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Cognitive and Action Control for Goal-Directed Reaching in a Humanoid Robot 1868
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Geometry of Gaudi-inspired Screw and Nut for Differential Drive Mechanism 1900
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Stability Analysis and Optimization on Conical Cylinder Block in Swash Plate Piston Pumps 1906
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Design and optimal springs stiffness estimation of a Modular OmniCrawler in-pipe climbing Robot 1912
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A Hybrid and Compact Spherical Mechanism of Large Workspace and Output Torque with Unlimited Torsion for Hand-Held Gimbal 1918
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Autonomous Navigation of a Quadrotor in Unknown Environments 1930
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A strategy for mid-air collision avoidance: Speed modulation to increase minimum separation using a mutually independent and mutually beneficial technique 1936
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A Hierarchical Decision-making Algorithm of UAV for Collision Avoidance in Target Tracking 1944
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Motion Description Language for Trajectory Generation of a Robot Manipulator 1950
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Motion Planning of Lower Limb Exoskeleton with Passive Anklefor Paraplegics 1956
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Generalization of Task Model using Compliant Movement Primitives in a Bimanual Setting 1967
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Mechanical design and analysis of a novel dexterous hand based on grasping manipulation 1973
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Tracking of Trajectory with Dynamic Deformation Based on Dynamic Compensation Concept 1979
Kenta Kajihara, Shouren Huang, Niklas Bergstrom, Yuji Yamakawa, Masatoshi Ishikawa

Geometric Isotropy Indices for Workspace Analysis of Spatial Parallel Manipulators 1985
Hao Xiong, Xiumin Diao

Design and experimental study of compliant joints of robot based on magneto-rheological fluid 1991
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An Optimized Cooperative Control Algorithm of Multi-Agent Array Based on the Skeletal Mechanism of Chrysopelea 2003
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Cycle Stability and Consumption Energy Efficiency Evaluation of Walking Stabilized by Stepping Feedforward and Visual-lifting Feedback 2009
Keli Shen, Xiang Li, Daiji Izawa, Mamoru Minami

Online Generation of Collision-free Trajectories for Multiple Robots in A Shared Workcell 2015
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Modelling and Control of Dual-Arm Free-Floating Space Robot Using Virtual Decomposition Control for Capturing Target 2021
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