2019 16th Workshop on Positioning, Navigation and Communications (WPNC 2019)

Bremen, Germany 23 – 24 October 2019



IEEE Catalog Number: ISBN: CFP1993B-POD 978-1-7281-2083-6

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IEEE Catalog Number:	CFP1993B-POD
ISBN (Print-On-Demand):	978-1-7281-2083-6
ISBN (Online):	978-1-7281-2082-9
ISSN:	2164-9758

Additional Copies of This Publication Are Available From:

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Day 1 - 23th of October 2018 IRC Conference Room – Jacobs University Bremen

08:30 - 12:00	Registration
	Located inside the conference room and operational continuously from 8:30 to 12:00.
08:50 - 09:00	Welcome and Opening Message
	Giuseppe Abreu, Jacobs University Bremen Sven Zeisberg, Dresden University of Applied Sciences Valérie Renaudin, IFSTTAR Jérrôme Härri, Eurecom
KEYNOTE	Invited Keynote Talk
09:00 - 9:50	Robot Localization in Challenging Environments
	Prof. Dr. Francesco Maurelli, Jacobs University Bremen, Germany
SESSION 1	Positioning in 5G Networks Chair: Prof. Dr. Giuseppe Abreu
09:50 - 10:10	S1P1: Enabling Angle-based Positioning to 3GPP NR Systems Yi Wang, Huawei Technologies Co., Ltd; Zhenyu Shi, Huawei Technologies Co., Ltd; Yingjie Yu, Huawei Technologies Co., Ltd; Su Huang, Huawei Technologies Co., Ltd; Lei Chen, Huawei Technologies Co., Ltd
10:10 - 10:30	S1P2: 5G Positioning -A Machine Learning Approach Magnus E Malmström, Linköping University; Isaac Skog, Linköping University; Sara Modarres Razavi, Ericsson Research; Yuxin Zhao, Ericsson Research; Fredrik Gunnarsson, Ericsson Research
10:30 - 10:50	S1P3: High Precision Synchronization between Commercial WiFi-ICs and External Device Alexey M. Romanov, RTU MIREA; Francesco Gringoli, Università degli Studi di Brescia; Axel Sikora, Offenburg University of Applied Sciences
10:50 - 11:10	S1P4: A New Position Quality Metric for NR RAT Dependent OTDOA Positioning Method Ritesh Shreevastav, Ericsson; Giuseppe Destino, King's College Londo; Deep Shrestha, Ericsson; Iana Siomina, Ericsson; Toktam Mahmoodi, King's College London
11:10 - 11:30	Coffee Break (20 mins)
	Coffee, tea and other drinks served along with fruits, cookies and more.
SESSION 2	Advanced Algorithms for Positioning and Ranging Chair: Prof. Dr. Francesco Maurelli
11:30 - 11:50	S2P1: Statistical Analysis of Noise in Triaxial Magnetometers and Calibration Procedure Nhan D Nguyen, Tampere University; Philipp Müller, Tampere University;
	Jussi Collin, Tampere University



11:50 - 12:10	S2P2: Indoor distance estimation using LSTMs over WLAN network
	Pranav M Sankhe, IIT BOMBAY; Saqib Azim, IIT BOMBAY; Sachin Goyal, IIT BOMBAY; Tanya Choudhary, IIT BOMBAY; Kumar Appaiah, IIT BOMBAY; Srikant Sukumar, IIT BOMBAY
12:10 - 12:30	S2P3: Detection of Feature Areas for Map-based Localization Using LiDAR Descriptors
	Constanze Hungar, Volkswagen AG; Jenny Fricke, Volkswagen AG; Stefan Jürgens, MAN Truck & Bus AG; Frank Köster DLR e.V.
12:30 - 12:50	S2P4: Robust Elliptic Localization using Worst-Case Formulation and Convex Approximation
	Wenxin Xiong, University of Freiburg; Hing Cheung So, City University of Hong Kong; Christian Schindelhauer, University of Freiburg; Johannes Wendeberg, University of Freiburg
12:50 - 13:50	Lunch Break
	Lunch at one of the serveries at Jacobs Campus (voucher included with registration)
13:50 - 14:00	Pre-session Coffee (10 mins)
	Coffee, tea and other drinks served along with fruits, cookies and more.
SESSION 3	Coffee, tea and other drinks served along with fruits, cookies and more. Positioning in IoT and Industrial Networks Chair: Dr. Igor Dotlic
SESSION 3 14:00 - 14:20	Positioning in IoT and Industrial Networks
	Positioning in IoT and Industrial Networks Chair: Dr. Igor Dotlic S3P1: A Reproducible Comparison of RSSI Fingerprinting Localization Methods Using LoRaWAN Grigorios G. Anagnostopoulos, Geneva School of Business Administration, HES-SO Geneva;
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15:20 – 15:40	Coffee Break (20 mins)
	Coffee, tea and other drinks served along with fruits, cookies and more.
SESSION 4	UWB Positioning and Ranging Chair: Florian Wolf
15:40 - 16:00	S4P1: Localization and communication resource budgeting for multi-user mm-Wave MIMO
	Remun Koirala, CEA Leti; Benoit Denis, CEA-Leti; Bernard Uguen, University of Rennes 1 - IETR, France; Davide Dardari, DEIS-University of Bologna, Italy; Henk Wymeersch, Chalmers Univ. of Techn., Sweden
16:00 - 16:20	S4P2: Periodic Ambiguity Function as a Tool in Designing Periodic Synchronization Preamble
	Igor Dotlic, Decawave
16:20 - 16:40	S4P3: A Comparative Study of UWB-based True-Range Positioning Algorithms using Experimental Data
	Cung Lian Sang, Bielefeld University; Michael Adams, Bielefeld University; Marc Hesse, Bielefeld University; Timm Hörmann, Bielefeld University; Timo Korthals, Bielefeld University; Ulrich Rückert, Bielefeld University
16:40 - 17:00	S4P4: Modeling the Magnitude and Phase of Multipath UWB Signals for the Use in Passive Localization
	Marco Cimdins, Technische Hochschule Luebeck - University of Applied Sciences; Sven Ole Schmidt, Technische Hochschule Luebeck - University of Applied Sciences; Horst Hellbrück, Technische Hochschule Luebeck - University of Applied Sciences
SPECIAL SESS	ION WPNC Traditional Beer Session with Exhibitors
	2019 Awards Announcements
17:00 - 19:00	Take advantage of the opportunity to discuss further with your colleagues and industry exhibitors while enjoying free beer and snacks!



Day 2 - 24th of October 2018 IRC Conference Room – Jacobs University Bremen

08:30 - 10:30	Registration
	Located inside the conference room and operational continuously from 8:30 to 10:30.
09:00 - 09:10	Morning Message and Housekeeping Information
	Giuseppe Abreu, Jacobs University Bremen
SESSION 5	Positioning for Navigation and Robotics Chair: Dr. Valérie Renaudin
09:10 - 09:30	S5P1: Location Privacy Preservation and Location-based Service Quality Tradeoff Framework Based on Differential Privacy
	Tianyi Feng, National University of Singapore; Wai Choong Wong, National University of Singapore; Sumei Sun, Institute for Infocomm Research, A*STAR; Yonghao Zhao, National University of Singapore; Zhixiang Zhang, National University of Singapore
09:30 - 09:50	S5P2: System-level Simulation of Cooperative Sensor Data Fusion Strategies for Improved Vulnerable Road Users Safety
	Alex P Da Silva, CEA-LETI; Imane Horiya Brahmi, CEA-LETI; Sylvain Leirens, CEA-LETI; Benoit Denis, CEA-Leti
09:50 - 10:10	S5P3: Multi-Mode Antenna Enabled Direction-of-Arrival Estimation for Swarm Navigation
	Robert Pöhlmann, German Aerospace Center (DLR) ; Gonzalo Pedregosa, German Aerospace Center (DLR) ; Stefano Caizzone, German Aerospace Center (DLR) ; Emanuel Staudinger, German Aerospace Center (DLR); Peter A. Hoeher, Faculty of Engineering, University of Kiel
10:10 - 10:30	S5P4: 3D Performance Analysis of a UWB Positioning System in a Dynamic Robotic Scenario
	Markus Pichler-Scheder, Linz Center of Mechatronics GmbH; Klaus Pendl, Linz Center of Mechatronics GmbH; Richard Schmidt, Linz Center of Mechatronics GmbH; Michael Petruzelka, KEBA AG; Günther Mühlberger, KEBA AG
10:30 - 10:50	Coffee Break (20 mins)
	Coffee, tea and other drinks served along with fruits, cookies and more.



SESSION 6	High-precision Positioning and Ranging Chair: Prof. Dr. Giuseppe Abreu
10:50 - 11:10	S6P1: Precise Probabilistic Grid Positioning based on GNSS Pseudoranges and Digital Elevation Models
	Paul Schwarzbach, TU Dresden; Andrea Jung, TU Dresden; Richard Weber, TU Dresden; Oliver Michler, TU Dresden
11:10 - 11:30	S6P2: Efficient Use of SSR RTCM Streams For Real-Time Precise Point Positioning on Smartphones
	Antoine Grenier, IFSTTAR; Valérie Renaudin, IFSTTAR, France
11:30 - 11:50	S6P3: A 400 Msps SDR platform for prototyping accurate wideband ranging techniques
	Cherif Diouf, TU DELFT; Tarik Kazaz, TU DELFT; Gerard Janssen, TU DELFT; Han Dun, TU DELFT; Farnaz Chaman Zadeh, TU DELFT; Christiaan Tiberius, TU DELFT
11:50 – 12:10	S6P4: Comparative Examination of Iterative and Non-Iterative Algorithms for Partial Discharge Location Approximation in High Voltage Equipment
	Máté Szirtes, Budapest University of Technology and Economics; Richárd Cselkó, Budapest University of Technology and Economics
12:10 - 12:20	Closing Words
	Giuseppe Abreu, Jacobs University Bremen Sven Zeisberg, Dresden University of Applied Sciences Valérie Renaudin, IFSTTAR Jérrôme Härri, Eurecom
12:20 - 14:00	Lunch Break
	Lunch at one of the serveries at Jacobs Campus (voucher included with registration)