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Day 1: Tuesday March 2, 2021

System Modeling and Control

Chair: Ahmet Cetinkaya (National Institute of Informatics, Japan)

10:30-12:10 JST

Schedule	No.	Title	Authors
10:30-10:50	19	SARSA(0) Reinforcement Learning Over	Jihoon Suh (The University of Texas at Austin),
		Fully Homomorphic Encryption1	Takashi Tanaka (The University of Texas at
			Austin)
10:50-11:10	4	Modeling of Flow Rate Variation of	Jinhui Yang (Okayama University), Kentaro
		Tube PumpsN/A	Hirata (Okayama University), Yukinori
			Nakamura (Okayama University), Kunihisa
			Okano (Okayama University), Kenichi Kato
			(National Institute of Technology, Matsue
			College)
11:10-11:30	11	Learning Dynamic Systems Using Gaussian	Shengbing Tang (Kyoto University), Kenji
		Process Regression with Prior Information	Fujimoto (Kyoto University), Ichiro Maruta
		Given by Analytic ModelsN/A	(Kyoto University)
11:30-11:50	6	Pre-Evaluation for Experimental Verification	Futa Hayashida (Osaka Prefecture University),
		of Attitude Control of a Spacecraft with	Sayaka Kanata (Osaka Prefecture University),
		Double-Gimbal Variable-Speed Control	Takashi Shimomura (Osaka Prefecture
		Moment GyroN/A	University)
11:50-12:10	17	Path Tracking of Non-Holonomic	Padmini Singh (Indian Institute of Technology -
		Mobile Robot Using Event-Triggered	Kanpur), Subhash Chand Yogi (Indian Institute
		Control in Presence of Time and	of Technology - Kanpur), Laxmidhar Behera
		State-Dependent Uncertainties8	(Indian Institute of Technology - Kanpur),
			Nishchal kumar Verma (Indian Institute of
			Technology - Kanpur)

ISCS Invited Talk

Chair: Tomohisa Hayakawa (Tokyo Institute of Technology, Japan)

13:10-14:00 JST

Insoon Yang (Seoul National University, South Korea)

Title: Wasserstein Distributionally Robust Control and Optimization for Ambiguous Stochastic Systems

Network Control Systems

Chair: Hideaki Ishii (Tokyo Institute of Technology, Japan)

14:20-16:00 JST

Schedule	No.	Title	Authors
14:20-14:40	10	Distributed Event-Triggered Control for	Rajiv Kumar Mishra (Tokyo Institute of
		Discrete-Time Multi-Agent Average	Technology), Hideaki Ishii (Tokyo Institute of
		ConsensusN/A	Technology)
14:40-15:00	18	Two-Player Rolling Horizon Games	Yurid Nugraha (Tokyo Institute of Technology),
		for Jamming Attacks on Multiagent	Ahmet Cetinkaya (National Institute of
		SystemsN/A	Informatics), Tomohisa Hayakawa (Tokyo

			Institute of Technology), Hideaki Ishii (Tokyo
			Institute of Technology), Quanyan Zhu (New
			York University)
15:00-15:20	13	Leader-Following Coordination of	Rodolfo Pietrasanta (Politecnico di Torino), Elisa
		Heterogeneous Multi-Agent Systems Via	Capello (Politecnico di Torino), Yasumasa
		Displacement Feedback14	Fujisaki (Osaka Univ.)
15:20-15:40	14	Remote Fault Filtering and Control for	Ching-Min Lee (I-Shou University), Siang Jheng
		a Networked Control System with	(I-Shou University), Yi-Chen Lee (I-Shou
		Unreliable SensorsN/A	University)
15:40-16:00		-	-

Day 2: Wednesday March 3, 2021

MSCS Plenaries: Kimura-Award Commemorative Lecture

9:30-10:10 JST

Masaaki Nagahara (The University of Kitakyushu, Japan)

Title: Sparsity Methods for Systems and Control

Nonlinear Control Systems

Chair: Kenta Hoshino (Kyoto University, Japan)

10:30-12:30 JST

Schedule	No.	Title	Authors
10:30-10:50	8	Estimation of Fall History by Plantar	Midori Kawada (Ochanomizu University), Kanako
		Pressure During Walking Based on	Nakajima (National Institute of Advanced
		Auto Encoder and Principal Component	Industrial Science and Technology), Akio
		Analysis20	Sashima (National Institute of Advanced
			Industrial Science and Technology), Yuji Ohta
			(Ochanomizu University), Koichi Kurumatani
			(National Institute of Advanced Industrial
			Science and Technology)
10:50-11:10	9	Complex Obstacle Avoidance Control for	Masayuki Saito (Tokyo University of Science),
		a Mobile Robot Using Nonsmooth	Issei Tezuka (Tokyo University of Science),
		Control Barrier FunctionN/A	Hisakazu Nakamura (Tokyo University of
			Science)
11:10-11:30	16	Human Assist Control of Electric Wheelchair	Yudai Yamashita (Tokyo University of Science),
		by Using Control Barrier FunctionN/A	Tsubasa Sano (Tokyo University of Science),
			Hisakazu Nakamura (Tokyo University of
			Science)
11:30-11:50	7	Safe Control with Control Barrier Function	Aditya Wildan Farras (Tokyo Institute of
		for Euler-Lagrange Systems Facing Position	Technology), Takeshi Hatanaka (Osaka
		Constraint28	University)
11:50-12:10	3	Deep Unfolding-Based Output Feedback	Koki Kobayashi (Nara Institute of Science and
		Control Design for Linear Systems with	Technology), Masaki Ogura (Osaka University),
		Input Saturation33	Taisuke Kobayashi (Nara Institute of Science and
			Technology), Kenji Sugimoto (Nara Institute of
			Science and Technology)
12:10-12:30		-	-

Linear Control Theory

Chair: Yutaka Hori (Keio University, Japan)

13:30-15:30 JST

Schedule	No.	Title				Authors	i			
13:30-13:50	15	Impossibility	Results	for	Stochastic	Ahmet	Cetinkaya	(National	Institute	of
		Constrained				Informa	itics), Masako	Kishida (Na	itional Instit	tute
		ControN/Al				of Infor	matics)			
13:50-14:10	12	Robust Instability Radius for Multi-Agent			Shinji H	Hara (The University of Tokyo), Tetsuya				
		Dynamical Syste	ms with C	yclic S	StructureN/A	Iwasaki	(UCLA), Yuta	aka Hori (Kei	o University	y)

14:10-14:30	5	Blade Pitch Controller Design Based on	Meijiao Yu (Osaka Prefecture University),
		Model Reference Adaptive Control for	Naoyuki Hara (Osaka Prefecture University),
		Floating Offshore Wind TurbinesN/A	Keiji Konishi (Osaka Prefecture University)
14:30-14:50	21	A GPS Measurement-Based Map Conversion	Tua Agustinus Tamba (Parahyangan Catholic
		Scheme for Railway Synchronization	University), Yul Yunazwin Nazaruddin (Institut
		Control under Moving Block SignallingN/A	Teknologi Bandung), M. Brahma Waluya
			(Institut Teknologi Bandung), Ismail Faruqi
			(Institut Teknologi Bandung)
14:50-15:10	22	A PSO-Based Moving Target Defense Control	Tua Agustinus Tamba (Parahyangan Catholic
		Optimization Scheme46	University)
15:10-15:30		-	-