <i>Yinlong Bai, Zhiqiang Miao, Xiangke Wang, Yong Liu, Hesheng Wang, Yaonan Wang</i>  |      |
| Rollvox: Real-Time and High-Quality LiDAR Colorization with Rolling Shutter Camera.....   | 5520 |
| <i>Sheng Hong, Chunran Zheng, Huan Yin, Shaojie Shen</i>  |      |
| 360FusionNeRF: Panoramic Neural Radiance Fields with Joint Guidance .....   | 5527 |
| <i>Shreyas Kulkarni, Peng Yin, Sebastian Scherer</i>  |      |
| Multi-Session, Localization-Oriented and Lightweight LiDAR Mapping Using Semantic Lines and<br>Planes .....                           | 5535 |
| <i>Zehuan Yu, Zhijian Qiao, Liuyang Qiu, Huan Yin, Shaojie Shen</i>   |      |
| Real-Time Elevation Mapping with Bayesian Ground Filling and Traversability Analysis for UGV<br>Navigation .....                      | 5543 |
| <i>Han Xie, Xunyu Zhong, Bushi Chen, Pengfei Peng, Huosheng Hu, Qiang Liu</i>   |      |
| Geometrically Consistent Monocular Metric-Semantic 3D Mapping for Indoor Environments with<br>Transparent and Reflecting Objects..... | 5551 |
| <i>Malik Mohrat, Amiran Berkaev, Alexey Burkov, Sergey Kolyubin</i>   |      |
| PanopticNDT: Efficient and Robust Panoptic Mapping.....   | 5558 |
| <i>Daniel Seichter, Benedict Stephan, Söhnke Benedikt Fischedick, Steffen Müller, Leonard<br/>Rabes, Horst-Michael Gross</i>          |      |
| Range-Based GP Maps: Local Surface Mapping for Mobile Robots Using Gaussian Process<br>Regression in Range Space .....                | 5566 |
| <i>Margaret Hansen, David Wettergreen</i>   |      |
| Pseudo Inputs Optimisation for Efficient Gaussian Process Distance Fields .....   | 5574 |
| <i>Lan Wu, Cedric Le Gentil, Teresa Vidal-Calleja</i>   |      |
| Computing Motion Plans for Assembling Particles with Global Control.....  | 5581 |
| <i>Patrick Blumenberg, Arne Schmidt, Aaron T. Becker</i>  |      |
| Efficient Constrained Multi-Agent Trajectory Optimization Using Dynamic Potential Games.....  | 5588 |
| <i>Maulik Bhatt, Yixuan Jia, Negar Mehr</i>   |      |
| Bidirectional Search Strategy for Incremental Search-Based Path Planning.....   | 5596 |
| <i>Chenming Li, Han Ma, Jiankun Wang, Max Q.-H. Meng</i>  |      |
| HELSA: Hierarchical Reinforcement Learning with Spatiotemporal Abstraction for Large-Scale<br>Multi-Agent Path Finding.....           | 5603 |
| <i>Zhaoyi Song, Rongqing Zhang, Xiang Cheng</i>   |      |
| Learning to Schedule in Multi-Agent Pathfinding .....   | 5611 |
| <i>Kyuree Ahn, Heemang Park, Jinkyoo Park</i>   |      |

|   |      |
|---|------|
| See What the Robot Can't See: Learning Cooperative Perception for Visual Navigation .....                                   | 5618 |
| <i>Jan Blumenkamp, Qingbiao Li, Binyu Wang, Zhe Liu, Amanda Prorok</i>  |      |
| Counterexample Guided Abstraction Refinement with Non-Refined Abstractions for Multi-Goal<br>Multi-Robot Path Planning..... | 5626 |
| <i>Pavel Surynek</i>  |      |
| Asynchronous, Option-Based Multi-Agent Policy Gradient: A Conditional Reasoning Approach.....                               | 5633 |
| <i>Xubo Lyu, Amin Banitalebi-Dehkordi, Mo Chen, Yong Zhang</i>  |      |
| Decentralised Multi-Robot Exploration Using Monte Carlo Tree Search.....  | 5639 |
| <i>Sean Bone, Luca Bartolomei, Florian Kennel-Maushart, Margarita Chli</i>  |      |
| Task Assignment, Scheduling, and Motion Planning for Automated Warehouses for Million Product<br>Workloads.....             | 5647 |
| <i>Christopher Leet, Chanwook Oh, Michele Lora, Sven Koenig, Pierluigi Nuzzo</i>  |      |
| LiDAR Missing Measurement Detection for Autonomous Driving in Rain .....  | 5655 |
| <i>Chen Zhang, Zefan Huang, Marcelo H. Ang, Daniela Rus</i>   |      |
| SMART-Degradation: A Dataset for LiDAR Degradation Evaluation in Rain.....  | 5662 |
| <i>Chen Zhang, Zefan Huang, Beatrix Xue Lin Tung, Marcelo H. Ang, Daniela Rus</i>   |      |
| Streaming Motion Forecasting for Autonomous Driving .....   | 5669 |
| <i>Ziqi Pang, Deva Ramanan, Mengtian Li, Yu-Xiong Wang</i>  |      |
| Leveraging Multimodal Sensing and Topometric Mapping for Human-Like Autonomous<br>Navigation in Complex Environments .....  | 5677 |
| <i>Kosmas Tsiakas, Dimitrios Alexiou, Dimitrios Giakoumis, Antonios Gasteratos, Dimitrios<br/>Tzovaras</i>                  |      |
| Towards Autonomous Robot Navigation in Human Populated Environments Using an Universal<br>SFM and Parametrized MPC .....    | 5684 |
| <i>Enrico Fiasché, Philippe Martinet, Ezio Malis</i>  |      |
| Pseudo-Stereo++: Cycled Generative Pseudo-Stereo for Monocular 3D Object Detection in<br>Autonomous Driving .....           | 5690 |
| <i>Ahmed Elhagry, Hang Dai, Abdulmotaleb El Saddik</i>  |      |
| Aggressive Trajectory Generation for a Swarm of Autonomous Racing Drones .....  | 5698 |
| <i>Yuyang Shen, Jin Zhou, Danzhe Xu, Fangguo Zhao, Jinming Xu, Jiming Chen, Shuo Li</i>                                     |      |
| Toward Human-Like Social Robot Navigation: A Large-Scale, Multi-Modal, Social Human<br>Navigation Dataset .....             | 5704 |
| <i>Duc M. Nguyen, Mohammad Nazeri, Amirreza Payandeh, Aniket Datar, Xuesu Xiao</i>  |      |
| Hilbert Space Embedding-Based Trajectory Optimization for Multi-Modal Uncertain Obstacle<br>Trajectory Prediction .....     | 5710 |
| <i>Basant Sharma, Aditya Sharma, K. Madhava Krishna, Arun Kumar Singh</i>   |      |
| Risk-Sensitive Mobile Robot Navigation in Crowded Environment Via Offline Reinforcement<br>Learning .....                   | 5718 |
| <i>Jiaxu Wu, Yusheng Wang, Hajime Asama, Qi An, Atsushi Yamashita</i>   |      |
| GP-Guided MPPI for Efficient Navigation in Complex Unknown Cluttered Environments .....                                     | 5725 |
| <i>Ihab S. Mohamed, Mahmoud Ali, Lantao Liu</i>   |      |

|  |      |
|--|------|
| V2X-Lead: LiDAR-Based End-To-End Autonomous Driving with Vehicle-To-Everything Communication Integration.....  | 5733 |
| <i>Zhiyun Deng, Yanjun Shi, Weiming Shen</i>   |      |
| C <sup>2</sup> : Co-Design of Robots Via Concurrent-Network Coupling Online and Offline Reinforcement Learning .....   | 5741 |
| <i>Ci Chen, Pingyu Xiang, Haojian Lu, Yue Wang, Rong Xiong</i>   |      |
| Autonomous Exploration and Mapping for Mobile Robots Via Cumulative Curriculum Reinforcement Learning.....   | 5749 |
| <i>Zhi Li, Jinghao Xin, Ning Li</i>  |      |
| Learning to Solve Tasks with Exploring Prior Behaviours.....   | 5755 |
| <i>Ruiqi Zhu, Siyuan Li, Tianhong Dai, Chongjie Zhang, Oya Celiktutan</i>  |      |
| Comparing Quadrotor Control Policies for Zero-Shot Reinforcement Learning Under Uncertainty and Partial Observability .....  | 5762 |
| <i>Sven Gronauer, Daniel Stümke, Klaus Diepold</i>   |      |
| Reducing Safety Interventions in Provably Safe Reinforcement Learning .....  | 5769 |
| <i>Jakob Thumm, Guillaume Pelat, Matthias Althoff</i>  |      |
| Bootstrapping Adaptive Human-Machine Interfaces with Offline Reinforcement Learning .....  | 5777 |
| <i>Jensen Gao, Siddharth Reddy, Glen Berseth, Anca D. Dragan, Sergey Levine</i>  |      |
| End-To-End Reinforcement Learning for Torque Based Variable Height Hopping .....   | 5785 |
| <i>Raghav Soni, Daniel Harnack, Hauke Isermann, Sotaro Fushimi, Shivesh Kumar, Frank Kirchner</i>  |      |
| Offline Reinforcement Learning for Quadrotor Control: Overcoming the Ground Effect.....  | 5793 |
| <i>Luca Sacchetto, Mathias Korte, Sven Gronauer, Matthias Kissel, Klaus Diepold</i>  |      |
| Dynamic Decision Frequency with Continuous Options.....  | 5799 |
| <i>Amirmohammad Karimi, Jun Jin, Jun Luo, A. Rupam Mahmood, Martin Jagersand, Samuele Tosatto</i>  |      |
| Imitation is Not Enough: Robustifying Imitation with Reinforcement Learning for Challenging Driving Scenarios .....  | 5807 |
| <i>Yiren Lu, Justin Fu, George Tucker, Xinlei Pan, Eli Bronstein, Rebecca Roelofs, Benjamin Sapp, Brandyn White, Aleksandra Faust, Shimon Whiteson, Dragomir Anguelov, Sergey Levine</i> |      |
| Boosting Feedback Efficiency of Interactive Reinforcement Learning by Adaptive Learning from Scores .....  | 5815 |
| <i>Shukai Liu, Chenming Wu, Ying Li, Liangjun Zhang</i>  |      |
| Dual Variable Actor-Critic for Adaptive Safe Reinforcement Learning .....  | 5822 |
| <i>Junseo Lee, Jaeseok Heo, Dohyeong Kim, Gunmin Lee, Songhwai Oh</i>  |      |
| Multimodal Diffusion Segmentation Model for Object Segmentation from Manipulation Instructions .....   | 5828 |
| <i>Yui Iioka, Yu Yoshida, Yuiga Wada, Shumpei Hatanaka, Komei Sugiura</i>  |      |
| InsMOS: Instance-Aware Moving Object Segmentation in LiDAR Data .....  | 5836 |
| <i>Neng Wang, Chenghao Shi, Ruibin Guo, Huimin Lu, Zhiqiang Zheng, Xieyuanli Chen</i>  |      |

|   |      |
|---|------|
| EIC-OIS: Ellipsoidal Clustering for Open-World Instance Segmentation on LiDAR Data .....  | 5844 |
| <i>Wenbang Deng, Kaihong Huang, Qinghua Yu, Huimin Lu, Zhiqiang Zheng, Xieyuanli Chen</i>   |      |
| Boosting Lidar 3D Object Detection with Point Cloud Semantic Segmentation .....   | 5852 |
| <i>Xuchong Zhang, Chong Min, Yijie Jia, Liming Chen, Jingmin Zhang, Hongbin Sun</i>   |      |
| Generalized Few-Shot Semantic Segmentation for LiDAR Point Clouds.....  | 5860 |
| <i>Pengze Wu, Jilin Mei, Xijun Zhao, Yu Hu</i>  |      |
| Baking in the Feature: Accelerating Volumetric Segmentation by Rendering Feature Maps.....  | 5867 |
| <i>Kenneth Blomqvist, Lionel Ott, Jen Jen Chung, Roland Siegwart</i>  |      |
| Optical Flow Boosts Unsupervised Localization and Segmentation.....   | 5873 |
| <i>Xinyu Zhang, Abdeslam Boularias</i>  |      |
| T-UDA: Temporal Unsupervised Domain Adaptation in Sequential Point Clouds .....   | 5881 |
| <i>Awet Haileslassie Gebrehiwot, David Hurých, Karel Zimmermann, Patrick Pérez, Tomáš Svoboda</i>                                   |      |
| Superpixel Transformers for Efficient Semantic Segmentation .....   | 5889 |
| <i>Alex Zhao Zhu, Jieru Mei, Siyuan Qiao, Hang Yan, Yukun Zhu, Liang-Chieh Chen, Henrik Kretzschmar</i>                             |      |
| Hierarchical Semi-Supervised Learning Framework for Surgical Gesture Segmentation and Recognition Based on Multi-Modality Data..... | 5897 |
| <i>Zhili Yuan, Jialin Lin, Dandan Zhang</i>   |      |
| Lidar Panoptic Segmentation and Tracking Without Bells and Whistles .....   | 5905 |
| <i>Abhinav Agarwalla, Xuhua Huang, Jason Ziglar, Francesco Ferroni, Laura Leal-Taixé, James Hays, Aljoša Ošep, Deva Ramanan</i>     |      |
| CompUDA: Compositional Unsupervised Domain Adaptation for Semantic Segmentation Under Adverse Conditions .....                      | 5913 |
| <i>Ziqiang Zhengl, Yingshu Chen, Binh-Son Hua, Sai-Kit Yeung</i>  |      |
| Transparent Object Tracking with Enhanced Fusion Module.....  | 5920 |
| <i>Kalyan Garigapati, Erik Blasch, Jie Wei, Haibin Ling</i>   |      |
| Self-Supervised Event-Based Monocular Depth Estimation Using Cross-Modal Consistency .....  | 5928 |
| <i>Junyu Zhu, Lina Liu, Bofeng Jiang, Feng Wen, Hongbo Zhang, Wanlong Li, Yong Liu</i>  |      |
| Sim-To-Real Vision-Depth Fusion CNNs for Robust Pose Estimation Aboard Autonomous Nano-Quadcopters.....                             | 5935 |
| <i>Luca Crupi, Elia Cereda, Alessandro Giusti, Daniele Palossi</i>  |      |
| SSC-RS: Elevate LiDAR Semantic Scene Completion with Representation Separation and BEV Fusion .....                                 | 5942 |
| <i>Jianbiao Mei, Yu Yang, Mengmeng Wang, Tianxin Huang, Xuemeng Yang, Yong Liu</i>  |      |
| PANet: LiDAR Panoptic Segmentation with Sparse Instance Proposal and Aggregation.....   | 5950 |
| <i>Jianbiao Mei, Yu Yang, Mengmeng Wang, Xiaojun Hou, Laijian Li, Yong Liu</i>  |      |
| Online Self-Supervised Thermal Water Segmentation for Aerial Vehicles.....  | 5958 |
| <i>Connor Lee, Jonathan Gustafsson Frennert, Lu Gan, Matthew Anderson, Soon-Jo Chung</i>  |      |
| Lightweight, Uncertainty-Aware Conformalized Visual Odometry .....  | 5966 |
| <i>Alex C. Stutts, Danilo Erricolo, Theja Tulabandhula, Amit Ranjan Trivedi</i>   |      |

|   |      |
|---|------|
| LiDAR Meta Depth Completion .....   | 5974 |
| <i>Wolfgang Boettcher, Lukas Hoyer, Ozan Unal, Ke Li, Dengxin Dai</i>   |      |
| Primitive Skill-Based Robot Learning from Human Evaluative Feedback .....   | 5981 |
| <i>Ayano Hiranaka, Minjune Hwang, Sharon Lee, Chen Wang, Li Fei-Fei, Jiajun Wu, Ruohan Zhang</i>  |      |
| Autocomplete of 3D Motions for UAV Teleoperation.....   | 5989 |
| <i>Batool Ibrahim, Mohammad Haj Hussein, Imad H. Elhajj, Daniel Asmar</i>   |      |
| Exploiting Spatio-Temporal Human-Object Relations Using Graph Neural Networks for Human Action Recognition and 3D Motion Forecasting.....         | 5996 |
| <i>Dimitrios Lagamitzis, Fabian Schmidt, Jan Seyler, Thao Dang, Steffen Schober</i>   |      |
| Improving Human-Robot Interaction Effectiveness in Human-Robot Collaborative Object Transportation Using Force Prediction.....                    | 6003 |
| <i>J. E. Dominguez-Vidal, Alberto Sanfeliu</i>  |      |
| Leveraging Saliency-Aware Gaze Heatmaps for Multiperspective Teaching of Unknown Objects.....   | 6010 |
| <i>Daniel Weber, Valentin Bolz, Andreas Zell, Enkelejda Kasneci</i>   |      |
| Language Guided Temporally Adaptive Perception for Efficient Natural Language Grounding in Cluttered Dynamic Worlds .....                         | 6018 |
| <i>Siddharth Patki, Jacob Arkin, Nikola Raicevic, Thomas M. Howard</i>  |      |
| T-Top, an Open Source Tabletop Robot with Advanced Onboard Audio, Vision and Deep Learning Capabilities .....                                     | 6026 |
| <i>Marc-Antoine Maheux, Adina M. Panchea, Philippe Warren, Dominic Létourneau, François Michaud</i>   |      |
| Learning Human Motion Intention for pHRI Assistive Control.....   | 6034 |
| <i>Paolo Franceschi, Fabio Bertini, Francesco Braghin, Loris Roveda, Nicola Pedrocchi, Manuel Beschi</i>  |      |
| VARIQuery: VAE Segment-Based Active Learning for Query Selection in Preference-Based Reinforcement Learning.....                                  | 6042 |
| <i>Daniel Marta, Simon Holk, Christian Pek, Jana Tumova, Iolanda Leite</i>  |      |
| Interactive Spatiotemporal Token Attention Network for Skeleton-Based General Interactive Action Recognition .....                                | 6050 |
| <i>Yuhang Wen, Zixuan Tang, Yunsheng Pang, Beichen Ding, Mengyuan Liu</i>   |      |
| Learning Joint Policies for Human-Robot Dialog and Co-Navigation.....   | 6057 |
| <i>Yohei Hayamizu, Zhou Yu, Shiqi Zhang</i>   |      |
| Initial Task Allocation for Multi-Human Multi-Robot Teams with Attention-Based Deep Reinforcement Learning.....                                   | 6063 |
| <i>Ruiqi Wang, Dezhong Zhao, Byung-Cheol Min</i>  |      |
| Human-Robot Collaboration for Unknown Flexible Surface Exploration and Treatment Based on Mesh Iterative Learning Control .....                   | 6071 |
| <i>Jingkang Xia, Kithmi N. D. Widanage, Ruiqing Zhang, Rizwana Parween, Hareesh Godaba, Nicolas Herzig, Romeo Glovnea, Deqing Huang, Yanan Li</i> |      |
| Projecting Robot Intentions Through Visual Cues: Static Vs. Dynamic Signaling .....   | 6079 |
| <i>Shubham Sonawani, Yifan Zhou, Heni Ben Amor</i>  |      |

|   |      |
|---|------|
| Robottheory Fitness: GoBot's Engagement Edge for Spurring Physical Activity in Young Children .....   | 6087 |
| <i>Rafael Morales Mayoral, Ameer Helmi, Shel-Twon Warren, Samuel W. Logan, Naomi T. Fitter</i>  |      |
| Implicit Projection: Improving Team Situation Awareness for Tacit Human-Robot Interaction Via<br>Virtual Shadows .....  | 6093 |
| <i>Andrew Boateng, Wenlong Zhang, Yu Zhang</i>  |      |
| User Interactions and Negative Examples to Improve the Learning of Semantic Rules in a<br>Cognitive Exercise Scenario.....  | 6101 |
| <i>Alejandro Suárez-Hernández, Antonio Andriella, Carme Torras, Guillem Alenyà</i>  |      |
| Large Language Models as Zero-Shot Human Models for Human-Robot Interaction.....  | 6109 |
| <i>Bowen Zhang, Harold Soh</i>  |      |
| MPC-Based Human-Accompanying Control Strategy for Improving the Motion Coordination<br>Between the Target Person and the Robot .....  | 6117 |
| <i>Jianwei Peng, Zhelin Liao, Hanchen Yao, Zefan Su, Yadan Zeng, Houde Dai</i>  |      |
| Improved Inference of Human Intent by Combining Plan Recognition and Language Feedback .....  | 6124 |
| <i>Ifrah Idrees, Tian Yun, Naveen Sharma, Yunxin Deng, Nakul Gopalan, George Konidaris,<br/>Stefanie Tellex</i>   |      |
| Online Human Capability Estimation Through Reinforcement Learning and Interaction .....   | 6132 |
| <i>Chengke Sun, Anthony G. Cohn, Matteo Leonetti</i>  |      |
| Cognitive Approach to Hierarchical Task Selection for Human-Robot Interaction in Dynamic<br>Environments.....   | 6140 |
| <i>Syed Tanweer Shah Bukhari, Bashira Akter Anima, David Feil-Seifer, Wajahat Mahmood Qazi</i>  |      |
| Reward Shaping for Building Trustworthy Robots in Sequential Human-Robot Interaction.....   | 6147 |
| <i>Yaohui Guo, X. Jessie Yang, Cong Shi</i>   |      |
| Latent Emission-Augmented Perspective-Taking (LEAPT) for Human-Robot Interaction .....  | 6154 |
| <i>Kaiqi Chen, Jing Yu Lim, Kingsley Kuan, Harold Soh</i>   |      |
| An Attentional Recurrent Neural Network for Occlusion-Aware Proactive Anomaly Detection in<br>Field Robot Navigation .....  | 6162 |
| <i>Andre Schreiber, Tianchen Ji, D. Livingston McPherson, Katherine Driggs-Campbell</i>   |      |
| Collaborative Trolley Transportation System with Autonomous Nonholonomic Robots.....  | 6170 |
| <i>Bingyi Xia, Hao Luan, Ziqi Zhao, Xuheng Gao, Peijia Xie, Anxing Xiao, Jiankun Wang, Max<br/>Q.-H. Meng</i>   |      |
| Deconfounded Opponent Intention Inference for Football Multi-Player Policy Learning .....   | 6178 |
| <i>Shijie Wang, Yi Pan, Zhiqiang Pu, Boyin Liu, Jianqiang Yi</i>  |      |
| Stroke-Based Rendering and Planning for Robotic Performance of Artistic Drawing.....  | 6186 |
| <i>Ivaylo Ilkin, Daeun Song, Young J. Kim</i>   |      |
| Heterogeneous Robot-Assisted Services in Isolation Wards: A System Development and Usability<br>Study.....  | 6193 |
| <i>Youngsun Kwon, Soyeon Shin, Kyonmo Yang, Seongah Park, Soomin Shin, Hwawoo Jeon,<br/>Kijung Kim, Guhnoo Yun, Sangyong Park, Jeewon Byun, Sang Hoon Kang, Kyoung-Ho Song,<br/>Doik Kim, Dong Hwan Kim, Kapho Seo, Sonya S. Kwak, Yoonseob Lim</i> |      |

|  |      |
|--|------|
| Irregular Change Detection in Sparse Bi-Temporal Point Clouds Using Learned Place Recognition Descriptors and Point-To-Voxel Comparison .....              | 6201 |
| <i>Nikolaos Stathoulopoulos, Anton Koval, George Nikolakopoulos</i>  |      |
| Magnetically Controlled Cell Robots with Immune-Enhancing Potential .....  | 6208 |
| <i>Hongyan Sun, Yuguo Dai, Jiaying Zhang, Junjie Xu, Lina Jia, Chutian Wang, Luyao Wang, Chan Li, Xue Bai, Bo Chen, Lin Feng</i>                           |      |
| Tightly-Coupled Visual-DVL Fusion for Accurate Localization of Underwater Robots.....  | 6214 |
| <i>Yupei Huang, Peng Li, Shuaizheng Yan, Yaming Ou, Zhengxing Wu, Min Tan, Junzhi Yu</i>   |      |
| Fully Proprioceptive Slip-Velocity-Aware State Estimation for Mobile Robots Via Invariant Kalman Filtering and Disturbance Observer .....                  | 6220 |
| <i>Xihang Yu, Sangli Teng, Theodor Chakhachiro, Wenzhe Tong, Tingjun Li, Tzu-Yuan Lin, Sarah Koehler, Manuel Ahumada, Jeffrey M. Walls, Maani Ghaffari</i> |      |
| Predicting Energy Consumption and Traversal Time of Ground Robots for Outdoor Navigation on Multiple Types of Terrain .....                                | 6228 |
| <i>Matthias Eder, Gerald Steinbauer-Wagner</i>   |      |
| Informative Path Planning for Scalar Dynamic Reconstruction Using Coregionalized Gaussian Processes and a Spatiotemporal Kernel.....                       | 6236 |
| <i>Lorenzo Booth, Stefano Carpin</i>   |      |
| Probabilistic Guarantees for Nonlinear Safety-Critical Optimal Control .....   | 6244 |
| <i>Prithvi Akella, Wyatt Ubellacker, Aaron D. Ames</i>   |      |
| Non-Gaussian Uncertainty Minimization Based Control of Stochastic Nonlinear Robotic Systems.....   | 6251 |
| <i>Weiqiao Han, Ashkan Jasour, Brian Williams</i>  |      |
| Learning Compliant Stiffness by Impedance Control-Aware Task Segmentation and Multi-Objective Bayesian Optimization with Priors .....                      | 6259 |
| <i>Masashi Okada, Mayumi Komatsu, Ryo Okumura, Tadahiro Taniguchi</i>  |      |
| Efficient Exploration Using Extra Safety Budget in Constrained Policy Optimization .....   | 6267 |
| <i>Haotian Xu, Shengjie Wang, Zhaolei Wang, Yunzhe Zhang, Qing Zhuo, Yang Gao, Tao Zhang</i>   |      |
| Quadratic Dynamic Matrix Control for Fast Cloth Manipulation .....   | 6274 |
| <i>Edoardo Caldarelli, Adrià Colomé, Carlos Ocampo-Martínez, Carme Torras</i>  |      |
| A Gaussian Process Model for Opponent Prediction in Autonomous Racing .....  | 6282 |
| <i>Edward L. Zhu, Finn Lukas Busch, Jake Johnson, Francesco Borrelli</i>   |      |
| Optimal Energy Tank Initialization for Minimum Sensitivity to Model Uncertainties .....  | 6288 |
| <i>Andrea Pupa, Paolo Robuffo Giordano, Cristian Secchi</i>  |      |
| A Data-Driven Approach to Synthesizing Dynamics-Aware Trajectories for Underactuated Robotic Systems.....  | 6296 |
| <i>Anusha Srikanthan, Fengjun Yang, Igor Spasojevic, Dinesh Thakur, Vijay Kumar, Nikolai Matni</i>   |      |
| Time-Optimal Control Via Heaviside Step-Function Approximation .....   | 6304 |
| <i>Kai Pfeiffer, Quang-Cuong Pham</i>  |      |
| Bi-Component Silicone 3D Printing with Dynamic Mix Ratio Modification for Soft Robotic Actuators .....   | 6312 |
| <i>Brice Parilusyan, Alina-Elena Nicolae, Thomas Batigne, Clément Duhart, Marcos Serrano</i>   |      |

|  |      |
|--|------|
| Two-Stage Train Components Defect Detection Based on Prior Knowledge .....   | 6318 |
| <i>Gang Peng, Zhiyong Li, Shaowei Wan, Zhang Deng</i>  |      |
| Complete Coverage Path Planning for Omnidirectional Expand and Collapse Robot Panthera .....   | 6324 |
| <i>Lim Yi, Ash Wan Yaw Sang, Abdullah Aamir Hayat, Qinrui Tang, Anh Vu Le, Mohan Rajesh Elara</i>  |      |
| Monte-Carlo Tree Search with Prioritized Node Expansion for Multi-Goal Task Planning .....   | 6330 |
| <i>Kai Pfeiffer, Leonardo Edgar, Quang-Cuong Pham</i>  |      |
| Efficient and Feasible Robotic Assembly Sequence Planning Via Graph Representation Learning .....  | 6337 |
| <i>Matan Atad, Jianxiang Feng, Ismael Rodríguez, Maximilian Durner, Rudolph Triebel</i>  |      |
| Statistical Characterization of Position-Dependent Behavior Using Frequency-Aware B-Spline.....  | 6345 |
| <i>Yazan M. Al-Rawashdeh, Marcel Heertjes, Mohammad Al Janaideh</i>  |      |
| Flexible Gear Assembly with Visual Servoing and Force Feedback.....  | 6351 |
| <i>Junjie Ming, Daniel Bargmann, Hongpeng Cao, Marco Caccamo</i>   |      |
| Robotic Powder Grinding with Audio-Visual Feedback for Laboratory Automation in Materials Science .....                                    | 6358 |
| <i>Yusaku Nakajima, Masashi Hamaya, Kazutoshi Tanaka, Takafumi Hawai, Felix Von Drigalski, Yasuo Takeichi, Yoshitaka Ushiku, Kanta Ono</i> |      |
| Deep Learning-Based Leaf Detection for Robotic Physical Sampling with P-AgBot .....  | 6366 |
| <i>Aarya Deb, Kitae Kim, David J. Cappelleri</i>   |      |
| In-Situ Measurement of Extrusion Width for Fused Filament Fabrication Process Using Vision and Machine Learning Models.....                | 6373 |
| <i>Arya Shabani, Uriel Martinez-Hernandez</i>  |      |
| Motion Orchestration in Dual-Stage Wafer Scanners.....   | 6379 |
| <i>Yazan M. Al-Rawashdeh, Marcel Heertjes, Mohammad Al Janaideh</i>  |      |
| Towards Packaging Unit Detection for Automated Palletizing Tasks .....   | 6385 |
| <i>Markus Völk, Kilian Kleeberger, Werner Kraus, Richard Bormann</i>   |      |
| Robotic Barrier Construction Through Weaved, Inflatable Tubes.....   | 6393 |
| <i>Heather Jin Hee Kim, Haron Abdel-Raziq, Xinyu Liu, Alexandra Young Siskovic, Shreyas Patil, Kirstin H. Petersen, Hsin-Liu Kao</i>       |      |
| Bistable Tensegrity Robot with Jumping Repeatability Based on Rigid Plate-Shaped Compressors.....  | 6399 |
| <i>Kento Shimura, Noriyasu Iwamoto, Takuya Umedachi</i>  |      |
| Accessible Soft Robotics Education with Re-Configurable Balloon Robots .....   | 6406 |
| <i>Yi-Shiun Wu, Kieran Gilday, Josie Hughes</i>  |      |
| A Fabrication and Simulation Recipe for Untethering Soft-Rigid Robots with Cable-Driven Stiffness Modulation .....                         | 6412 |
| <i>James M. Bern, Zach J. Patterson, Leonardo Zamora Yañez, Kristoff K. Misquitta, Daniela Rus</i>   |      |
| Integrated Design of a Robotic Bio-Inspired Trunk .....  | 6418 |
| <i>Tanguy Chevillon, Steeve Mbakop, Gilles Tagne, Rochdi Merzouki</i>  |      |
| A New Design of Multilayered String Jamming Mechanism with Three-Degree-Of-Freedom .....   | 6424 |
| <i>Ryohei Michikawa, Kenjiro Tadakuma, Fumitoshi Matsuno</i>   |      |

|  |      |
|--|------|
| Protective Skin Mechanism with an Exhaustive Arrangement of Tiny Rigid Bodies for Soft Robots:<br>Evaluation of Puncture Resistance, Elasticity, and Descaling Resistance of the Scale Mechanism ..... | 6431 |
| <i>Kenjiro Tadakuma, Masahiro Watanabe, Satoshi Tadokoro</i>   |      |
| Printable Bistable Structures for Programmable Frictional Skins of Soft-Bodied Robots .....  | 6439 |
| <i>Tung D. Ta, Yoshihiro Kawahara</i>  |      |
| MCLARI: A Shape-Morphing Insect-Scale Robot Capable of Omnidirectional Terrain-Adaptive<br>Locomotion in Laterally Confined Spaces .....   | 6446 |
| <i>Heiko Kabutz, Alexander Hedrick, William P. McDonnell, Kaushik Jayaram</i>  |      |
| FABRIKv: A Fast, Iterative Inverse Kinematics Solver for Surgical Continuum Robot with Variable<br>Curvature Model.....  | 6452 |
| <i>Fuhao Wang, Wang Ye, Xiaoyang Kang, Hongbo Wang, Jingjing Luo, Li Chen, Xiuhong Tang</i>  |      |
| Design and Synchronous Control of a Magnetically-Actuated and Ultrasound-Guided Multi-Arm<br>Robotic System.....   | 6460 |
| <i>Zhengyang Li, Qingsong Xu</i>   |      |
| A Shared-Control Dexterous Robotic System for Assisting Transoral Mandibular Fracture<br>Reduction: Development and Cadaver Study .....  | 6466 |
| <i>Yan Wang, Hao Zheng, Yu-Chung Lee, Catherine P. L. Chan, Jason Ying-Kuen Chan, Russell<br/>H. Taylor, Kwok Wai Samuel Au</i>  |      |
| Model-Based Bending Control of Magnetically-Actuated Robotic Endoscopes for Automatic<br>Retroflexion in Confined Spaces .....   | 6474 |
| <i>Yichong Sun, Yehui Li, Jixiu Li, Wing Yin Ng, Yitian Xian, Yisen Huang, Philip Wai Yan Chiu,<br/>Zheng Li</i>   |      |
| 3D Laser-And-Tissue Agnostic Data-Driven Method for Robotic Laser Surgical Planning .....  | 6481 |
| <i>Guangshen Ma, Ravi Prakash, Brian Mann, Weston Ross, Patrick Codd</i>   |      |
| Insertion, Retrieval and Performance Study of Miniature Magnetic Rotating Swimmers for the<br>Treatment of Thrombi.....  | 6489 |
| <i>Yitong Lu, Jocelyn Ramos, Mohamad G. Ghosn, Dipan J. Shah, Aaron T. Becker, Julien<br/>Leclerc</i>  |      |
| Hybrid Tendon and Ball Chain Continuum Robots for Enhanced Dexterity in Medical Interventions.....   | 6496 |
| <i>Giovanni Pittiglio, Margherita Mencattelli, Abdulhamit Donder, Yash Chitalia, Pierre E.<br/>Dupont</i>  |      |
| Semi-Autonomous Assistance for Telesurgery Under Communication Loss.....   | 6502 |
| <i>Hisashi Ishida, Adnan Munawar, Russell H. Taylor, Peter Kazanzides</i>  |      |
| Improving Surgical Situational Awareness with Signed Distance Field: A Pilot Study in Virtual<br>Reality .....   | 6509 |
| <i>Hisashi Ishida, Juan Antonio Barragan, Adnan Munawar, Zhaoshuo Li, Andy Ding, Peter<br/>Kazanzides, Danielle Trakimas, Francis X. Creighton, Russell H. Taylor</i>                                  |      |
| Development and Evaluation of a Single-Arm Robotic System for Autonomous Suturing .....  | 6515 |
| <i>Jiawei Liu, Michael Kam, Justin D. Opfermann, Zheyuan Zhang, Michael H. Hsieh, Jin U.<br/>Kang, Axel Krieger</i>  |      |
| End-To-End Learning of Deep Visuomotor Policy for Needle Picking.....  | 6522 |
| <i>Hongbin Lin, Bin Li, Xiangyu Chu, Qi Dou, Yunhui Liu, Kwok Wai Samuel Au</i>  |      |

|   |      |
|---|------|
| Value-Informed Skill Chaining for Policy Learning of Long-Horizon Tasks with Surgical Robot.....  | 6530 |
| <i>Tao Huang, Kai Chen, Wang Wei, Jianan Li, Yonghao Long, Qi Dou</i>   |      |
| Design of a Jumping Control Framework with Heuristic Landing for Bipedal Robots .....   | 6537 |
| <i>Jingwen Zhang, Junjie Shen, Yeting Liu, Dennis Hong</i>  |      |
| Proprioceptive External Torque Learning for Floating Base Robot and Its Applications to Humanoid Locomotion.....  | 6545 |
| <i>Daegyu Lim, Myeong-Ju Kim, Junhyeok Cha, Donghyeon Kim, Jaeheung Park</i>  |      |
| Time to Danger, an Alternative to Passive Safety for the Locomotion of a Biped Robot in a Crowd.....  | 6553 |
| <i>Matteo Ciocca, Pierre-Brice Wieber, Thierry Fraichard</i>  |      |
| ZMP Feedback Balance Control of Humanoid in Response to Ground Acceleration .....   | 6560 |
| <i>Masanori Konishi, Kunio Kojima, Kei Okada, Masayuki Inaba, Koji Kawasaki</i>   |      |
| Manipulation of Center of Pressure for Bipedal Locomotion by Passive Twisting of Viscoelastic Trunk Joint and Asymmetrical Arm Swinging .....                                   | 6567 |
| <i>Takashi Takuma, Ibuki Hashimoto, Ryo Andachi, Yasuhiro Sugimoto, Shinya Aoi</i>  |      |
| An Implantable Variable Length Actuator for Modulating in Vivo Musculo-Tendon Force in a Bipedal Animal Model .....   | 6573 |
| <i>Sean Thomas, Ravin Joshi, Bo Cheng, Huanyu Cheng, Michael C. Aynardi, Gregory S. Sawicki, Jonas Rubenson</i>   |      |
| Whole-Body Torque Control Without Joint Position Control Using Vibration-Suppressed Friction Compensation for Bipedal Locomotion of Gear-Driven Torque Sensorless Humanoid..... | 6579 |
| <i>Takuma Hiraoka, Shimpei Sato, Naoki Hiraoka, Annan Tang, Kunio Kojima, Kei Okada, Masayuki Inaba, Koji Kawasaki</i>  |      |
| An Approach for Generating Families of Energetically Optimal Gaits from Passive Dynamic Walking Gaits .....   | 6586 |
| <i>Nelson Rosa, Bassel Katamish, Maximilian Raff, C. David Remy</i>   |      |
| Stair Climbing Using the Angular Momentum Linear Inverted Pendulum Model and Model Predictive Control.....  | 6593 |
| <i>Oluwami Dosunmu-Ogunbi, Aayushi Shrivastava, Grant Gibson, Jessy W Grizzle</i>   |      |
| Real-Time Dynamic Bipedal Avoidance .....   | 6601 |
| <i>Tianze Wang, Jason White, Christian Hubicki</i>  |      |
| Data-Driven Adaptation for Robust Bipedal Locomotion with Step-To-Step Dynamics .....   | 6609 |
| <i>Min Dai, Xiaobin Xiong, Jaemin Lee, Aaron D. Ames</i>  |      |
| Template Model Inspired Task Space Learning for Robust Bipedal Locomotion .....   | 6617 |
| <i>Guillermo A. Castillo, Bowen Weng, Shunpeng Yang, Wei Zhang, Ayonga Hereid</i>   |      |
| Overtaking Moving Obstacles with Digit: Path Following for Bipedal Robots Via Model Predictive Contouring Control.....  | 6625 |
| <i>Kunal S. Narkhede, Dhruv A. Thanki, Abhijeet M. Kulkarni, Ioannis Poulopoulos</i>  |      |
| STL: Surprisingly Tricky Logic (for System Validation) .....  | 6632 |
| <i>Ho Chit Siu, Kevin Leahy, Makai Mann</i>   |      |
| Real-Time RRT* with Signal Temporal Logic Preferences.....  | 6640 |
| <i>Alexis Linard, Ilaria Torre, Ermanno Bartoli, Alex Sleat, Iolanda Leite, Jana Tumova</i>   |      |

|   |      |
|---|------|
| Sensor Selection for Fine-Grained Behavior Verification that Respects Privacy .....   | 6647 |
| <i>Rishi Phatak, Dylan A. Shell</i>   |      |
| An Interactive System for Multiple-Task Linear Temporal Logic Path Planning .....   | 6655 |
| <i>Yizhou Chen, Xinyi Wang, Zixuan Guo, Ruoyu Wang, Xunkuai Zhou, Guidong Yang, Shupeng Lai, Ben M. Chen</i>                      |      |
| Temporal Logic-Based Intent Monitoring for Mobile Robots.....   | 6662 |
| <i>Hansol Yoon, Sriram Sankaranarayanan</i>   |      |
| Evaluation Metrics of Object Detection for Quantitative System-Level Analysis of Safety-Critical Autonomous Systems .....         | 6670 |
| <i>Apurva Badithela, Tichakorn Wongpiromsarn, Richard M. Murray</i>   |      |
| Energy-Aware Planning of Heterogeneous Multi-Agent Systems for Serving Cooperative Tasks with Temporal Logic Specifications ..... | 6678 |
| <i>Ali Teyfik Buyukkocak, Derya Aksaray, Yasin Yazicioglu</i>   |      |
| Efficient Symbolic Approaches for Quantitative Reactive Synthesis with Finite Tasks.....  | 6685 |
| <i>Karan Muvala, Morteza Lahijanian</i>   |      |
| Minimal Path Violation Problem with Application to Fault Tolerant Motion Planning of Manipulators.....                            | 6692 |
| <i>Aakriti Upadhyay, Mukulika Ghosh, Chinwe Ekenna</i>  |      |
| Reinforcement Learning Under Probabilistic Spatio-Temporal Constraints with Time Windows .....                                    | 6699 |
| <i>Xiaoshan Lin, Abbasali Koochakzadeh, Yasin Yazicioglu, Derya Aksaray</i>   |      |
| A Unified Trajectory Generation Algorithm for Dynamic Dexterous Manipulation .....  | 6706 |
| <i>Cheng Zhou, Wentao Gao, Weifeng Lu, Yanbo Long, Sicheng Yang, Longfei Zhao, Bidan Huang, Yu Zheng</i>                          |      |
| Hybrid Learning- And Model-Based Planning and Control of In-Hand Manipulation .....   | 6714 |
| <i>Rana Soltani Zarrin, Rianna Jitosho, Katsu Yamane</i>  |      |
| Vision-Based In-Hand Manipulation of Variously Shaped Objects Via Contact Point Prediction .....                                  | 6721 |
| <i>Yuzuka Isobe, Sunhwi Kang, Takeshi Shimamoto, Yoshinari Matsuyama, Sarthak Pathak, Kazunori Umeda</i>                          |      |
| Object Manipulation Through Contact Configuration Regulation: Multiple and Intermittent Contacts .....                            | 6729 |
| <i>Orion Taylor, Neel Doshi, Alberto Rodriguez</i>  |      |
| Non-Parametric Self-Identification and Model Predictive Control of Dexterous In-Hand Manipulation .....                           | 6737 |
| <i>Podshara Chanrungmaneekul, Kejia Ren, Joshua T. Grace, Aaron M. Dollar, Kaiyu Hang</i>   |      |
| In-Hand Cube Reconfiguration: Simplified.....   | 6745 |
| <i>Sumit Patidar, Adrian Sieler, Oliver Brock</i>   |      |
| Dexterous Soft Hands Linearize Feedback-Control for In-Hand Manipulation.....   | 6751 |
| <i>Adrian Sieler, Oliver Brock</i>  |      |
| In-Hand Manipulation of Unknown Objects with Tactile Sensing for Insertion .....  | 6759 |
| <i>Chaoyi Pan, Marion Lepert, Shenli Yuan, Rika Antonova, Jeannette Bohg</i>  |      |

|   |      |
|---|------|
| Bi-Manual Robot Shoe Lacing .....   | 6766 |
| <i>Haining Luo, Yiannis Demiris</i>   |      |
| Hand Design Approach for Planar Fully Actuated Manipulators .....   | 6772 |
| <i>Keegan Nave, Kyle Dufrene, Nigel Swenson, Ravi Balasubramanian, Cindy Grimm</i>  |      |
| Dynamic Finger Gaits Via Pivoting and Adapting Contact Forces.....  | 6778 |
| <i>Yuechuan Xue, Ling Tang, Yan-Bin Jia</i>   |      |
| Rotating Objects Via in-Hand Pivoting Using Vision, Force and Touch.....  | 6786 |
| <i>Shiyu Xu, Tianyuan Liu, Michael Wong, Dana Kulic, Akansel Cosgun</i>   |      |
| CoFlyers: A Universal Platform for Collective Flying of Swarm Drones .....  | 6794 |
| <i>Jialei Huang, Fakui Wang, Tianjiang Hu</i>   |      |
| Collective Decision-Making and Change Detection with Bayesian Robots in Dynamic Environments.....                                       | 6800 |
| <i>Kai Pfister, Heiko Hamann</i>  |      |
| Autonomous Swarm Robot Coordination Via Mean-Field Control Embedding Multi-Agent Reinforcement Learning.....                            | 6806 |
| <i>Huaze Tang, Hengxi Zhang, Zhenpeng Shi, Xinlei Chen, Wenbo Ding, Xiao-Ping Zhang</i>   |      |
| Multi-Instance Task in Swarm Robotics: Sorting Groups of Robots Or Objects into Clusters with Minimalist Controllers.....               | 6813 |
| <i>Adilson Krischanski, Yuri K. Lopes, Andre B. Leal, Ricardo F. Martins, Roberto S. U. Rosso</i>                                       |      |
| Bio-Inspired 3D Flocking Algorithm with Minimal Information Transfer for Drones Swarms.....   | 6819 |
| <i>Matthieu Verdoucq, Clément Sire, Ramón Escobedo, Guy Theraulaz, Gautier Hattenberger</i>   |      |
| A Generic Framework for Byzantine-Tolerant Consensus Achievement in Robot Swarms.....   | 6825 |
| <i>Hanqing Zhao, Alexandre Pacheco, Volker Strobel, Andreagiovanni Reina, Xue Liu, Gregory Dudek, Marco Dorigo</i>                      |      |
| Sharing the Control of Robot Swarms Among Multiple Human Operators: A User Study .....  | 6833 |
| <i>Genki Miyauchi, Yuri K. Lopes, Roderich Groß</i>   |      |
| Decentralized Multi-Agent Reinforcement Learning with Global State Prediction .....   | 6840 |
| <i>Joshua Bloom, Pranjal Paliwal, Apratim Mukherjee, Carlo Pinciroli</i>  |      |
| Minimalistic Collective Perception with Imperfect Sensors .....   | 6848 |
| <i>Khai Yi Chin, Yara Khaluf, Carlo Pinciroli</i>   |      |
| Onboard Predictive Flocking of Quadcopter Swarm in the Presence of Obstacles and Faulty Robots .....                                    | 6855 |
| <i>Giray Önür, Mehmet Sahin, Erhan Ege Keyvan, Ali Emre Turgut, Erol Sahin</i>  |      |
| OA-Bug: An Olfactory-Auditory Augmented Bug Algorithm for Swarm Robots in a Denied Environment .....                                    | 6861 |
| <i>Siqi Tan, Xiaoya Zhang, Jingyao Li, Ruitao Jing, Mufan Zhao, Yang Liu, Quan Quan</i>   |      |
| Agent Prioritization and Virtual Drag Minimization in Dynamical System Modulation for Obstacle Avoidance of Decentralized Swarms.....   | 6868 |
| <i>Louis-Nicolas Douce, Alessandro Menichelli, Lukas Huber, Anastasia Bolotnikova, Diego Paez-Granados, Auke Ijspeert, Aude Billard</i> |      |
| How the Fingerprint Effect Applies to Digitized Fingerprint-Like Structures .....   | 6875 |
| <i>Robert Kovenburg, Chase George, Richard Gale, Burak Aksak</i>  |      |

|   |      |
|---|------|
| A Two-Dimensional Reticular Core Optical Waveguide Sensor for Tactile and Positioning Sensing.....                                    | 6883 |
| <i>Zeyu Liu, Zhengwei Li, Long Cheng</i>  |      |
| Sliding Touch-Based Exploration for Modeling Unknown Object Shape with Multi-Fingered Hands .....                                     | 6889 |
| <i>Yiting Chen, Ahmet Ercan Tekden, Marc Peter Deisenroth, Yasemin Bekiroglu</i>  |      |
| Re-Evaluating Parallel Finger-Tip Tactile Sensing for Inferring Object Adjectives: An Empirical Study.....                            | 6897 |
| <i>Fangyi Zhang, Peter Corke</i>  |      |
| Content Estimation Through Tactile Interactions with Deformable Containers.....   | 6904 |
| <i>Yu-En Liu, Chun-Yu Chai, Yi-Ting Chen, Shiao-Li Tsao</i>   |      |
| Placing by Touching: An Empirical Study on the Importance of Tactile Sensing for Precise Object Placing.....                          | 6910 |
| <i>Luca Lach, Niklas Funk, Robert Haschke, Séverin Lemaignan, Helge Joachim Ritter, Jan Peters, Georgia Chalvatzaki</i>               |      |
| Incipient Slip Detection with a Biomimetic Skin Morphology .....  | 6918 |
| <i>David Córdova Bulens, Nathan F. Lepora, Stephen J. Redmond, Benjamin Ward-Cherrier</i>   |      |
| GelSight Svelte: A Human Finger-Shaped Single-Camera Tactile Robot Finger with Large Sensing Coverage and Proprioceptive Sensing..... | 6925 |
| <i>Jialiang Zhao, Edward H. Adelson</i>   |      |
| Estimating Properties of Solid Particles Inside Container Using Touch Sensing.....  | 6931 |
| <i>Xiaofeng Guo, Hung-Jui Huang, Wenzhen Yuan</i>   |      |
| Acquisition and Prediction of High-Density Tactile Field Data for Rigid and Flexible Objects.....                                     | 6939 |
| <i>Hongxiang Xue, Pengkun Liu, Zhaoxun Ju, Fuchun Sun</i>   |      |
| Calibration-Free BEV Representation for Infrastructure Perception.....  | 6947 |
| <i>Siqi Fan, Zhe Wang, Xiaoliang Huo, Yan Wang, Jingjing Liu</i>  |      |
| UVSS: Unified Video Stabilization and Stitching for Surround View of Tractor-Trailer Vehicles .....                                   | 6953 |
| <i>Chunhui Zhu, Yi Yang, Hao Liang, Zhipeng Dong, Mengyin Fu</i>  |      |
| Falcon: A Wide-And-Deep Onboard Active Vision System .....  | 6960 |
| <i>Masahiro Hirano, Yuji Yamakawa</i>   |      |
| Driver Distraction Detection for Daytime and Nighttime with Unpaired Visible and Infrared Image Translation.....                      | 6966 |
| <i>Hong-Ze Shen, Huei-Yung Lin</i>  |      |
| Long-Short Term Policy for Visual Object Navigation .....   | 6974 |
| <i>Yubing Bai, Xinhang Song, Weijie Li, Sixian Zhang, Shuqiang Jiang</i>  |      |
| Lidar-Based Multiple Object Tracking with Occlusion Handling.....   | 6982 |
| <i>Ruo-Tsz Ho, Chieh-Chih Wang, Wen-Chieh Lin</i>   |      |
| Local and Global Information in Obstacle Detection on Railway Tracks .....  | 6988 |
| <i>Matthias Brucker, Andrei Cramariuc, Cornelius Von Einem, Roland Siegwart, Cesar Cadena</i>   |      |
| Hybrid Object Tracking with Events and Frames.....  | 6996 |
| <i>Zhichao Li, Nicola A. Piga, Franco Di Pietro, Massimiliano Iacono, Arren Glover, Lorenzo Natale, Chiara Bartolozzi</i>             |      |

|   |      |
|---|------|
| Semantic Segmentation Based on Multiple Granularity Learning .....  | 7004 |
| <i>Kebin Wu, Ameera Bawazir, Xiaofei Xiao, Sai Bhargav Avula, Ebtesam Almazrouei, Eloy Roura, Merouane Debbah</i>   |      |
| Enhanced Robot Navigation with Human Geometric Instruction .....  | 7010 |
| <i>Hideki Deguchi, Shun Taguchi, Kazuki Shibata, Satoshi Koide</i>  |      |
| InterTracker: Discovering and Tracking General Objects Interacting with Hands in the Wild .....   | 7018 |
| <i>Yanyan Shao, Qi Ye, Wenhan Luo, Kaihao Zhang, Jiming Chen</i>  |      |
| ECTLO: Effective Continuous-Time Odometry Using Range Image for LiDAR with Small FoV .....  | 7025 |
| <i>Xin Zheng, Jianke Zhu</i>  |      |
| TwistSLAM++: Fusing Multiple Modalities for Accurate Dynamic Semantic SLAM .....  | 7033 |
| <i>Mathieu Gonzalez, Eric Marchand, Amine Kacete, Jérôme Royan</i>  |      |
| SLAM and Shape Estimation for Soft Robots.....  | 7040 |
| <i>Mohammad Amin Karimi, David Cañones Bonham, Esteban Lopez, Ankit Srivastava, Matthew Spenko</i>  |      |
| Trajectory-Based SLAM for Indoor Mobile Robots with Limited Sensing Capabilities .....  | 7046 |
| <i>Yao Chen, Jeremias Rodriguez, Arman Karimian, Benjamin Pheil, Jose Franco, Renaud Moser, Read Sandstrom, Scott Lenser, Artem Gritsenko, Daniele Tamino, Felipe Andres Tenaglia Giunta, Guanlai Li, Philip Wasserman, Andrea Okerholm Huttlin</i> |      |
| Graph-Based Global Robot Localization Informing Situational Graphs.....   | 7054 |
| <i>Muhammad Shaheer, Jose Andres Millan-Romera, Hriday Bavle, Jose Luis Sanchez-Lopez, Javier Civera, Holger Voos</i>   |      |
| SSGM: Spatial Semantic Graph Matching for Loop Closure Detection in Indoor Environments .....   | 7062 |
| <i>Yujie Tang, Meiling Wang, Yinan Deng, Yi Yang, Yufeng Yue</i>  |      |
| Training-Free Attentive-Patch Selection for Visual Place Recognition.....   | 7068 |
| <i>Dongshuo Zhang, Meiqing Wu, Siew-Kei Lam</i>   |      |
| Exact Point Cloud Downsampling for Fast and Accurate Global Trajectory Optimization .....   | 7074 |
| <i>Kenji Koide, Shuji Oishi, Masashi Yokozuka, Atsuhiko Banno</i>   |      |
| GAPSLAM: Blending Gaussian Approximation and Particle Filters for Real-Time Non-Gaussian SLAM.....  | 7082 |
| <i>Qiangqiang Huang, John J. Leonard</i>  |      |
| Multi-Scale Point Octree Encoding Network for Point Cloud Based Place Recognition.....  | 7090 |
| <i>Zhilong Tang, Hanjing Ye, Hong Zhang</i>   |      |
| Analytical Jacobian Approximation for Direct Optimization of a Trajectory of Interpolated Poses on SE(3).....   | 7097 |
| <i>Kazii Botashev, Gonzalo Ferrer</i>   |      |
| On Cyber-Attacks Mitigation for Distributed Trajectory Generators .....   | 7104 |
| <i>Yazan M. Al-Rawashdeh, Mohammad Al Janaideh</i>  |      |
| CAMETA: Conflict-Aware Multi-Agent Estimated Time of Arrival Prediction for Mobile Robots.....  | 7110 |
| <i>Jonas Le Fevre Sejersen, Erdal Kayacan</i>   |      |
| Non-Linear Heterogeneous Bayesian Decentralized Data Fusion.....  | 7118 |
| <i>Ofer Dagan, Tycho L. Cinquini, Nisar R. Ahmed</i>  |      |

|  |      |
|--|------|
| BRNES: Enabling Security and Privacy-Aware Experience Sharing in Multiagent Robotic and Autonomous Systems .....           | 7125 |
| <i>Md Tamjid Hossain, Hung Manh La, Shahriar Badsha, Anton Netchaev</i>  |      |
| Beacon-Based Distributed Structure Formation in Multi-Agent Systems .....  | 7133 |
| <i>Tamzidul Mina, Wonse Jo, Shyam S. Kannan, Byung-Cheol Min</i>   |      |
| Decentralized Swarm Trajectory Generation for LiDAR-Based Aerial Tracking in Cluttered Environments.....                   | 7141 |
| <i>Longji Yin, Fangcheng Zhu, Yunfan Ren, Fanze Kong, Fu Zhang</i>   |      |
| Decentralized Planning for Car-Like Robotic Swarm in Cluttered Environments .....  | 7149 |
| <i>Changjia Ma, Zhichao Han, Tingrui Zhang, Jingping Wang, Long Xu, Chengyang Li, Chao Xu, Fei Gao</i>                     |      |
| SCRIMP: Scalable Communication for Reinforcement- And Imitation-Learning-Based Multi-Agent Pathfinding.....                | 7157 |
| <i>Yutong Wang, Bairan Xiang, Shinan Huang, Guillaume Sartoretti</i>   |      |
| Distributed Model Predictive Formation Control of Robots with Sampled Trajectory Sharing in Cluttered Environments.....    | 7165 |
| <i>Sami Satir, Yasin Furkan Aktas, Simay Atasoy, Mert Ankarali, Erol Sahin</i>   |      |
| Control Transformer: Robot Navigation in Unknown Environments Through PRM-Guided Return-Conditioned Sequence Modeling..... | 7172 |
| <i>Daniel Lawson, Ahmed H. Qureshi</i>   |      |
| InteractionNet: Joint Planning and Prediction for Autonomous Driving with Transformers .....                               | 7180 |
| <i>Jiawei Fu, Yanqing Shen, Zhiqiang Jian, Shitao Chen, Jingmin Xin, Nanning Zheng</i>                                     |      |
| ANEC: Adaptive Neural Ensemble Controller for Mitigating Latency Problems in Vision-Based Autonomous Driving.....          | 7188 |
| <i>Aws Khalil, Jaerock Kwon</i>  |      |
| A Dynamic Programming Algorithm for Grid-Based Formation Planning of Multiple Vehicles.....                                | 7195 |
| <i>Tsz-Chiu Au</i>   |      |
| LB-L2L-Calib 2.0: A Novel Online Extrinsic Calibration Method for Multiple Long Baseline 3D LiDARs Using Objects.....      | 7202 |
| <i>Jun Zhang, Qiao Yan, Mingxing Wen, Qiyang Lyu, Guohao Peng, Zhenyu Wu, Danwei Wang</i>                                  |      |
| A GM-PHD Filter with Estimation of Probability of Detection and Survival for Individual Targets .....                      | 7208 |
| <i>R. A. Thivanka Perera, Mingi Jeong, Alberto Quattrini Li, Paolo Stegagno</i>  |      |
| F2BEV: Bird's Eye View Generation from Surround-View Fisheye Camera Images for Automated Driving .....                     | 7215 |
| <i>Ekta U. Samani, Feng Tao, Harshavardhan R. Dasari, Sihao Ding, Ashis G. Banerjee</i>                                    |      |
| One-4-All: Neural Potential Fields for Embodied Navigation .....   | 7223 |
| <i>Sacha Morin, Miguel Saavedra-Ruiz, Liam Paull</i>   |      |
| Communication Resources Constrained Hierarchical Federated Learning for End-To-End Autonomous Driving.....                 | 7231 |
| <i>Wei-Bin Kou, Shuai Wang, Guangxu Zhu, Bin Luo, Yingxian Chen, Derrick Wing Kwan Ng, Yik-Chung Wu</i>                    |      |

|  |      |
|--|------|
| Poly-MOT: A Polyhedral Framework for 3D Multi-Object Tracking .....  | 7239 |
| <i>Xiaoyu Li, Tao Xie, Dedong Liu, Jinghan Gao, Kun Dai, Zhiqiang Jiang, Lijun Zhao, Ke Wang</i>   |      |
| SUIT: Learning Significance-Guided Information for 3D Temporal Detection .....   | 7247 |
| <i>Zheyuan Zhou, Jiachen Lu, Yihan Zeng, Hang Xu, Li Zhang</i>   |      |
| Enhancing Sample Efficiency and Uncertainty Compensation in Learning-Based Model Predictive Control for Aerial Robots .....                                    | 7255 |
| <i>Kong Yao Chee, Thales C. Silva, M. Ani Hsieh, George J. Pappas</i>  |      |
| Data-Driven Modeling and Experimental Validation of Autonomous Vehicles Using Koopman Operator.....  | 7262 |
| <i>Ajinkya Joglekar, Sarang Sutavani, Chinmay Samak, Tanmay Samak, Krishna Chaitanya Kosaraju, Jonathon Smereka, David Gorsich, Umesh Vaidya, Venkat Krovi</i> |      |
| Adaptive Exploration-Exploitation Active Learning of Gaussian Processes.....   | 7268 |
| <i>George P. Kontoudis, Michael Otte</i>   |      |
| Sample-Efficient Real-Time Planning with Curiosity Cross-Entropy Method and Contrastive Learning .....   | 7276 |
| <i>Mostafa Kotb, Cornelius Weber, Stefan Wermter</i>   |      |
| Underactuated MIMO Airship Control Based on Online Data-Driven Reinforcement Learning .....  | 7284 |
| <i>Derek Boase, Wail Gueaieb, Md Suruz Miah</i>  |      |
| Grasp Stability Assessment Through Attention-Guided Cross-Modality Fusion and Transfer Learning .....  | 7292 |
| <i>Zhuangzhuang Zhang, Zhenning Zhou, Haili Wang, Zhinan Zhang, Huang Huang, Qixin Cao</i>   |      |
| On-Robot Bayesian Reinforcement Learning for POMDPs.....   | 7300 |
| <i>Hai Nguyen, Sammie Katt, Yuchen Xiao, Christopher Amato</i>   |      |
| TemporalStereo: Efficient Spatial-Temporal Stereo Matching Network.....  | 7308 |
| <i>Youmin Zhang, Matteo Poggi, Stefano Mattoccia</i>   |      |
| Convolutional Occupancy Models for Dense Packing of Complex, Novel Objects .....   | 7316 |
| <i>Nikhil Mishra, Pieter Abbeel, Xi Chen, Maximilian Sieb</i>  |      |
| Real-Time Video Inpainting for RGB-D Pipeline Reconstruction .....   | 7323 |
| <i>Luyuan Wang, Tina Tian, Xinzhi Yan, Fujun Ruan, G. Jaya Aadityaa, Howie Choset, Lu Li</i>   |      |
| MUFeat: Multi-Level CNN and Unsupervised Learning for Local Feature Detection and Description .....  | 7331 |
| <i>Sheng-Hung Kuo, Tzu-Han Wu, Zheng-Yan Chen, Kuan-Wen Chen</i>   |      |
| Early Or Late Fusion Matters: Efficient RGB-D Fusion in Vision Transformers for 3D Object Recognition .....  | 7338 |
| <i>Georgios Tziasas, Hamidreza Kasaei</i>  |      |
| TransTouch: Learning Transparent Objects Depth Sensing Through Sparse Touches .....  | 7346 |
| <i>Liuyu Bian, Pengyang Shi, Weihang Chen, Jing Xu, Li Yi, Rui Chen</i>  |      |
| WatchPed: Pedestrian Crossing Intention Prediction Using Embedded Sensors of Smartwatch .....  | 7354 |
| <i>Jibran Ali Abbasi, Navid Mohammad Imran, Lokesh Chandra Das, Myounggyu Won</i>  |      |

|  |      |
|--|------|
| Object Detection Based on Raw Bayer Images .....   | 7362 |
| <i>Guoyu Lu</i>  |      |
| SDFMAP: Neural Signed Distance Fields for Mapping and Positioning in Real-Time.....  | 7370 |
| <i>Shaofan Liu, Jianke Zhu</i>   |      |
| LocalViT: Analyzing Locality in Vision Transformers.....   | 7378 |
| <i>Yawei Li, Kai Zhang, Jiezhang Cao, Radu Timofte, Michele Magno, Luca Benini, Luc Van Gool</i>                                     |      |
| HistoDepth - Novel Depth Perception for Safe Collaborative Robots .....  | 7386 |
| <i>Cornelius Buerkle, Fabian Oboril, Kay-Ulrich Scholl</i>   |      |
| Safe Active Learning and Probabilistic Design of Experiment for Autonomous Hydraulic Excavators .....                                | 7394 |
| <i>Maximilian Dio, Ozan Demir, Adrian Trachte, Knut Graichen</i>   |      |
| SMART-Rain: A Degradation Evaluation Dataset for Autonomous Driving in Rain.....   | 7400 |
| <i>Chen Zhang, Zefan Huang, Hongliang Guo, Lei Qin, Marcelo H. Ang, Daniela Rus</i>  |      |
| Learning Representation for Anomaly Detection of Vehicle Trajectories .....  | 7408 |
| <i>Ruochen Jiao, Juyang Bai, Xiangguo Liu, Takami Sato, Xiaowei Yuan, Qi Alfred Chen, Qi Zhu</i>                                     |      |
| Lateral-Direction Localization Attack in High-Level Autonomous Driving: Domain-Specific Defense Opportunity Via Lane Detection.....  | 7416 |
| <i>Junjie Shen, Yunpeng Luo, Ziwen Wan, Qi Alfred Chen</i>   |      |
| Safety-Assured Speculative Planning with Adaptive Prediction .....   | 7423 |
| <i>Xiangguo Liu, Ruochen Jiao, Yixuan Wang, Yimin Han, Bowen Zheng, Qi Zhu</i>   |      |
| A Decision Tree-Based Monitoring and Recovery Framework for Autonomous Robots with Decision Uncertainties.....                       | 7431 |
| <i>Rahul Peddi, Nicola Bezzo</i>   |      |
| A Safety Filter for Realizing Safe Robot Navigation in Crowds.....   | 7438 |
| <i>Kaijun Feng, Zetao Lu, Jun Xu, Haoyao Chen, Yunjiang Lou</i>  |      |
| Risk-Aware Safe Control for Decentralized Multi-Agent Systems Via Dynamic Responsibility Allocation .....                            | 7446 |
| <i>Yiwei Lyu, Wenhao Luo, John M. Dolan</i>  |      |
| Autonomous Exploration Using Ground Robots with Safety Guarantees.....   | 7454 |
| <i>David Smith Sundarsingh, Jay Bhagiya, Jeel Chatrola, Pushpak Jagtap</i>   |      |
| Exploiting the Kinematic Redundancy of a Backdrivable Parallel Manipulator for Sensing During Physical Human-Robot Interaction ..... | 7460 |
| <i>Arda Yigit, Tan-Sy Nguyen, Clément Gosselin</i>   |      |
| Measuring People's Boredom and Indifference to the Robot's Explanation in a Museum Scenario .....                                    | 7466 |
| <i>Rei Nagaya, Stela H. Seo, Takayuki Kanda</i>  |      |
| Is Weakly-Supervised Action Segmentation Ready for Human-Robot Interaction? No, Let's Improve it with Action-Union Learning .....    | 7472 |
| <i>Fan Yang, Shigeyuki Odashima, Shoichi Masui, Shan Jiang</i>   |      |
| Co-Speech Gesture Synthesis Using Discrete Gesture Token Learning.....   | 7480 |
| <i>Shuhong Lu, Youngwoo Yoon, Andrew Feng</i>  |      |

|   |      |
|---|------|
| WSCFER: Improving Facial Expression Representations by Weak Supervised Contrastive Learning .....   | 7488 |
| <i>Wei Nie, Bowen Chen, Wenhao Wu, Xiu Xu, Weihong Ren, Honghai Liu</i>   |      |
| Expressing and Inferring Action Carefulness in Human-To-Robot Handovers.....  | 7496 |
| <i>Linda Lastrico, Nuno Ferreira Duarte, Alessandro Carfi, Francesco Rea, Alessandra Sciutti, Fulvio Mastrogiovanni, José Santos-Victor</i>   |      |
| Learning Open-Loop Saccadic Control of a 3D Biomimetic Eye Using the Actor-Critic Algorithm .....   | 7504 |
| <i>Henrique Granado, Reza Javanmard Alitappeh, Akhil John, A. John Van Opstal, Alexandre Bernardino</i>   |      |
| Communicating Human Intent to a Robotic Companion by Multi-Type Gesture Sentences .....   | 7511 |
| <i>Petr Vanc, Jan Kristof Behrens, Karla Stepanova, Vaclav Hlavac</i>   |      |
| MoEmo Vision Transformer: Integrating Cross-Attention and Movement Vectors in 3D Pose   |      |
| Estimation for HRI Emotion Detection .....  | 7518 |
| <i>David C. Jeong, Tianma Shen, Hongji Liu, Raghav Kapoor, Casey Nguyen, Song Liu, Christopher A. Kitts</i>   |      |
| How Do Humans Provide Motion Assistance for a Robotic Shape-Tracing Task? .....   | 7525 |
| <i>Taylor M. Higgins, Ann Majewicz Fey</i>  |      |
| The Effects of Robot Motion on Comfort Dynamics of Novice Users in Close-Proximity Human-Robot Interaction.....   | 7531 |
| <i>Pierce Howell, Jack Kolb, Yifan Liu, Harish Ravichandar</i>  |      |
| Estimating Human Comfort Levels in Autonomous Vehicles Based on Vehicular Behaviors and Physiological Signals.....  | 7537 |
| <i>Haotian Su, Yunyi Jia</i>  |      |
| EELS: Towards Autonomous Mobility in Extreme Terrain with a Versatile Snake Robot with Resilience to Exteroception Failures .....   | 7543 |
| <i>Rohan Thakker, Michael Paton, Marlin P. Strub, Michael Swan, Guglielmo Daddi, Rob Royce, Phillippe Tosi, Matthew Gildner, Tiago Vaquero, Marcel Veismann, Peter Gavrilov, Eloise Marteau, Joseph Bowkett, Daniel Loret, Yashwanth Nakka, Benjamin Hockman, Andrew Orekhov, Tristan Hasseler, Carl Leake, Benjamin Nuernberger, Pedro Proen  a, William Reid, William Talbot, Nikola Georgiev, Torkom Pailevanian, Avak Archanian, Eric Ambrose, Jay Jasper, Rachel Etheredge, Christiahn Roman, Dan Levine, Kyohei Otsu, Hovhannes Melikyan, Jeremy Nash, Richard Rieber, Kalind Carpenter, Abhinandan Jain, Lori Shiraishi, Daniel Pastor, Sarah Yearicks, Michel Ingham, Matthew Robinson, Ali Agha, Matthew Travers, Howie Choset, Joel Burdick, Masahiro Ono</i> |      |
| Track, Stop, and Eliminate: An Algorithm to Solve Stochastic Orienteering Problems Using MCTS.....  | 7551 |
| <i>Carlos Diaz Alvarenga, Stefano Carpin</i>  |      |
| DVL-Based Odometry for Autonomous Underwater Gliders .....  | 7559 |
| <i>Gideon Billings, Amy Phung, Richard Camilli</i>  |      |
| Terrain-Aware Kinodynamic Planning with Efficiently Adaptive State Lattices for Mobile Robot Navigation in Off-Road Environments.....   | 7567 |
| <i>Eric R. Damm, Jason M. Gregory, Eli S. Lancaster, Felix A. Sanchez, Daniel M. Sahu, Thomas M. Howard</i>   |      |
| Evaluation of Underwater AprilTag Localization for Highly Agile Micro Underwater Robots.....  | 7575 |
| <i>Nathalie Bauschmann, Daniel A Duecker, Thies L Alff, Robert Seifried</i>   |      |

|   |      |
|---|------|
| Weakly Supervised Caveline Detection for AUV Navigation Inside Underwater Caves .....   | 7582 |
| <i>Boxiao Yu, Reagan Tibbetts, Titon Barna, Ailani Morales, Ioannis Rekleitis, Md Jahidul Islam</i>   |      |
| Wireless Network Demands of Data Products from Small Uncrewed Aerial Systems at Hurricane Ian.....  | 7590 |
| <i>Thomas Manzini, Robin Murphy, David Merrick, Justin Adams</i>  |      |
| Robot Learning to Mop Like Humans Using Video Demonstrations.....   | 7596 |
| <i>Sanket Gaurav, Aaron Crookes, David Hoying, Vignesh Narayanaswamy, Harish Venkataraman, Matthew Barker, Venugopal Vasudevan, Brian Ziebart</i> |      |
| AcTag: Opti-Acoustic Fiducial Markers for Underwater Localization and Mapping .....   | 7604 |
| <i>Kalin Norman, Daniel Butterfield, Joshua G. Mangelson</i>  |      |
| Multi-Agent Collective Construction Using 3D Decomposition.....   | 7612 |
| <i>Akshaya Kesariangalam Srinivasan, Shambhavi Singh, Geordan Gutow, Howie Choset, Bhaskar Vundurthy</i>  |      |
| Daily Assistive Modular Robot Design Based on Multi-Objective Black-Box Optimization.....   | 7619 |
| <i>Kento Kawaharazuka, Tasuku Makabe, Kei Okada, Masayuki Inaba</i>   |      |
| A Unified Perspective on Multiple Shooting in Differential Dynamic Programming .....  | 7627 |
| <i>He Li, Wenhao Yu, Tingnan Zhang, Patrick M. Wensing</i>  |      |
| Data-Driven Distributionally Robust Optimal Control with State-Dependent Noise.....   | 7635 |
| <i>Rui Liu, Guangyao Shi, Pratap Tokekar</i>  |      |
| A Mangasarian-Soldov Function Based Neural Network for Constrained Control of Parallel and Serial Robots .....                                    | 7641 |
| <i>Weibing Li, Yanying Zou, Zilian Yi, Haimei Wu, Yongping Pan</i>  |      |
| Controller and Trajectory Optimization for a Quadrotor UAV with Parametric Uncertainty .....  | 7648 |
| <i>Ali Srour, Antonio Franchi, Paolo Robuffo Giordano</i>   |      |
| Real-Time NMPC for an Automated Valet Parking with Load-Based Safety Constraints and a Path-Parametric Model .....                                | 7655 |
| <i>Bárbara Barros Carlos, Martin Williams, Benoît Pelourdeau</i>  |      |
| Time-Optimal Point-To-Point Motion Planning and Assembly Mode Change of Cuspidal Manipulators: Application to 3R and 6R Robots.....               | 7663 |
| <i>Tobias Marauli, Durgesh Haribhau Salunkhe, Hubert Gatringer, Andreas Müller, Damien Chablat, Philippe Wenger</i>                               |      |
| End-To-End Learning of Behavioural Inputs for Autonomous Driving in Dense Traffic .....   | 7669 |
| <i>Jatan Shrestha, Simon Idoko, Basant Sharma, Arun Kumar Singh</i>   |      |
| Gaussian Max-Value Entropy Search for Multi-Agent Bayesian Optimization .....   | 7677 |
| <i>Haitong Ma, Tianpeng Zhang, Yixuan Wu, Flavio P. Calmon, Na Li</i>   |      |
| FATROP: A Fast Constrained Optimal Control Problem Solver for Robot Trajectory Optimization and Control.....                                      | 7685 |
| <i>Lander Vanroye, Ajay Sathya, Joris De Schutter, Wilm Decré</i>   |      |
| CineTransfer: Controlling a Robot to Imitate Cinematographic Style from a Single Example.....   | 7693 |
| <i>Pablo Pueyo, Eduardo Montijano, Ana C. Murillo, Mac Schwager</i>   |      |

|  |      |
|--|------|
| Robust Satisfaction of Joint Position and Velocity Bounds in Discrete-Time Acceleration Control of Robot Manipulators .....  | 7699 |
| <i>Erik Zanolli, Andrea Del Prete</i>  |      |
| Toward Closed-Loop Additive Manufacturing: Paradigm Shift in Fabrication, Inspection, and Repair .....   | 7707 |
| <i>Manpreet Singh, Fujun Ruan, Albert Xu, Yuchen Wu, Archit Rungta, Luyuan Wang, Kevin Song, Howie Choset, Lu Li</i>   |      |
| Optimal Decision Making in Robotic Assembly and Other Trial-And-Error Tasks .....  | 7715 |
| <i>James Watson, Nikolaus Correll</i>  |      |
| A Cartesian Platform for Cooperative Multi-Robot Manipulation Tasks .....  | 7723 |
| <i>Silvio Müller, Stefan Ilic, Vincenzo Scamarcio, Josie Hughes</i>  |      |
| Robotic Crop Handling in Cluttered and Unstructured Environments Using Simulated L-System Dynamic Plant Models .....   | 7729 |
| <i>Quinlan T. Barthelme, Chris. Lehnert</i>  |      |
| Understanding the Influence of Robot Motion on the Experimental Processes Present in Food Science Applications .....   | 7737 |
| <i>Stefan Ilic, Edgar Chávez Montes, Constantijn Sanders, Cécile Gehin-Delval, Giulia Marchesini, Josie Hughes</i>   |      |
| High-Accuracy Injection Using a Mobile Manipulation Robot for Chemistry Lab Automation .....   | 7743 |
| <i>Angelos Angelopoulos, Matthew Verber, Collin McKinney, James Cahoon, Ron Alterovitz</i>   |      |
| Robotic Defect Inspection with Visual and Tactile Perception for Large-Scale Components .....  | 7751 |
| <i>Arpit Agarwal, Abhiroop Ajith, Chengtao Wen, Veniamin Stryzheus, Brian Miller, Matthew Chen, Micah K. Johnson, Jose Luis Susa Rincon, Justinian Rosca, Wenzhen Yuan</i> |      |
| Sensor Selection for Fine-Grained Behavior Verification that Respects Privacy .....  | 7758 |
| <i>Rishi Phatak, Dylan A. Shell</i>  |      |
| Development of the Whole-Body Waterproof Shell Applying and Removing System Using Phase-Change Paraffin and Grease for the Multi-DOF Robot .....                           | 7766 |
| <i>Tasuku Makabe, Kei Okada, Masayuki Inaba</i>  |      |
| Learning to Adapt the Parameters of Behavior Trees and Motion Generators (BTMGs) to Task Variations.....   | 7774 |
| <i>Faseeh Ahmad, Matthias Mayr, Volker Krueger</i>   |      |
| CEFHRI: A Communication Efficient Federated Learning Framework for Recognizing Industrial Human-Robot Interaction .....  | 7782 |
| <i>Umar Khalid, Hasan Iqbal, Saeed Vahidian, Jing Hua, Chen Chen</i>   |      |
| COMPlacent: A Compliant Whisker Manipulator for Object Tactile Exploration .....   | 7790 |
| <i>Chenxi Xiao, Juan Wachs</i>   |      |
| Monolithic Microchannels in Miniature Pneumatic Soft Robots for Sequential Motions.....  | 7797 |
| <i>Dongliang Fan, Hao Liu, Ting Wang, Renjie Zhu, Hongqiang Wang</i>   |      |
| Polymer-Based Self-Calibrated Optical Fiber Tactile Sensor.....  | 7803 |
| <i>Wentao Chen, Youcan Yan, Zeqing Zhang, Lei Yang, Jia Pan</i>  |      |
| 2-DOF Robot Arm with Variable Torque Limiters Realized by Electrostatic Film Motors .....  | 7810 |
| <i>Masahiko Osada, Guangwei Zhang, Shunsuke Yoshimoto, Akio Yamamoto</i>   |      |

|   |      |
|---|------|
| Design and Stiffness Analysis of a Bio-Inspired Soft Actuator with Bi-Direction Tunable Stiffness Property .....  | 7816 |
| <i>Jianfeng Lin, Ruikang Xiao, Zhao Guo</i>   |      |
| MIGHTY: Multi-Functional Suction Cup for Object Gripping and Surface Attachment.....  | 7822 |
| <i>Emmanouil Papadakis, Markos Sigalas, Michail Vangos, Panos Trahanias</i>   |      |
| Multiple-Contact Estimation for Tendon-Driven Continuum Robots with Proprioceptive Sensor Information by Contact Particle Filter and Kinetostatic Models .....  | 7830 |
| <i>Tim-David Job, Martin Bensch, Moritz Schappler</i>   |      |
| Eversion-Capable Fabric Robot Gripper with Novel Retraction Mechanism .....   | 7838 |
| <i>Ahmed Hassan, Taqi Abrar, Faisal Aljaber, Ivan Vitanov, Kaspar Althoefer</i>   |      |
| Emergent Sequential Motion Through Compliant Auxetic Shells.....  | 7844 |
| <i>Audrey Sedal, Margaret Kohler, Godswill Agbofode, Talia Y. Moore, Sridhar Kota</i>   |      |
| Automated Gait Generation for Walking, Soft Robotic Quadrupeds.....   | 7851 |
| <i>Jake Ketchum, Sophia Schiffer, Muchen Sun, Pranav Kaarthik, Ryan L. Truby, Todd D. Murphey</i>   |      |
| Towards MR-Safe Concentric Bellows-Based Hydrostatic Linear Actuator for a Needle Driver.....   | 7858 |
| <i>Kwan Kit Lin, Yufu Qiu, Kim Yan, Qingpeng Ding, Shing Shin Cheng</i>   |      |
| Analytical Computation of the Contact Force Jacobian for MRI-Actuated Robotic Catheter .....  | 7866 |
| <i>Yuttana Itsarachaiyot, Ran Hao, M. Cenk Çavusoglu</i>  |      |
| Magnet Array-Actuated Steerable Flexible Robot with Beacon-TFM Ultrasonic Position Sensing for Robotic Neurosurgery .....                                       | 7873 |
| <i>Xinfeng Gu, Qingyu Zhang, Xiaoyu Sun, Zhiyuan Shen, Bruce W. Drinkwater, Feng Ju</i>   |      |
| Sunram 7: An MR Safe Robotic System for Breast Biopsy .....   | 7879 |
| <i>Harsh Ranjan, Marijn Van Hilten, Vincent Groenhuis, Juan Verde, Alain Garcia, Silvana Perretta, Jeroen Veltman, Françoise J. Siepel, Stefano Stramigioli</i> |      |
| Constrained Reinforcement Learning and Formal Verification for Safe Colonoscopy Navigation.....   | 7887 |
| <i>Davide Corsi, Luca Marzari, Ameya Pore, Alessandro Farinelli, Alicia Casals, Paolo Fiorini, Diego Dall'Alba</i>  |      |
| Design and Development of a Novel Soft and Inflatable Tactile Sensing Balloon for Early Diagnosis of Colorectal Cancer Polyps .....                             | 7893 |
| <i>Ozdemir Can Kara, Hansoul Kim, Jiaqi Xue, Tarunraj G. Mohanraj, Yuki Hirata, Naruhiko Ikoma, Farshid Alambeigi</i>   |      |
| A Telescopic Tendon-Driven Needle Robot for Minimally Invasive Neurosurgery.....  | 7899 |
| <i>Saeed Rezaeian, Behnam Badie, Jun Sheng</i>  |      |
| Characteristics of Permanent Magnet Coupling Based Wireless Manipulation Via Simulation.....  | 7906 |
| <i>Tao Zhang, Jixiu Li, Truman Cheng, Calvin S. H. Ng, Philip W. Y. Chiu, Zheng Li</i>  |      |
| Design and Evaluation of Bidirectional Continuous Rotation and Variable Curvature Needle Steering Algorithm .....   | 7913 |
| <i>Farid Tavakkolmoghaddam, Charles Bales, Yang Wang, Zhanyue Zhao, Gregory S. Fischer</i>  |      |

|  |      |
|--|------|
| Development of a Whole-Body Work Imitation Learning System by a Biped and Bi-Armed Humanoid .....  | 7921 |
| <i>Yutaro Matsuura, Kento Kawaharazuka, Naoki Hiraoka, Kunio Kojima, Kei Okada, Masayuki Inaba</i>   |      |
| Humanoid Walking System with CNN-Based Uneven Terrain Recognition and Landing Control with Swing-Leg Velocity Constraints .....  | 7929 |
| <i>Shimpei Sato, Kunio Kojima, Naoki Hiraoka, Kei Okada, Masayuki Inaba</i>  |      |
| Whole Body Control Formulation for Humanoid Robots with Closed/Parallel Kinematic Chains: Kangaroo Case Study .....  | 7937 |
| <i>Sait Sovukluk, Johannes Englsberger, Christian Ott</i>  |      |
| Exploring Kinodynamic Fabrics for Reactive Whole-Body Control of Underactuated Humanoid Robots .....   | 7944 |
| <i>Alphonsus Adu-Bredu, Grant Gibson, Jessy Grizzle</i>  |      |
| Step Toward Deploying the Torque-Controlled Robot TALOS on Industrial Operations .....   | 7952 |
| <i>Côme Perrot, Olivier Stasse</i>   |      |
| Learning Joint Space Reference Manifold for Reliable Physical Assistance .....   | 7959 |
| <i>Amirreza Razmjoo, Tilen Breclj, Kristina Savevska, Aleš Ude, Tadej Petric, Sylvain Calinon</i>  |      |
| MELP: Model Embedded Linear Policies for Robust Bipedal Hopping.....   | 7965 |
| <i>Raghav Soni, Guillermo A. Castillo, Lokesh Krishna, Ayonga Hereid, Shishir Kolathaya</i>  |      |
| EvoBOT – Design and Learning-Based Control of a Two-Wheeled Compound Inverted Pendulum Robot .....   | 7972 |
| <i>Patrick Klokowski, Julian Eßer, Nils Gramse, Benedikt Pschera, Marc Plitt, Frido Feldmeier, Shubham Bajpai, Christian Jestel, Nicolas Bach, Oliver Urbann, Sören Kerner</i> |      |
| Investigations into Exploiting the Full Capabilities of a Series-Parallel Hybrid Humanoid Using Whole Body Trajectory Optimization .....                                       | 7980 |
| <i>Melya Boukheddimi, Rohit Kumar, Shivesh Kumar, Justin Carpentier, Frank Kirchner</i>  |      |
| Integrable Whole-Body Orientation Coordinates for Legged Robots .....  | 7987 |
| <i>Yu-Ming Chen, Gabriel Nelson, Robert Griffin, Michael Posa, Jerry Pratt</i>   |      |
| Learning Multimodal Bipedal Locomotion and Implicit Transitions: A Versatile Policy Approach .....   | 7995 |
| <i>Lokesh Krishna, Quan Nguyen</i>   |      |
| CLF-CBF Constraints for Real-Time Avoidance of Multiple Obstacles in Bipedal Locomotion and Navigation .....   | 8003 |
| <i>Jinze Liu, Minzhe Li, Jessy W. Grizzle, Jiunn-Kai Huang</i>   |      |
| Next-Best-View Selection from Observation Viewpoint Statistics .....   | 8011 |
| <i>Stéphanie Aravecchia, Antoine Richard, Marianne Clausel, Cédric Pradalier</i>   |      |
| Feedback Motion Prediction for Safe Unicycle Robot Navigation .....  | 8017 |
| <i>Aykut Isleyen, Nathan Van De Wouw, Ömür Arslan</i>  |      |
| Learned Parameter Selection for Robotic Information Gathering.....   | 8025 |
| <i>Christopher E. Denniston, Gautam Salhotra, Akseli Kangaslahti, David A. Caron, Gaurav S. Sukhatme</i>   |      |

|   |      |
|---|------|
| FISS+: Efficient and Focused Trajectory Generation and Refinement Using Fast Iterative Search and Sampling Strategy.....  | 8033 |
| <i>Shuo Sun, Jie Chen, Jiawei Sun, Chengran Yuan, Yuanchen Li, Tangyike Zhang, Marcelo H. Ang</i>   |      |
| Real-Time Failure-Adaptive Control for Dynamic Robots .....   | 8041 |
| <i>Jacob Hackett, Christian Hubicki</i>   |      |
| Risk-Aware Stochastic Ship Routing Using Conditional Value-At-Risk.....   | 8049 |
| <i>Andre Nuñez, Felix H. Kong, Alberto González-Cantos, Robert Fitch</i>  |      |
| RAMP: Hierarchical Reactive Motion Planning for Manipulation Tasks Using Implicit Signed Distance Functions .....   | 8057 |
| <i>Vasileios Vasilopoulos, Suveer Garg, Pedro Piacenza, Jinwook Huh, Volkan Isler</i>   |      |
| Towards Safe and Aggressive Motion Generation for Dynamic Targets Pick-And-Place.....   | 8065 |
| <i>Jun Shao, Jianfeng Liao, Han Li, Haoyang Zhang, Shiqiang Zhu, Wei Song, Yinchun Huang</i>  |      |
| SPONGE: Sequence Planning with Deformable-ON-Rigid Contact Prediction from Geometric Features .....   | 8073 |
| <i>Tran Nguyen Le, Fares J. Abu-Dakka, Ville Kyrki</i>  |      |
| Contact-Aware Non-Prehensile Manipulation for Object Retrieval in Cluttered Environments .....  | 8081 |
| <i>Yongpeng Jiang, Yongyi Jia, Xiang Li</i>   |      |
| SDF-Pack: Towards Compact Bin Packing with Signed-Distance-Field Minimization.....  | 8089 |
| <i>Jia-Hui Pan, Ka-Hei Hui, Xiaojie Gao, Shize Zhu, Yun-Hui Liu, Pheng-Ann Heng, Chi-Wing Fu</i>  |      |
| Multi-Modal Planning on Regrasping for Stable Manipulation .....  | 8097 |
| <i>Jiaming Hu, Zhao Tang, Henrik I. Christensen</i>   |      |
| Efficient Object Manipulation Planning with Monte Carlo Tree Search.....  | 8105 |
| <i>Huaijiang Zhu, Avadesh Meduri, Ludovic Righetti</i>  |      |
| A New Method Combining Single-Point Push and Double-Point Complete Push for Partially Observable Scenarios .....  | 8113 |
| <i>Jiawei Zhang, Chengchao Bai, Jifeng Guo</i>  |      |
| Pre-And Post-Contact Policy Decomposition for Non-Prehensile Manipulation with Zero-Shot Sim-To-Real Transfer .....   | 8121 |
| <i>Minchan Kim, Junhyek Han, Jaehyung Kim, Beomjoon Kim</i>   |      |
| Material-Agnostic Shaping of Granular Materials with Optimal Transport.....   | 8129 |
| <i>Nikhilesh Alatur; Olov Andersson, Roland Siegwart, Lionel Ott</i>  |      |
| Learning to Efficiently Plan Robust Frictional Multi-Object Grasps .....  | 8137 |
| <i>Wisdom C. Agboh, Satvik Sharma, Kishore Srinivas, Mallika Parulekar, Gaurav Datta, Tianshuang Qiu, Jeffrey Ichnowski, Eugen Solowjow, Mehmet Dogar, Ken Goldberg</i> |      |
| POMDP-Guided Active Force-Based Search for Robotic Insertion.....   | 8145 |
| <i>Chen Wang, Haoxiang Luo, Kun Zhang, Hua Chen, Jia Pan, Wei Zhang</i>   |      |
| Shared Autonomy Control for Slosh-Free Teleoperation .....  | 8153 |
| <i>Rafael I. Cabral Muchacho, Seongjin Bien, Riddhiman Laha, Abdeldjallil Naceri, Luis F. C. Figueiredo, Sami Haddadin</i>  |      |

|   |      |
|---|------|
| Leader-Follower Formation Control of a Large-Scale Swarm of Satellite System Using the State-Dependent Riccati Equation: Orbit-To-Orbit and In-Same-Orbit Regulation .....                  | 8161 |
| <i>Saeed Rafee Nekoo, Jie Yao, Alejandro Suarez, Raul Tapia, Anibal Ollero</i>  |      |
| Lunar Excavator Mission Operations Using Dynamic Movement Primitives.....   | 8169 |
| <i>Joseph M. Cloud, Minh Q. Tram, William J. Beksi, Michael A. Dupuis</i>   |      |
| Fast Bi-Monocular Visual Odometry Using Factor Graph Sparsification.....  | 8177 |
| <i>César Debeunne, Joan Vallvé, Alex Torres, Damien Vivet</i>   |      |
| Assisting Spectral Mapping Using Cameras .....  | 8184 |
| <i>Srinivasan Vijayarangan, David Wettergreen</i>   |      |
| Autonomous Multi-Robot Servicing for Spacecraft Operation Extension .....   | 8190 |
| <i>Longsen Gao, Giovanni Cordova, Claus Danielson, Rafael Fierro</i>  |      |
| SOLL-E: A Module Transport and Placement Robot for Autonomous Assembly of Discrete Lattice Structures.....  | 8197 |
| <i>In-Won Park, Damiana Catanoso, Olivia Formoso, Christine Gregg, Megan Ochalek, Taiwo Olatunde, Frank Sebastianelli, Pascal Spino, Elizabeth Taylor, Greenfield Trinh, Kenneth Cheung</i> |      |
| Bi-Level Image-Guided Ergodic Exploration with Applications to Planetary Rovers .....   | 8203 |
| <i>Elena Wittemyer, Ian Abraham</i>   |      |
| 6D Object Pose Estimation from Approximate 3D Models for Orbital Robotics.....  | 8210 |
| <i>Maximilian Ulmer, Maximilian Durner, Martin Sundermeyer, Manuel Stoiber, Rudolph Triebel</i>   |      |
| An Origami-Inspired Deployable Space Debris Collector .....   | 8218 |
| <i>Yuto Tanaka, Aditya Arjun Anibha, Leonard Jung, Roha Gul, Jeffrey Sun, Ran Dai</i>   |      |
| Principled ICP Covariance Modelling in Perceptually Degraded Environments for the EELS Mission Concept.....   | 8224 |
| <i>William Talbot, Jeremy Nash, Michael Paton, Eric Ambrose, Brandon Metz, Rohan Thakker, Rachel Etheredge, Masahiro Ono, Viorela Ila</i>   |      |
| Deep Functional Predictive Control (deep-FPC): Robot Pushing 3-D Cluster Using Tactile Prediction .....   | 8232 |
| <i>Kiyanoush Nazari, Gabriele Gandolfi, Zeynab Talebpour, Vishnu Rajendran, Willow Mandil, Paolo Rocco, Amir Ghalamzan-E.</i>   |      |
| Wireless Capacitive Tactile Sensor Arrays for Sensitive/Delicate Robot Grasping .....   | 8238 |
| <i>Serkan Ergun, Tobias Mitterer, Sherjeel Khan, Narendiran Anandan, Rishabh B. Mishra, Jürgen Kosel, Hubert Zangl</i>  |      |
| Active Planar Mass Distribution Estimation with Robotic Manipulation .....  | 8246 |
| <i>Jiacheng Yuan, Changhyun Choi, Ellad B. Tadmor, Volkan Isler</i>   |      |
| Touch if It's Transparent! ACTOR: Active Tactile-Based Category-Level Transparent Object Reconstruction.....  | 8253 |
| <i>Prajval Kumar Murali, Bernd Porr, Mohsen Kaboli</i>  |      |
| Learn from Incomplete Tactile Data: Tactile Representation Learning with Masked Autoencoders.....   | 8261 |
| <i>Guanqun Cao, Jiaqi Jiang, Danushka Bollegala, Shan Luo</i>   |      |
| Attention for Robot Touch: Tactile Saliency Prediction for Robust Sim-To-Real Tactile Control.....  | 8267 |
| <i>Yijiong Lin, Mauro Comi, Alex Church, Dandan Zhang, Nathan F. Lepora</i>   |      |

|   |      |
|---|------|
| FingerTac - An Interchangeable and Wearable Tactile Sensor for the Fingertips of Human and Robot Hands .....                            | 8274 |
| <i>Prathamesh Sathe, Alexander Schmitz, Tito Pradhono Tomo, Sophon Somlor, Satoshi Funabashi, Sugano Shigeki</i>                        |      |
| AcouSkin: Full Surface Contact Localization Using Acoustic Waves .....  | 8282 |
| <i>Adarsh Kumar Kosta, Alexis Burns, Siddharth Rupavatharam, Caleb Escobedo, Daewon Lee, Richard Howard, Larry Jackel, Volkan Isler</i> |      |
| Unsupervised OmniMVS: Efficient Omnidirectional Depth Inference Via Establishing Pseudo-Stereo Supervision.....                         | 8290 |
| <i>Zisong Chen, Chunyu Lin, Lang Nie, Kang Liao, Yao Zhao</i>   |      |
| Multi-IMU Proprioceptive State Estimator for Humanoid Robots.....   | 8297 |
| <i>Fabio Elnecave Xavier, Guillaume Burger, Marine Pétriaux, Jean-Emmanuel Deschaud, François Goulette</i>                              |      |
| Design Space Exploration on Efficient and Accurate Human Pose Estimation from Sparse IMU-Sensing .....                                  | 8305 |
| <i>Iris Fürst-Walter, Antonio Nappi, Tanja Harbaum, Jürgen Becker</i>   |      |
| Language-Conditioned Observation Models for Visual Object Search.....   | 8311 |
| <i>Thao Nguyen, Vladislav Hrosinkov, Eric Rosen, Stefanie Tellex</i>  |      |
| TransCAR: Transformer-Based Camera-And-Radar Fusion for 3D Object Detection.....  | 8319 |
| <i>Su Pang, Daniel Morris, Hayder Radha</i>   |      |
| DualCross: Cross-Modality Cross-Domain Adaptation for Monocular BEV Perception.....   | 8327 |
| <i>Yunze Man, Liangyan Gui, Yu-Xiong Wang</i>   |      |
| INF: Implicit Neural Fusion for LiDAR and Camera.....   | 8335 |
| <i>Shuyi Zhou, Shuxiang Xie, Ryoichi Ishikawa, Ken Sakurada, Masaki Onishi, Takeshi Oishi</i>   |      |
| Multi-Modal Upper Limbs Human Motion Estimation from a Reduced Set of Affordable Sensors.....   | 8343 |
| <i>Mohamed Adjel, Maxime Sabbah, Raphael Dumas, Nicolas Mansard, Samer Mohammed, Bruno Watier, Vincent Bonnet</i>                       |      |
| Cognition Difference-Based Dynamic Trust Network for Distributed Bayesian Data Fusion .....   | 8350 |
| <i>Yingke Li, Ziqiao Zhang, Junkai Wang, Huibo Zhang, Enlu Zhou, Fumin Zhang</i>  |      |
| Sparse Dense Fusion for 3D Object Detection .....   | 8356 |
| <i>Yulu Gao, Chonghao Sima, Shaoshuai Shi, Shangzhe Di, Si Liu, Hongyang Li</i>   |      |
| Visual Contact Pressure Estimation for Grippers in the Wild.....  | 8364 |
| <i>Jeremy A. Collins, Cody Houff, Patrick Grady, Charles C. Kemp</i>  |      |
| Hydra-Multi: Collaborative Online Construction of 3D Scene Graphs with Multi-Robot Teams.....   | 8372 |
| <i>Yun Chang, Nathan Hughes, Aaron Ray, Luca Carlone</i>  |      |
| TWO: A Simple Method of Directly Closing the Loop for LiDAR Odometry .....  | 8380 |
| <i>Zhuo Zhang, Zheng Yao, Mingquan Lu</i>   |      |
| MEM: Multi-Modal Elevation Mapping for Robotics and Learning .....  | 8388 |
| <i>Gian Erni, Jonas Frey, Takahiro Miki, Matias Mattamala, Marco Hutter</i>   |      |
| Cooperative LiDAR Localization and Mapping for V2X Connected Autonomous Vehicles.....   | 8396 |
| <i>Bingyi Cao, Claas-Norman Ritter, Khaled Alomari, Daniel Goehring</i>   |      |

|   |      |
|---|------|
| Resilient and Distributed Multi-Robot Visual SLAM: Datasets, Experiments, and Lessons Learned .....   | 8404 |
| <i>Yulun Tian, Yun Chang, Long Quang, Arthur Schang, Carlos Nieto-Granda, Jonathan P. How,<br/>Luca Carlone</i>                             |      |
| Assignment Algorithms for Multi-Robot Multi-Target Tracking with Sufficient and Limited<br>Sensing Capability.....                          | 8412 |
| <i>Peihan Li, Lifeng Zhou</i>   |      |
| Multi-View Robust Collaborative Localization in High Outlier Ratio Scenes Based on Semantic<br>Features .....                               | 8419 |
| <i>Yujie Tang, Meiling Wang, Yinan Deng, Yi Yang, Ziquan Lan, Yufeng Yue</i>  |      |
| KD-EKF: A Consistent Cooperative Localization Estimator Based on Kalman Decomposition.....  | 8425 |
| <i>Ning Hao, Fenghua He, Chungeng Tian, Yu Yao, Weilong Xia</i>   |      |
| A Distributed Scheduling Method for Networked UAV Swarm Based on Computing for<br>Communication .....                                       | 8432 |
| <i>Runfeng Chen, Jie Li, Yiting Chen, Yuchong Huang</i>   |      |
| Visual, Spatial, Geometric-Preserved Place Recognition for Cross-View and Cross-Modal<br>Collaborative Perception .....                     | 8440 |
| <i>Peng Gao, Jing Liang, Yu Shen, Sanghyun Son, Ming C. Lin</i>   |      |
| A Co-Simulation Framework for Communication and Control in Autonomous Multi-Robot<br>Systems.....   | 8448 |
| <i>Srikrishna Acharya, Mukunda Bharatheesha, Yogesh Simmhan, Bharadwaj Amrutar</i>  |      |
| FPECMV: Learning-Based Fault-Tolerant Collaborative Localization Under Limited Connectivity .....   | 8456 |
| <i>Rong Ou, Guanqi Liang, Tin Lun Lam</i>   |      |
| Dynamic Multi-Target Tracking Using Heterogeneous Coverage Control .....  | 8464 |
| <i>Ruoyu Lin, Magnus Egerstedt</i>  |      |
| Decentralized Connectivity Maintenance for Quadrotor UAVs with Field of View Constraints .....  | 8472 |
| <i>Maxime Bernard, Claudio Pacchierotti, Paolo Robuffo Giordano</i>   |      |
| FogROS2-SGC: A ROS2 Cloud Robotics Platform for Secure Global Connectivity .....  | 8480 |
| <i>Kaiyuan Chen, Ryan Hoque, Karthik Dharmarajan, Edith Llontopl, Simeon Adebola, Jeffrey<br/>Ichnowski, John Kubiakowicz, Ken Goldberg</i> |      |
| Covering Dynamic Demand with Multi-Resource Heterogeneous Teams .....   | 8488 |
| <i>Mela Coffey, Alyssa Pierson</i>  |      |
| Decision-Oriented Learning with Differentiable Submodular Maximization for Vehicle Routing<br>Problem .....                                 | 8496 |
| <i>Guangyao Shi, Pratap Tokekar</i>   |      |
| Privacy-Preserving and Uncertainty-Aware Federated Trajectory Prediction for Connected<br>Autonomous Vehicles.....                          | 8502 |
| <i>Muzi Peng, Jiangwei Wang, Dongjin Song, Fei Miao, Lili Su</i>  |      |
| On Collaborative Robot Teams for Environmental Monitoring: A Macroscopic Ensemble Approach .....  | 8509 |
| <i>Victoria Edwards, Thales C. Silva, Bharg Mehta, Jasleen Dhanoa, M. Ani Hsieh</i>   |      |
| Part-Level Scene Reconstruction Affords Robot Interaction.....  | 8515 |
| <i>Zeyu Zhang, Lexing Zhang, Zaijin Wang, Ziyuan Jiao, Muzhi Han, Yixin Zhu, Song-Chun Zhu,<br/>Hangxin Liu</i>                             |      |

|   |      |
|---|------|
| Online Adaptive Disparity Estimation for Dynamic Scenes in Structured Light Systems .....   | 8523 |
| <i>Rukun Qiao, Hiroshi Kawasaki, Hongbin Zha</i>  |      |
| RaPlace: Place Recognition for Imaging Radar Using Radon Transform and Mutable Threshold.....   | 8531 |
| <i>Hyesu Jang, Minwoo Jung, Ayoung Kim</i>  |      |
| Pyramid Semantic Graph-Based Global Point Cloud Registration with Low Overlap .....   | 8539 |
| <i>Zhijian Qiao, Zehuan Yu, Huan Yin, Shaojie Shen</i>  |      |
| Verifiable Goal Recognition for Autonomous Driving with Occlusions .....  | 8547 |
| <i>Cillian Brewitt, Massimiliano Tamborski, Cheng Wang, Stefano V. Albrecht</i>   |      |
| Semantically Informed MPC for Context-Aware Robot Exploration.....  | 8555 |
| <i>Yash Goel, Narunas Vaskevicius, Luigi Palmieri, Nived Chebrolu, Kai O. Arras, Cyrill Stachniss</i>                                     |      |
| Automotive Radar Missing Dimension Reconstruction from Motion.....  | 8563 |
| <i>Chun-Yu Hou, Chieh-Chih Wang, Wen-Chieh Lin</i>  |      |
| VERN: Vegetation-Aware Robot Navigation in Dense Unstructured Outdoor Environments .....  | 8570 |
| <i>Adarsh Jagan Sathyamoorthy, Kasun Weerakoon, Tianrui Guan, Mason Russell, Damon Conover, Jason Pusey, Dinesh Manocha</i>               |      |
| Sequential Neural Barriers for Scalable Dynamic Obstacle Avoidance .....  | 8578 |
| <i>Hongzhan Yu, Chiaki Hirayama, Chenning Yu, Sylvia Herbert, Sicun Gao</i>   |      |
| Collision Prevention Strategy Using Sparse 2D Spatial Information for Indoor Mobile Robots .....  | 8586 |
| <i>Youngil Koh, Eunsol Chang, Mideum Choi</i>   |      |
| Arena-Rosnav 2.0: A Development and Benchmarking Platform for Robot Navigation in Highly Dynamic Environments .....                       | 8594 |
| <i>Linh Kästner, Reyk Carstens, Huajian Zeng, Jacek Kmiecik, Teham Bhuiyan, Niloufar Khorsandhi, Volodymyr Shcherbyna, Jens Lambrecht</i> |      |
| Data-Efficient Policy Selection for Navigation in Partial Maps Via Subgoal-Based Abstraction.....   | 8602 |
| <i>Abhishek Paudel, Gregory J. Stein</i>  |      |
| Accelerating Reinforcement Learning for Autonomous Driving Using Task-Agnostic and Ego-Centric Motion Skills .....                        | 8610 |
| <i>Tong Zhou, Letian Wang, Ruobing Chen, Wenshuo Wang, Yu Liu</i>   |      |
| Probabilistic Traversability Model for Risk-Aware Motion Planning in Off-Road Environments.....   | 8618 |
| <i>Xiaoyi Cai, Michael Everett, Lakshay Sharma, Philip R. Osteen, Jonathan P. How</i>   |      |
| NeU-NBV: Next Best View Planning Using Uncertainty Estimation in Image-Based Neural Rendering .....                                       | 8626 |
| <i>Liren Jin, Xieyuanli Chen, Julius Rückin, Marija Popovic</i>   |      |
| ITIRRT: A Decoupled Framework for the Integration of Machine Learning into Path Planning.....   | 8634 |
| <i>Thibault Barbie, Shigeharu Mukai</i>   |      |
| Navigation Among Movable Obstacles Using Machine Learning Based Total Time Cost Optimization.....   | 8642 |
| <i>Kai Zhang, Eric Lucet, Julien Alexandre Dit Sandretto, David Filliat</i>   |      |
| Spatial Reasoning Via Deep Vision Models for Robotic Sequential Manipulation.....   | 8649 |
| <i>Hongyou Zhou, Ingmar Schubert, Marc Toussaint, Ozgur S. Oguz</i>   |      |

|   |      |
|---|------|
| SpeedFormer: Learning Speed Profiles with Upper and Lower Boundary Constraints Based on Transformer .....   | 8657 |
| <i>Kyuhwan Yeon, Hayoung Kim, Seong-Gyun Jeong</i>  |      |
| Stackelberg Meta-Learning for Strategic Guidance in Multi-Robot Trajectory Planning .....   | 8663 |
| <i>Yuhan Zhao, Quanyan Zhu</i>  |      |
| NaviSTAR: Socially Aware Robot Navigation with Hybrid Spatio-Temporal Graph Transformer and Preference Learning.....  | 8669 |
| <i>Weizheng Wang, Ruiqi Wang, Le Mao, Byung-Cheol Min</i>   |      |
| PTDRL: Parameter Tuning Using Deep Reinforcement Learning .....   | 8677 |
| <i>Elias Goldsztejn, Tal Feiner, Ronen Brafman</i>  |      |
| Hierarchical Transformer for Visual Affordance Understanding Using a Large-Scale Dataset.....   | 8684 |
| <i>Syed Afaq Ali Shah, Zeyad Khalifa</i>  |      |
| Traffic Incident Database with Multiple Labels Including Various Perspective Environmental Information.....   | 8690 |
| <i>Shota Nishiyama, Takuma Saito, Ryo Nakamura, Go Ohtani, Hirokatsu Kataoka, Kensho Hara</i>   |      |
| SeasonDepth: Cross-Season Monocular Depth Prediction Dataset and Benchmark Under Multiple Environments.....   | 8697 |
| <i>Hanjiang Hu, Baoquan Yang, Zhijian Qiao, Shiqi Liu, Jiacheng Zhu, Zuxin Liu, Wenhao Ding, Ding Zhao, Hesheng Wang</i>  |      |
| Exploring Visual Pre-Training for Robot Manipulation: Datasets, Models and Methods .....  | 8703 |
| <i>Ya Jing, Xuelin Zhu, Xingbin Liu, Qie Sima, Taozheng Yang, Yunhai Feng, Tao Kong</i>   |      |
| DORMADL - Dataset of Human-Operated Robot Arm Motion in Activities of Daily Living .....  | 8709 |
| <i>Felix Goldau, Yashaswini Shivashankar, Annalies Baumeister, Lennart Drescher, Patrizia Tolle, Udo Frese</i>  |      |
| IPA-3D1K: A Large Retail 3D Model Dataset for Robot Picking.....  | 8717 |
| <i>Jochen Lindermayr, Cagatay Odabasi, Florian Jordan, Florenz Graf, Lukas Knak, Werner Kraus, Richard Bormann, Marco F. Huber</i>  |      |
| EVOLIN Benchmark: Evaluation of Line Detection and Association .....  | 8725 |
| <i>Kirill Ivanov, Gonzalo Ferrer, Anastasiia Kornilova</i>  |      |
| Generating Scenarios from High-Level Specifications for Object Rearrangement Tasks .....  | 8733 |
| <i>Sanne Van Waveren, Christian Pek, Iolanda Leite, Jana Tumova, Danica Kragic</i>  |      |
| HANDAL: A Dataset of Real-World Manipulable Object Categories with Pose Annotations, Affordances, and Reconstructions .....   | 8741 |
| <i>Andrew Guo, Bowen Wen, Jianhe Yuan, Jonathan Tremblay, Stephen Tyree, Jeffrey Smith, Stan Birchfield</i>   |      |
| Understanding the Impact of Image Quality and Distance of Objects to Object Detection Performance.....  | 8749 |
| <i>Yu Hao, Haoyang Pei, Yixuan Lyu, Zhongzheng Yuan, John-Ross Rizzo, Yao Wang, Yi Fang</i>   |      |
| The Bystander Affect Detection (BAD) Dataset for Failure Detection in HRI .....   | 8756 |
| <i>Alexandra Bremers, Maria Teresa Parreira, Xuanyu Fang, Natalie Friedman, Adolfo Ramirez-Aristizabal, Alexandria Pabst, Mirjana Spasojevic, Michael Kuniavsky, Wendy Ju</i> |      |

|  |      |
|--|------|
| Few-Shot Segmentation and Semantic Segmentation for Underwater Imagery.....  | 8764 |
| <i>Imran Kabir, Shubham Shaurya, Vijayalaxmi Maigur, Nikhil Thakurdesai, Mahesh Latnekar, Mayank Raunak, David Crandall, Md Alimoor Reza</i>   |      |
| RACECAR - The Dataset for High-Speed Autonomous Racing.....  | 8771 |
| <i>Amar Kulkarni, John Chrosniak, Emory Ducote, Florian Sauerbeck, Andrew Saba, Utkarsh Chirimar, John Link, Madhur Behl, Marcello Cellina</i> |      |
| WIT-UAS: A Wildland-Fire Infrared Thermal Dataset to Detect Crew Assets from Aerial Views .....  | 8777 |
| <i>Andrew Jong, Mukai Yu, Devansh Dhrafani, Siva Kailas, Brady Moon, Katia Sycara, Sebastian Scherer</i>                                       |      |

#### **Author Index**