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| | | Pa |
|--|--|----|
| Welcome | | 1 |
| Paper | Authors | |
| Sunrise, Sunset and Temperature Now-cast model comparisons for local Safe Drone Flights Predictions | Riaan Stopforth and Shaniel Davrajh | |
| Electric Vehicle User Behaviour and Demand Response | Nithin Isaac | 9 |
| Shape tracing app for movement disorder detection | Vered Aharonson, Sarah Ward, David Rubin, David Anderson and Michiel Postema | 1 |
| The Similarity of Images Generated by Bag Context Shape Grammars | Blessing Ogbuokiri and Mpho Raborife | 2 |
| Performance evaluation of some facts placement methods for available transfer capability enhancement in a deregulated power networks | Babatunde Adewolu and Akshay Kumar Saha | 2 |
| Available transfer capability enhancement with facts: perspective of performance comparison | Babatunde Adewolu and Akshay Kumar Saha | 3 |
| Distributed Generation Interconnection with Improved Unified Power Quality Conditioner for Power Quality Mitigation | Osaloni Oluwole and Akshay Kumar Saha | 3 |
| Evaluation of performance index methodology for power network contingency ranking | Babatunde Adewolu and Akshay Kumar Saha | 4 |
| Transient Stability Analysis of a Grid-Integrated Wind Farm Under Fault Condition at the Point of Common Coupling | Edwin Tareka and Sunetra Chowdhury | 5 |
| Development of Solar Irradiation Forecast Confidence Intervals for Solar Electric Vehicle Energy Simulations | Christiaan Oosthuizen, Barend Jacobus Van Wyk, Yskandar Hamam, Yasser Alayli and Dawood Desai | 5 |
| Detecting inter-sectional accuracy differences in driver drowsiness detection algorithms | Mkhuseli Ngxande, Jules-Raymond Tapamo and Michael Burke | 6 |
| The effects of image smoothing on CNN-based detectors | Vusi Skosana and Mkhuseli Ngxande | 6 |
| Impact of Integrating Residential Solar PV Clusters on Voltage Profile in Urban Distribution Network | Tawanda Maseva and Sunetra Chowdhury | 7 |
| Energy management opportunities exploration in a residential air source heat pump water heater | Mandlenkosi Sikhonza, Stephen Tangwe and Michael Simon | 8 |
| A Comparative Analysis of Different MPC Controllers for Load Frequency Control for Interconnected Power System | Igbineweka Ernest Uyioghosa and Akshay Kumar Saha | 8 |
| DMPC Scheme on Load Frequency Control with Application to Interconnected Power System | Igbineweka Ernest Uyioghosa and Akshay Kumar Saha | 9 |
| An Analysis of the Method for Determining the Lowest Sensitivity of Solar-blind Ultraviolet Corona Cameras | Casper Coetzer, Sanet Groenewaldt and Wilhelm Leuschner | 9 |
| Overcurrent Protection Philosophy Using Microprocessor Based Relays For a South African Power Distribution Network | Lindokuhle Dlamini and Ali Hasan | 10 |

| Edwin Tareka and Sunetra Chowdhury |
|--|
| Anuoluwapo Oluwatobiloba Aluko, David Dorrell, Rudiren |
| Pillay Carpanen and Evans Ojo |
| I lilay Carpanen and Evans Ojo |
| Innocent Davidson |
| IIIIIocent Davidson |
| |
| Azka Zaheer, Muhammad Zeeshan and Muhammad Waqas |
| Khan |
| Talan |
| Oluwafemi Oni, Andrew Swanson and Rudiren Pillay |
| Carpanen |
| Tessa Hall and Herman Kamper |
| · · |
| Eduan Kotzé, Burgert Senekal and Walter Daelemans |
| <u> </u> |
| Peter Gbadega and Akshay Kumar Saha |
| |
| |
| |
| Alex Macfarlane, Theo van Niekerk and Udo Becker |
| |
| Daniel Rodrigues van Niekerk and Pitshou Bokoro |
| |
| Sarah Keartland and Terence van Zyl |
| |
| Samuel Ogunniyi, Daniel Withey, Stephen Marais and |
| |
| Gerrie Crafford |
| |
| Gerrie Crafford |
| Gerrie Crafford Matt Harcus and Glen Bright |
| Gerrie Crafford |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes |
| Gerrie Crafford Matt Harcus and Glen Bright |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert Sabourin |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert Sabourin Reghard Grobler and Willem Jordaan |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert Sabourin Reghard Grobler and Willem Jordaan Greig Swanepoel, George van Schoor, Kenny Uren and |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert Sabourin Reghard Grobler and Willem Jordaan Greig Swanepoel, George van Schoor, Kenny Uren and Johan Rens |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert Sabourin Reghard Grobler and Willem Jordaan Greig Swanepoel, George van Schoor, Kenny Uren and |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert Sabourin Reghard Grobler and Willem Jordaan Greig Swanepoel, George van Schoor, Kenny Uren and Johan Rens Warren Farmer and Arnold Rix |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert Sabourin Reghard Grobler and Willem Jordaan Greig Swanepoel, George van Schoor, Kenny Uren and Johan Rens |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert Sabourin Reghard Grobler and Willem Jordaan Greig Swanepoel, George van Schoor, Kenny Uren and Johan Rens Warren Farmer and Arnold Rix Rofhiwa Takalani and Bernard Bekker |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert Sabourin Reghard Grobler and Willem Jordaan Greig Swanepoel, George van Schoor, Kenny Uren and Johan Rens Warren Farmer and Arnold Rix |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert Sabourin Reghard Grobler and Willem Jordaan Greig Swanepoel, George van Schoor, Kenny Uren and Johan Rens Warren Farmer and Arnold Rix Rofhiwa Takalani and Bernard Bekker Andreas Liebenberg |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert Sabourin Reghard Grobler and Willem Jordaan Greig Swanepoel, George van Schoor, Kenny Uren and Johan Rens Warren Farmer and Arnold Rix Rofhiwa Takalani and Bernard Bekker |
| Gerrie Crafford Matt Harcus and Glen Bright Leonel Fanequico, John Van Coller and Chandima Gomes Erick Arwa and Komla Folly Ingrid Botha, Glen Bright and James Collins Anton Erasmus and Willem Jordaan Qin Chen and Komla Folly Aviwe Kohlakala and Johannes Coetzer Emile Beukes and Johannes Coetzer Johannes Coetzer, Jacques Swanepoel and Robert Sabourin Reghard Grobler and Willem Jordaan Greig Swanepoel, George van Schoor, Kenny Uren and Johan Rens Warren Farmer and Arnold Rix Rofhiwa Takalani and Bernard Bekker Andreas Liebenberg |
| |

| Comparison of Graphene Oxide and Reduced Graphene Oxide Doping on YBCO For Power Applications Human eye inspired log-polar pre-processing for neural networks Theoretical 3-D Monitoring System for Human-Robot Collaboration Mohammed Gaffoor, Alan Lawrence Leigh Jarvis and Sol Perumal Leendert Remmelzwaal, Amit Mishra and George Ellis Mishkar Bhana and Glen Bright |
|--|
| Applications Human eye inspired log-polar pre-processing for heural networks Theoretical 3-D Monitoring System for Human-Robot Mishkar Bhana and Glen Bright |
| Human eye inspired log-polar pre-processing for heural networks Theoretical 3-D Monitoring System for Human-Robot Mishkar Bhana and Glen Bright |
| Theoretical 3-D Monitoring System for Human-Robot Mishkar Bhana and Glen Bright |
| |
| PD Magnitude Variation with Voltage in Single Cavity Isaac Kyere, Cuthbert Nyamupangedengu and Jerry Wall and Double Cavities |
| Quantisation and Pruning for Neural Network Compression and Regularisation Kimessha Paupamah, Steven James and Richard Klein |
| Evaluation of the Behaviour of HFCTs for Corona Herry Sibanyoni, Jerry Walker and Jules Djeumen Measurement under HVDC Application |
| A Software Defined Approach for Improving Resilience on Smart Distribution Grids Gerhard Brown, Neco Ventura and Joyce Mwangama |
| Review of Sequential Steps to Realize Power System Resilience. Okeolu Samuel Omogoye, Komla Folly and Kehinde Awodele |
| nter- and Intra-domain Knowledge Transfer for Nishai Kooverjee, Terence van Zyl and Steven James |
| Related Tasks in Deep Character Recognition |
| Detection of electricity theft in low voltagenetworks using analytics and machine learning Mabatho Hashatsi, Chizeba Maulu and Mercy Shuma-Iwi |
| A Prediction Model to Improve Student Placement at a South African Higher-Education Institution |
| Harmonic Emission of Non-Linear Loads in Distribution Systems – A Computer Laboratory Case Study |
| Sentiment Analysis as an Indicator to Evaluate Gender Jude Oyasor, Mpho Raborife and Pravesh Ranchod |
| disparity on Sexual Violence Tweets in South Africa |
| Comparison of Recurrent Neural Network Rylan Perumal and Terence van Zyl |
| Architectures for Wildfire Spread Modelling |
| Review and comparison of the South African grid code equirements for wind generation with the European countries grid code |
| The Impact of Water Surface Albedo on Incident Solar Shahina Salim Patel and Arnold Johan Rix nsolation of a Collector Surface |
| OC Power Quality Emulator Riekert Jansen van Vuuren and Gerhard Botha |
| oad models for technical and tariff analysis of Lolo Johannes Buys and Trevor Gaunt nedium voltage feeders |
| nvestigating the performance of an R-Criterion based protection method when applied on PV Solar microgrid |
| Autonomous Landing of a Multirotor Aircraft on a Docking Station Benjamin Nelson, Jacques Du Preez, Theo van Niekerk, Russell Phillips and Riaan Stopforth |
| Influence of Supply Voltage Frequency on Cavity Partial Discharge Parameters: Simulation Results |
| Building Undirected Influence Ontologies Using Pairwise Similarity Functions Tamlin Love and Ritesh Ajoodha |
| Archiving 4.0: Application of Image Processing and Daria Kern, Manuel Zweng, Stanley Sello, Antoine Bagula |
| Machine Learning for the Robben Island Mayibuye Archives |
| Assessment of the Cup-to-Disc ratio method for Afolabi Oluwatobi, Gugulethu Mabuza-Hocquet and |
| Slaucoma detection Fulufhelo Nelwamondo |
| Context-Aware Action with a Small Mobile Robot Daniel Withey, Katlego Mogokonyane, Mayur Tikam, Ros Holder, Mahalingam Veeraragoo and Mxolisi Gambushe |
| Haptic System Interface Design and Modelling for Syeda Nadiah Fatima Nahri, Shengzhi Du and Barend |
| Bilateral Teleoperation Systems Jacobus Van Wyk nvestigation of Diverse Sampling Time for LFC of Milan Joshi, Gulshan Sharma and Innocent Davidson |
| |

| Frequency Regulation Studies of Interconnected PV | Milton Estrice, Gulshan Sharma, Kayode Timothy Akindeji |
|---|---|
| Thermal Power System | and Innocent Davidson |
| Combining primitive DQNs for improved reinforcement | Matthew Reynard, Herman Engelbrecht, Herman Kamper |
| earning in Minecraft | and Benjamin Rosman |
| Modelling of Wind Turbine Power Curves (WTPCs) | Arman Goudarzi and Farzad Ghayoor |
| Based on the Sum of the Sine Functions and Improved | · |
| version of Particle Swarm Optimization (IPSO) | |
| , | |
| Fransmission Line Damping Effects on Power System | Michael Rainey and David Oyedokun |
| nertia Response | , , |
| ractional Order Internal Model Control Strategies for | Isabela Birs, Cristina Muresan and Ioan Nascu |
| a Submersed Nanorobot | , - |
| Removal of Nuisance Signals in Electric Grid | Rastko Zivanovic |
| Disturbance Data | |
| Reinforcement Learning-based Control System of a | Francisca Daniel and Arnold Rix |
| Hybrid Power Supply | Translessa Barrior and 7 arrora 1 and |
| nvestigating the Impact of HVDC on the Damping | Christophe Basila Tambwe and Rudiren Pillay Carpanen |
| Subsynchronous Resonance | Officiophio Busha Fambwo ana Fadanon Finay Garpanon |
| Generation of metrics by semantic segmentation of | Jason Smit, Hugh Hunt, Tyson Cross, Carina Schumann |
| nigh speed lightning footage using machine learning | and Tom Warner |
| ngn speed ngmining lootage using machine learning | and Tolli VVallici |
| Application of Active Filters for Distribution Naturals | Alaba Ojo, Kehinde Awodele, Adoniya Sebitosi and Mdu |
| Application of Active Filters for Distribution Network | |
| Performance Enhancement | Mzulwini Dillan Ockhuis and Maarten Kamper |
| mpedance Matching of Direct Grid-Connected | Dilian Ookhuis ahu waanen Kamper |
| Renewable Energy Synchronous Generators | Corol Landman and Arnold Johan Div |
| Jsing cloud cover forecasts for estimating a solar | Carel Landman and Arnold Johan Rix |
| powered vehicles' range. | I Image Attai Abu Karala Fallis Israhasi I |
| Echo State Network (ESN) Based Generator Speed | Umar Attai Abu, Komla Folly, Iroshani Jayawardene and |
| Prediction of Wide Area Signals in a Multimachine | Ganesh Kumar Venayagamoorthy |
| Power System | |
| Comparison of grounding methods for utility scale PV | Herme Charles Smit and Arnold Johan Rix |
| plants. | |
| mage processing-based identification of dicentric | Sarah Galloway, Johannes Coetzer and Neil Muller |
| chromosomes in slide images | |
| Jse of Electrical Energy Storage to Improve the | Ziphezinhle Kazi, Kehinde Awodele, Bongane Nhlapo and |
| /oltage Stability of a Power System with Large | Adeyinka Adebayo |
| Amount of Wind Generation | |
| A review on the use of Recommendation and Value | Emmanuel Nxumalo and Kehinde Awodele |
| Estimation Systems to determine Protection Based | |
| Distributed Generation Penetration Limits | |
| | |
| An Experimental Investigation Of 3D Printed Cold Gas | Daniel Jansen, Lourens Visagie and Willem Jordaan |
| Thruster Nozzles | |
| mproving Unsupervised Acoustic Word Embeddings | Lisa van Staden and Herman Kamper |
| ising Speaker and Gender Information | ' |
| <u> </u> | |
| ine Reactance Criteria for Minimizing Line Current | Maarten Kamper, Christopher Africa, Hannes Labuschagne |
| Harmonic Content in Diode Rectifier Connected Wind | and Lethiwe Mdakane |
| Generator Systems | |
| Learning Options from Demonstration using Skill | Matthew Cockcroft, Shahil Mawjee, Steven James and |
| Segmentation | Prayesh Ranchod |
| Effect of flake size of natural graphite precursor on | |
| | Solan Perumal, Alan Lawrence Leigh Jarvis and |
| graphene oxide supercapacitor for energy storage | Mohammed Gaffoor |
| Jser Classification by Keystroke Dynamics using Text | Thato Mokoena and Deon Sabatta |
| Retrieval Methods | Em E 1 1 1 2 1 1 1 1 1 1 |
| Optical Monitoring of Pollution on MV Bushings | Filipe Fernandes, John Van Coller and Nishal Mahatho |
| Circular Interpolation Techniques towards Accurate | Norman Nelufule, Gugulethu Mabuza-Hocquet and Anton de |
| Segmentation of Iris Biometric Images for Infants | Kock |
| - | |
| The Effect of Thermal Transient on the Leakage | Ayanda Dlamini, Pitshou Bokoro and Wesley Doorsamy |
| | |

| Deep Learning and Transfer Learning applied to Sentinel-1 DInSAR and Sentinel-2 optical satellite imagery for change detection | Zainoolabadien Karim and Terence Van Zyl |
|--|---|
| Investigating the Effects of Creepage Discharges on the Breakdown Voltage of Natural Ester Oil | Bakhekile Ndlovu and Cuthbert Nyamupangedengu |
| Impregnated Pressboard in Power Transformers Sunspot Identification and Tracking with OpenCV | Ruben du Toit, Gunther Drevin, Nicolaas Maree and Du Toit Strauss |
| Design of a 90 W Low Cost Solar Emulator for Testing MPPT Algorithms on PV Based Energy Systems | Tristan Kuisis, Muhammed Aswat, Willem Cronje and Ken Nixon |
| A Review of Power System Instability Prediction Methods Using Phasor Measurement Unit Data | Teboho Machabe, Ellen de Mello Koch and Ken Nixon |
| Design and Construction of a Smart Meter for DC Energy Trading in Rural Environments | Willem Cronje, Vincent Matlou and Milliscent Mufunda |
| Review of Control Strategies for Lithium-ion Battery Energy Storage Systems in Distribution Networks | Johann Bierman and Bernard Bekker |
| Optimization of reactive power under load uncertainty | Oliver Dzobo |
| Dissolved Gases Analysis of canola-based ester oil under creepage discharge | Hlengiwe Mnisi |
| Investigation of Corona Partial Discharge at Variable Applied Frequency | Thandeka Khumalo, Zakhele Skosana and Cuthbert Nyamupangedengu |
| SCADA and Substation Automation Systems for the Port of Durban Power Supply Upgrade | Siphokazi Mnukwa and Akshay Kumar Saha |
| An Investigation Into an Appropriate optical Calibration Source for a Corona Camera | Casper Coetzer, Nicholas West, Andrew Van Tonder and Andre Swart |
| A Self-Driving Car Architecture in ROS2 | Michael Reke, Daniel Peter, Joschua Schulte-Tigges, Stefar Schiffer, Alexander Ferrein, Thomas Walter and Dominik Matheis |
| Hindsight Reward Shaping in Deep Reinforcement Learning | Byron de Villiers and Deon Sabatta |
| A Review of the Impact of Integrating Wind Generation on Transient Stability | Siyanda Ncwane and Komla Folly |
| Learning fine-grained control for mapless navigation | Fred De Villiers and Willie Brink |
| Preliminary analysis of the impact of design-stage uncertainties on the performance of microgrids | Daniello Mouton and Bernard Bekker |
| Preliminary Study of Fault Detection on an Islanded Microgrid Using Artificial Neural Networks | Itani Phafula, Ellen De Mello Koch and Ken Nixon |
| End-to-End Text-To-Speech synthesis for under resourced South African languages | Thapelo Nthite and Mohohlo Tsoeu |
| Real-Time Optimization Method for Complimentary Filter using Signal-to-Noise Ratio Maximization | Winston Dyason, Riaan Stopforth, Theo van Niekerk and Russell Phillips |
| Estimating financial viability of behind-the-meter peak shaving based on load profile shape: a shopping mall case study | Johannes Mostert and Bernard Bekker |
| Development of a low cost rotor position sensor | Sidwell Nkosi, Lloyd Patsika and Lesedi Masisi |
| Comparison of DC voltage control strategies for multi- terminal HVDC network during AC faults. | Sindisiwe C. Malanda, Innocent Davidson and Grain P Adam |
| Batch construction and multitask learning in visual relationship recognition | Shane Josias and Willie Brink |
| Characterisation of the primary heat replacement element event for a horizontal electric water heater | Tyron Reddy, Sewpersad and Yen |
| Variable Speed Drive dc-link ride-through improvement using switched capacitors | Freeman Chiranga and Lesedi Masisi |
| Thin Film Photovoltaic Module Characterisation Based in Indoor and Outdoor Methods | Siyasanga Innocent May, Lawrence Pratt and Pitshou Bokoro |
| Load and energy profile developments using occupancy and interactions/activities in the residential | Agnes Ramokone, Olawale Popoola and Ayodele Temitope |

| Balancing between Demand and Trading in Microgrids | Masimba Gomba |
|---|--|
| Preliminary Tests on the Suitability of the Beta PDF to | Munyaradzi Justice Chihota and Bernard Bekker |
| Model the Residential Load for New Planning | manyaradzi odolioo omnota ana Bornara Bornar |
| Applications | |
| | Emmanuel Raubenheimer, Tlotlollo Hlalele and Adedayo |
| transmission lines | Yusuff |
| 3D Pose Estimation and Tracking of an Electricity | Emmanuel Ali and Fred Nicolls |
| Pylon | |
| A Study into the Effect of Current Harmonics on the | Bonginkosi Thango, Jacobus Jordaan and Agha Francis |
| Maximum Loading Capability of Transformers within | Nnachi |
| Solar Power Plants | |
| A Review on the Condition Monitoring and Fault | Ester Hamatwi and Paul Barendse |
| Diagnosis of Stator and Rotor Interturn Winding Faults | |
| in a DFIG-based Wind Turbine System | |
| Short-Term Load Forecasting using Minimalistic | Evan Weyermüller, Hendrik Vermeulen and Matthew Groch |
| Adaptive Neuro Fuzzy Inference Systems | , , , |
| Challenges of Planning Future High Voltage Power | Vasu Chetty and Innocent Davidson |
| Systems Networks | , |
| Comparative Analysis of Load Compensation | Anesuishe Nyanjowa, Kehinde Awodele and Alaba Ojo |
| Techniques in Low-Voltage Distribution Networks | 7 7 . |
| Using Passive Components | |
| Power Quality Evaluation of Electrical Loads in a | Tshwanelo Mathwai, Kehinde Awodele and Alaba Ojo |
| Typical Commercial Building | , |
| The Ollie: A Case Study in Trajectory Optimization with | Nicholas Anderson, Stacey Shield and Amir Patel |
| Varied Contacts | , , |
| Impedance Behavioural Study of Silicon Steel | Chigozie Boniface and Paul Barendse |
| Laminated Core Inductor | , and the second |
| Automatic classification of medical X-ray images with | Xolisani Nkwentsha, Anicet Hounkanrin and Fred Nicolls |
| convolutional neural networks | |
| Transformer models and meters in MATLAB and | Pitambar Jankee, Hilary Chisepo, Victor Adebayo, David |
| PSCAD for GIC and leakage dc studies | Oyedokun and Trevor Gaunt |
| Frequency Components of Geomagnetically Induced | David Oyedokun, Michael Heyns, Pierre Cilliers and Ct |
| Currents for Power System Modelling | Gaunt |
| Development of a Cost-effective Solar/Wind/Fuel-cell | Tshilidzi Ramunenyiwa, Kehinde Awodele and Okeolu |
| Independent Power Plant for a Remote Base | Samuel Omogoye |
| Transceiver Station | |
| Real-Time Simulation of Power System Wide Area | Bright Tetteh, Kehinde Awodele and Komla Folly |
| Protection | |
| Realtime Thévenin Equivalent Impedance at a PCC in | George Gabriels, David Oyedokun and Simona Ruggeri |
| the Italian Power Grid | |
| Active Distribution System State Estimation on | Jeff Watitwa and Kehinde Awodele |
| Modified IEEE 33 bus test system | |
| On the Effectiveness of Silly Walks as Initial Guesses | Stacey Shield and Amir Patel |
| for Optimal Legged Locomotion Problems | |
| | |
| Development and automation of a 12 kW-capacity | Ilesanmi Daniyan, Lanre Daniyan, Adefemi Adeodu and |
| gasifier for energy generation | Osazele Momoh |
| Sub-Synchronous Resonance (SSR) in Series | Tinashe Chikohora and David Oyedokun |
| Compensated Networks with High Penetration of | |
| Renewable Energy Sources | |

Additional Paper:

Quasi-Serial Manipulator - Inverse Kinematics and Workspace Analysis for Industrial Automation

Bryan Kelly, J Padayachee and G Bright