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Table of Contents

MA1-P	Poster Session (Intelligent Mechatronics and Automation)	
	Research on Spacecraft Assembly System Integration Based on PLM	1
	<i>Han, Xinglong; Li, Manli</i>	
	Adaptive RBFNN Fuzzy Sliding Mode Control for Active Power Filter	6
	<i>Wang, Tengting; Fei, Juntao</i>	
	A Spatial Scheduling Strategy for Irregular Workplace in Shipbuilding	12
	<i>Ge, Yan; Wang, Aimin; Cheng, Jincheng</i>	
	Research of PMSM Fuzzy Direct Torque Controller Based on Sliding Mode Observer	17
	<i>Gao, Ya; Gao, Yi</i>	
	Research and Implementation of SVPWM Control Algorithm Based on FPGA	22
	<i>Liang, Xuexiu; Luo, Min; Zhao, Bo; Yuan, Yanwei; Chen, Zhi</i>	
	The Influence of Magnetic Field on Losses of High-Speed Permanent Magnet Motor	27
	<i>Chen, Duo; Feng, Ming</i>	
	Realization of Drill Rectifying Control for Coal Shearer Based on An Improved PID Algorithm	32
	<i>Liu, Ting; Du, Yuxin; Tong, Minming; Zhang, Dan</i>	
	Investigation of a Target Reachability by a Manipulator in an Unknown Environment	37
	<i>Lopatin, Pavel</i>	
	The Evaluation of a Novel Force Feedback Interventional Surgery Robotic System	43
	<i>Guo, Shuxiang; Peng, Weili; Xiao, Nan; Wang, Yuan; Xu, Changqi; Li, Guangxuan</i>	
	Structural Design and Stiffness Analysis of the Robot Bound Planes	50
	<i>Shao, Junpeng; Gao, Yuanfeng; Gao, Bingwei</i>	
	Study on Movement Stability for the Spherical Amphibious Robot	55
	<i>Guo, Jian; Wu, Guoqiang; Guo, Shuxiang</i>	
	An Investigation on the Static Performance of Hydrodynamic Wave Journal Bearings	61
	<i>Yang, Baisong; Geng, Haipeng; Qi, Shemiao; Zhou, Jian; Zhuo, Ming; Yu, Lie; Xiong, Ling</i>	
	Sparse Fusion Based on SAM Elective Sample Dictionary Establishment	68
	<i>Sun, Xiaofang</i>	

Design and Implementation of Intelligent Decision-Making System Software for Industrial Circulating Cooling Water	73
<i>Wang, Tieqiang; Li, Junfang; Liu, Mingyuan; Gao, Qiang; Yang, Junxiang</i>	
Application of Improved DPCA to Distillation Column Process Monitoring	78
<i>Yang, Junxiang; Li, Dong; Gao, Qiang</i>	
Remote Tracking of Nonholonomic Mobile Robots via Networked Predictive Control	84
<i>Zhang, Tianyong; Liu, Guoping</i>	
Research on Hydro-oscillator for Petroleum Drilling Engineering	90
<i>Yang, Zenghui; Yi, Xianzhong; Liu, Hangming; Yi, Hongyu; Deng, Zhiyong; Wei, Shizhong; Jiang, Shengzong</i>	
Development of a CMOS Driving Circuit with Compensation Function for Gyroscope Applications	95
<i>Chiang, Cheng-Ta; Huang, You-Hong</i>	
Improve Assembly Line Balancing by Changing Cycle Time	100
<i>Chao, Yongsheng; Sun, Wenlei</i>	
The Discussion on Static Synchronous Compensator Technology	106
<i>Ma, Youjie; Gao, Luwen, ; Zhou, Xuesong; Gao, Zhiqiang</i>	
Study on Process and Performance of Laser Heating Assisted Micro Cutting of Alumina Ceramics	112
<i>Xu, Jinkai; Xu, Zhe; Chu, Chuanpeng; Wang, Zhichao; Yu, Huadong</i>	
A Novel Heading Predictive Control Model for Autonomous Ground Vehicles	117
<i>Zhou, Junjie; Tang, Shouxing; Li, Xueyuan; Yin, Xufeng</i>	
Research on Linear Sparse Sonar Array for Targets Azimuth Bearing Estimation	122
<i>Zhang, Hongmei; Sun, Xiwei; Chen, Mingjie</i>	
Self-Calibration of a 6-DOF Redundantly Actuated Parallel Mechanism	128
<i>Gao, Changhong; Cong, Dacheng; Han, Junwei ; Yang, Zhidong; Wang, Xiao</i>	
The Design and Implementation of the Voice Control System of Smart Home based on IOS	133
<i>Wang, Yunliang; Dong, Peng</i>	
Modelling of the Finishing Allowance of Optical Surfaces and its Application in Material Removal	139
<i>Yang, Xu; Liu, Chang; Zheng, Haisheng; Qu, Xingtian</i>	
Research on Control scheme of Dual-Spin Projectile with Fixed Canards	144

<i>Zhang, Yanru; Li, Peng; Xiao, Liangang; Tian, Feng</i>	
Surface Defect Analysis of Rotary Metal Parts	149
<i>Zhou, Awei; Shao, Wei</i>	
The Review of Smart Distribution Grid	154
<i>Ma, Youjie; Tong, Xin; Zhou, Xuesong; Gao, Zhiqiang</i>	
Research Review on Energy Storage Technology	159
<i>Ma, Youjie; Yang, Peilin; Zhou, Xuesong; Gao, Zhiqiang</i>	
Simulation and Experiment on the Serial-parallel Leg of a Novel Quadruped Walking Robot	165
<i>Gao, Jianshe; Wang, Yuchuang; Liu, Deping; Zuo, Weilong</i>	
Application of Modified Kalman Filtering Restraining Outliers Based on Orthogonality of Innovation to Track Tester	171
<i>Zhang, Xinchun; Cui, Ximin; Yan, Dongkun</i>	
The Research on Smart Distribution Grid	176
<i>Zhou, Xuesong; Huang, Tianxiang; Ma, Youjie; Gao, Zhiqiang</i>	
Control of Rotorcraft Landing Gear on Different Ground Conditions	181
<i>Goh, Keng; Boix, Daniel Melia; McWhinnie, James; Smith, Gareth</i>	
A Method of 3D Human-Motion Capture and Reconstruction Based on Depth Information	187
<i>Quan, Wei; Jiang, Shan; Han, Cheng; Zhang, Yu; Bai, Lijuan; Zhao, Haimei</i>	
Exact Limit Pressure of High-speed Couplings of Micro Gas Turbines for Interference Fits	193
<i>Xiong, Ling; Shang, Peng; Feng, Sheng; Yu, Lie; Cheng, Wenjie</i>	
A Visual Target Tracking Algorithm Based on Improved Kernelized Correlation Filters	199
<i>Zhang, Yanghong; Zeng, Chunnian; Liang, Hong; Luo, Jie; Xu, Fan</i>	
Onboard Autonomy for On-orbit GEO Satellites	205
<i>Li, Yuheng; Jun, Zheng; Chen, Hong; Zhang, Jun</i>	
Multi-robot Target Hunting Based on Dynamic Adjustment Auction Algorithm	211
<i>Gao, Jinge; Li, Min; Wang, Zhongya; Li, Jie; Wang, Hanqing</i>	
Chattering-free Sliding Mode Control of Drum Water Level for Ship Boiler	217
<i>Liu, Sheng; Zhao, Shiquan; Wang, Yuchao</i>	
The on-line Identification of Moment of Inertia of Servo System	222
<i>Sun, Jinqiu; You, Youpeng; Li, Yafei; Yang, Xuefeng; Sun, Jinqiu</i>	

Design of the Monitoring System for an Ocean Drilling Rig <i>Chen, Chen; Liang, Xuehui; Zhao, Yan; Cao, Zenghui</i>	228
Simulation of Surplus Harmonics in Selective Harmonic Elimination Technique <i>Zhang, Wenyi; Song, Ting; Guo, Fangxin; Zhang, Qiang</i>	233
LIDAR-based Dynamic Environment Modeling and Tracking Using Particles Based Occupancy Grid <i>Li, Qiaohui; Dai, Bin; Fu, Hao</i>	238
Mechatronic Design of a Humanoid Head Robot <i>Wan, Minhong; Fu, Mingliang; Zhang, Huiwen; Zhou, Weijia</i>	244
Research on Movement Relationship and Synchronized Motion Control Strategy for the Attack Angle Device of the 2.4m Transonic Wind Tunnel <i>Yang, Ling; Chu, Weihua</i>	249
A Method of Synthetical Fault Diagnosis for Power System Based on Fuzzy Hierarchical Petri Net <i>Wang, Yunliang; Qiu, Dawei</i>	254
Based on Composite Control Method of Researching on Inverter Power Supply <i>Liu, Keping; Xu, Peng; Wang, Yuenan; Li, Yan</i>	259
Motion Simulation of Six-Bar Tensegrity Robot Based on Adams <i>Luo, Ani; Xin, Hao; Cao, Pengfei; Hao, Xiaodong; Yu, Yue; Sun, Penghao; Tian, Wei</i>	264
Data VV&C of Artificial Beijing System <i>Luo, Yuyu; Duan, Hong</i>	270
Research on Logistics Autonomous Mobile Robot System <i>Wang, Chunjie; Du, Dandan</i>	275
Optimization Design of Electric Control System for 6.25m Stamp Charging Coke Oven Dedusting Station <i>Xu, Linlin; Su, Yuhan</i>	281
The Simulation of BLDC Motor Speed Control Based-Optimized Fuzzy PID Algorithm <i>Zhang, Songmao; Wang, Yunliang</i>	287
Conditional Fault Tolerance Properties of (n, k)-Star Graphs <i>Lv, Yali; Wang, Ang; Xu, Yulong</i>	293
Non-fragile Decentralized Force/Position Control for Reconfigurable Manipulator Based on the ACPGA <i>Du, Yanli; Zhao, Ying</i>	299

Study on the Impact of 3D Subtitle Characteristics on Visual Comfort <i>Wu, Yan; Li, Qi; Yang, Jingjing</i>	305
Nonlinear Observer Design for Ships Based on Gaussian Particle Filter <i>Lin, Xiaogong; Nie, Lanrong</i>	311
Tracking RGB Color Markers through DLT Calibrated Monocular Vision System <i>Shahzad, Adil; Mu, Yu; Gao, Xueshan</i>	317
Path Planning Method of Mobile Manipulator Based on the Representation Space <i>Liu, Keping; Sui, Jilei; Yue, Ning; Liu, Shuaishi</i>	322
Research on Yaw Control System of 1.5 MW Double-fed Wind Power Generators <i>Liu, Yan; Zhao, Yangyang; Hou, Chunyu; Meng, Guanhua</i>	327
Intelligent Track Cleaning Robot <i>James, Jesin; Wilson, Jesse; Jetto, Jovna; Thomas, Alna; Dhahabiya, V K</i>	332
A Vibration Suppression Method for Flexible Joints Manipulator Based on Trajectory Optimization <i>Guo, Chuangqiang; Gao, Haibo; Ni, Fenglei; Liu, Hong</i>	338
Software-Based Resolver-to-Digital Conversion and Online Fault Compensation <i>Guo, Chuangqiang; Wu, Chunya; Ni, Fenglei; Liu, Hong</i>	344
A System for Modeling Robotic Intellectual Belief <i>Gao, Jinsheng; Zhou, Changle</i>	350
Based on Continuum Mechanics Thrust Rod Fatigue Life Prediction <i>Feng, Guoyu; Shi, Wenku; Zhang, Henghai; Teng, Teng</i>	356
Modeling and Numerical Simulation of Diesel Engine SCR Deposit <i>Qian, Feng; Lv, Lin; Yang, Dong</i>	361
Research on Spectrum Eigenvalues of Transformer Vibration and its Application on diagnosis <i>Qian, Guochao</i>	366
Based on Short-time Fourier Transform Impulse Frequency Response Analysis in the Application of the Transformer Winding Deformation <i>Li, Yaning; Peng, Wenbang; Zhu, Xiaoyan; Wei, Genyuan; Yu, Hong; Qian, Guochao</i>	371
Research on the Detection Robot for Climbing Tower <i>Ma, Pengfei; Shi, Tengfei; Liu, Ronghai; Zheng, Xin; Yang, Yinchun; Duan, Xinhui; Chang, Ximao</i>	376

	Research on the Towing Torque and Friction Performance of Hydro-viscous Clutch with Different Friction Materials	381
	<i>Ma, Ligang; Xiang, Changle; Du, Minggang; Zhang, Jianwei</i>	
	Design and Simulation of the Digital Controller of Digital Closed Loop Fiber Optic Gyroscope Based on Matlab	387
	<i>Huang, Weiquan; Liu, Chengyang</i>	
	A Wireless Biomimetic Underwater Microrobot for a Father-son Robot System	392
	<i>Li, Maoxun; Guo, Shuxiang</i>	
	The Design of Insertion Force Measurement Device for Catheter Operation Surgery System's Slave Side	398
	<i>Wang, Yu; Guo, Shuxiang; Li, Hengrui</i>	
	Communication between Spherical Underwater Robots Based on the Acoustic Communication Methods	403
	<i>Li, Yaxin; Guo, Shuxiang</i>	
MP1-1	Organization Session: Medical Robots for Minimal Invasive Surgery (I)	
	The Valve Hybrid Fractal Stent for the Next Generation Brain Aneurysm Treatment	409
	<i>Ichikawa, Akihiko; Ito, Takahiro; Shimogaito, Kouhei; Kubo, Takashi ; Fukuda, Toshio</i>	
	An Improved Master-Slave Interventional Surgery Robotic System with Force Feedback	415
	<i>Guo, Shuxiang; Li, Guangxuan; Gao, Baofeng; Wang, Yuan</i>	
	Study on Slave Side of Interventional Surgery Robotic System Focused on the Feed-back Force Detection	420
	<i>Yan, Zhao; Guo, Shuxiang; Shi, Liwei; Wang, Yuan; Li, Guangxuan; Peng, Weili</i>	
	A Fuzzy PID Control Algorithm for The Interventional Surgical Robot with Guide Wire Feedback Force	426
	<i>Guo, Shuxiang; Chen, Qianrui; Xiao, Nan; Wang, Yuan</i>	
	Design and Evaluation of a Novel Guidewire Navigation Robot	431
	<i>Bao, Xianqiang; Guo, Shuxiang; Xiao, Nan; Wang, Yuan; Qin, Mingyang; Zhao, Yan; Xu, Changqi; Pen, Weili</i>	
	A Novel Application of Positioning Method with Force Feedback for Interventional Surgery Robot	437
	<i>Guo, Shuxiang; Xu, Changqi; Xiao, Nan; Wang, Yuan; Peng, Weili</i>	
MP2-1	Organization Session: Medical Robots for Minimal Invasive Surgery (II)	

	Pneumatically-Driven Hand-held Forceps with Wrist Joint Operated by Built-in Master Controller	442
	<i>Miayazaki, Ryoken; Kanno, Takahiro; Kawashima, Kenji</i>	
	Movement Characteristics Evaluation of the Spherical Robot Actuated by the Magnetic Field for Medical Applications	448
	<i>Guo, Shuxiang; Liang, Nan; Guo, Jian; Liu, Pengyu; Wang, Lili; Sun, Gang</i>	
	MR Fluid Interface of Endovascular Catheterization Based on Haptic Sensation	454
	<i>Song, Yu; Guo, Shuxiang; Zhang, Linshuai; Yin, Xuanchun</i>	
	An Experimental Comparison of Four Different Structures for Continuum Manipulators	459
	<i>Wang, Hairong; Fan, Shaowei; Liu, Hong</i>	
	Automatic Space Calibration of A Medical Robot System	465
	<i>Liu, Gangfeng; Li, Changle; Li, Ge; Yu, Xianfu; Li, Liyi</i>	
	An Improved Fall Detection Approach for Elderly People Based on Feature Weight and Bayesian Classification	471
	<i>Wang, Hanqing; Li, Min; Li, Jie; Gao, Jinge; Wang, Zhongya</i>	
MP3-1	Organization Session: Medical Robots for Minimal Invasive Surgery (III)	
	A Compact and Stiffer Shape Memory Alloy Actuator for Surgical Instruments	477
	<i>Shi, Zhenyun; Zhu, Qiancheng; Yuan, Peijiang</i>	
	Study on Motion Following with Feedback Force Disturbance in Interventional Surgical Robot System	485
	<i>Wang, Yuan; Guo, Shuxiang; Gao, Baofeng; Peng, Weili; Li, Guangxuan</i>	
	Design and Principle Analysis for Electromagnetic Brake Clamping Mechanism of a Novel Slave Manipulator	490
	<i>Zhang, Linshuai; Guo, Shuxiang; Yu, Huadong; Yu, Song</i>	
	The Application of Hydraulic Rock Drill Axial Thrust Control Based on Fuzzy PID Control	496
	<i>Liu, Zhong; Liu, Junjun; Zhong, Jiawei; Zou, Yu; Cheng, Longrui</i>	
MP1-2	Organization Session: Biomimetic Measurement and Control in Robotics (I)	
	Image-based Fuzzy control of a Car-like Mobile Robot for Parking Problems	502
	<i>Aye, Yin Yin; Watanabe, Keigo; Maeyama, Shoichi; Nagai, Isaku</i>	
	Safety Analysis of a Climbing Robot with Dual Pumps for Building Surface Detection	508
	<i>Cui, Dengqi; Lei, Yang; Chen, Dongsheng; Mu, Yu; Dong, Han; Qi, Falin; Gao, Xueshan</i>	
	Error analysis of multi-station and time-sharing measurement by laser tracker	514

	<i>Wang, Jindong; Chen, Peng</i>	
	The Integration of Some Sensors for Measuring the Attitudes of a Manta Robot	519
	<i>Deng, Liying; Wang, Qiuying; Mikuriya, Kota; Watanabe, Keigo</i>	
	Surface-Common-Feature Descriptor of Point Cloud Data for Deep Learning	525
	<i>Maimaitimin, Maierdan; Watanabe, Keigo; Maeyama, Shoichi</i>	
	Experimental Study on the Ultrasonic Motor using a Longitudinal-bending Vibration Converter with Inclined Teeth	530
	<i>Chen, Jianyi; Zheng, Zhutang; Lin, Xingling</i>	
MP2-2	Organization Session: Biomimetic Measurement and Control in Robotics (II)	
	Generation of Triangulated Patches Smoothed from Original Point Cloud Data with Noise and Its Application to Robotic Machining	535
	<i>Nagata, Fusaomi; Takeshita, Kazuhiro; Watanabe, Keigo; Habib, Maki K.</i>	
	Biomechanical Measurement and Analysis of Tai Chi Push-hand	541
	<i>Wang, Kun; Zhang, Xiuli; Zhao, Hongfu</i>	
	Blade Vibration Monitoring for a Straight-bladed Vertical Axis Wind Turbine With Pitch Control	546
	<i>Liang, Yingbin; Li, Jiandong; Meng, Jingjia</i>	
	Research on Trajectory Planning of a Robot Inspired by Free-Falling Cat Based on Modified Quasi-Newton Algorithm	552
	<i>Liang, Xingcan; Xu, Linsen; Li, Lu</i>	
	Detection of Hydroxyl Radical in the Electro Catalytic System of BDD Electrode	558
	<i>Wu, Haiqiang; Sun, Jie; Zheng, Longyang; Li, Xiaowei; Gao, Chengyao</i>	
	Autonomous Path Planning of Differential Drive Robots for Co-Ordinate Based Navigation	563
	<i>Gupta, Sparsh</i>	
MP3-2	Organization Session: Biomimetic Measurement and Control in Robotics (III)	
	The Discussion on Power Quality Technology	569
	<i>Gao, Zhiqiang; Zhang, Ke; Zhou, Xuesong; Ma, Youjie</i>	
	Research Review on Smart Distribution Grid	575
	<i>Zhou, Xuesong; Cui, Haobo; Ma, Youjie; Gao, Zhiqiang</i>	
	The Discussion on Smart Distribution Grid System	581
	<i>Zhou, Xuesong; Ren, Tianxi; Ma, Youjie; Gao, Zhiqiang</i>	

	An Overview of PV System	587
	<i>Gao, Zhiqiang; Li, Song; Zhou, Xuesong; Ma, Youjie</i>	
MP1-3	Organization Session: Biometric Underwater Robots	
	Leader-follower Cooperative Movement Method for Multiple Amphibious Spherical Robots	593
	<i>Shi, Liwei; Tang, Kun; Guo, Shuxiang; Bao, Xianqiang; Pan, Shaowu; Guo, Ping</i>	
	Bio-inspired Sliding Mode Controller for ROV with Disturbance Observer	599
	<i>Chen, Wei; Wei, Yanhui; Liu, Hewei; Zhang, Haoyuan</i>	
	An Adaptive Compressive Tracking Algorithm for Amphibious Spherical Robots	605
	<i>Pan, Shaowu; Guo, Shuxiang; Shi, Liwei; Guo, Ping; He, Yanlin; Tang, Kun</i>	
	A Non-Contact Measurement Method of Cabin Capacity Based on Structured Light Vision	612
	<i>Zhu, Wei; Qi, Guanglin; Zhang, Qiang; Wang, Yanghong; Ou, Jian</i>	
	Hydrodynamic Performance Study on a Flexible Caudal Fin	618
	<i>Liu, Bo; Guo, Zhongze</i>	
	Passive Acoustic Detection of Diver Based on SVM	623
	<i>Zhao, Wu; Chen, Hong; Xiang, Longfeng; Xie, Xiaomei; Chen, Min; Zhao, Zuli; Li, Qi</i>	
MP2-3	Biomimetic Systems (I)	
	Autonomous Environmental Monitoring by Self-powered Biohybrid Robot	629
	<i>Shoji, Kan; Morishima, Kersuke; Akiyama, Yoshitake; Nakamura, Nobuhumi; Ohno, Hiroyuki</i>	
	Self-assembly of Magnetized Microstructures for in Vitro Cell Systems	635
	<i>Hattori, Mamoru; Ichikawa, Akihiko; Ohara, Kenichi; Fukuda, Toshio; Takeuchi, Masaru; Nakajima, Masahiro; Hasegawa, Yasuhisa; Huang, Qiang</i>	
	Biologically Inspired Guidelines for the Design of the Hyper-Dexterous Manipulator	641
	<i>Wang, Hairong; Fan, Shaowei; Ni, Fenglei; Liu, Hong</i>	
	Short-Range Dynamic Gain Control for Laser Radar	647
	<i>Xiang, Dong; Dong, Wenfei; Ge, Mingfeng; Chen, Xiangcheng</i>	
	Controller-Switching Based Gait Transition for a Quadruped Robot	653
	<i>Huang, Zhuhui; Wang, Wei</i>	
	Foot Contact Force of Walk Gait for a Quadruped Robot	659
	<i>Li, Xiaoqi; Wang, Wei; Yi, Jianqiang</i>	

MP3-3	Biomimetic Systems (II)	
	Design and Experiment of a Bioinspired Wall-Climbing Robot Using Spiny Grippers	665
	<i>Liu, Gaowei; Liu, Yanwei; Wang, Xiaojie; Wu, Xuan; Mei, Tao</i>	
	Design and Experiment of a Tank-like Wall-Climbing Robot Using Fibril Dry Adhesives	671
	<i>Zhang, Yanan; Zhang, Yongjie; Wu, Xuan; Mei, Tao</i>	
	Variable Stiffness Control and Implementation of Hydraulic SEA Based on Virtual Spring Leg	677
	<i>Chu, Zhen; Luo, Jianwen; Fu, Yili</i>	
	Development of a Flexible Tail for Legged Robot	683
	<i>Sato, Ryuki; Hashimoto, Shun; Ming, Aiguo; Shimojo, Makoto</i>	
MP1-4	Rotor Dynamics, Vibration Analysis and Vibration Control	
	Dynamic Gait Analysis of a Multi-functional Robot with Bionic Springy Legs	689
	<i>He, Yanlin; Guo, Shuxiang; Shi, Liwei; Pan, Shaowu; Guo, Ping</i>	
	A Novel Speed Regulated Algorithm for Surface Mounted Permanent Magnet Synchronous Motor	695
	<i>Wu, Yingzhe; Li, Hui</i>	
	The Beam Theory-based Collision Force Detection of the Catheter Operating System	701
	<i>Zhang, Chaonan; Guo, Shuxiang; Gao, Baofeng; Jia, Feiyu</i>	
	Autonomous Pallet Localization and Picking for Industrial Forklifts Based on the Line Structured Light	707
	<i>Wang, Shijun; Ye, Aixue; Guo, Hao; Gu, Jiaojiao; Wang, Xiaonan; Yuan, Kui</i>	
	Effects of Contact Interfaces on Rotor Dynamic Characteristics of Heavy-Duty Gas Turbine Generator Set	714
	<i>Xia, Kai; Sun, Yanhua; Hong, Dejiang; Guo, Jiafang; Kang, Xian</i>	
	Design of the Rock Coal Shearer Cutting Mechanism and Its Vibration Analysis	720
	<i>Zhang, Dan; Zhao, Ning; Tong, Minming; Du, Changlong</i>	
MP2-4	Control Systems	
	Application of Model Predictive Control Technique for Wave Piercing Catamarans Ride Control System	726
	<i>Liang, Lihua; Yuan, Jia; Zhang, Songtao</i>	
	Research on Feedforward Dynamic Matrix Control of a Four-stabilizer Fin System	732

	<i>Yu, Lijun; Bi, Wenpeng; Wei, Zhihong; Wang, Hui</i>	
	A Hybrid Passive/Active Force Control Scheme for Robotic Belt Grinding System	737
	<i>Zhang, Jinfeng; Liu, Gangfeng; Zang, Xizhe; Li, Liyi</i>	
	The Space Vector Control System Design of the Cross Section Cutting Based on the Fuzzy PID Algorithm in the Coal Mine	743
	<i>Zhao, Jie; Yu, Zongyan; Ren, Sijing</i>	
	A Fault Diagnosis Method by Multi Sensor Fusion for Spacecraft Control System Sensors	748
	<i>Li, Yuqing; Yang, Tianshe; Liu, Jian; Fu, Na; Wu, Guan</i>	
	D-UKF Based State of Health Estimation for 18650 Type Lithium Battery	754
	<i>Cai, Yifei; Wang, Qiuting; Qi, Wei</i>	
MP3-4	Robotic Structure and Manipulator Control	
	Multi-objective Optimal Trajectory Planning of Manipulators Based on Quintic NURBS	759
	<i>Shi, Xiangling; Fang, Honggen; Guo, Lijie</i>	
	An Untethered Self-folding Locomotive Paper Robot Using Pneumatic Actuators	766
	<i>Wu, Hongtao; Fang, Yibo; Du, Xiaohan; Ni, Feng; Tang, Kai</i>	
	Characteristics Research of an Underactuated Manipulator Basing on the Statics and Dynamics Analysis	772
	<i>Lv, Xin; Qiao, Shangling; Shi, Yuming; Liu, Rongqiang</i>	
	Real-time Collision Detection for Manipulators Based on Fuzzy Synthetic Evaluation	777
	<i>Jing, Xia; Guangxin, Wu; Li, Chongyang; Liu, Hong</i>	
MP1-5	Control Strategy (I)	
	IMP-Based Synchronization Controller for Distributed Three-Phase Inverter with Uncertain Loads	783
	<i>Bangbose, Samuel Oludare; Zhang, Yongpeng; Qian, Lijun</i>	
	Improved ADRC Control Strategy in FPSO Dynamic Positioning Control Application	789
	<i>Wang, Yuanhui; Yang, Yunlong; Ding, Fuguang</i>	
	High Accuracy Inertial Stabilization via Kalman Filter Based Disturbance Observer	794
	<i>Wang, Fuchao; Tian, Dapeng; Wang, Yutang</i>	
	Finite Element Modelling and LQG Control of Piezoelectric Composite Structure with Distributed Sensors and Actuators	803
	<i>Wang, Zhuang</i>	

	Study of Flux Linkage Control Method in Discrete Frequency	809
	<i>Meng, Yanjing; Chen, Jun; Duan, Mingliang; Li, Xiaonan; Gao, Zeyu</i>	
	An Online Calculation Method of Theoretical Power Losses for High-voltage Distribution System Based on Rapid Modeling and Data Quality Analysis	816
	<i>Han, Song; Li, Kai; Xu, Kui</i>	
MP2-5	Control Strategy (II)	
	Investigation on Vehicle Height Control Algorithm Based on UKF Observer	822
	<i>Wang, Ming; Chen, Sizhong; Zhao, Yuzhuang</i>	
	Investigation of a Stiffness Varying Mechanism for Flexible Robotic System	828
	<i>Huan, Angeliqye Sixuan; Xu, Wenjun; Ren, Hongliang</i>	
	Formation Controller of Multiple Unmanned Underwater Vehicle Based Passivity Design	834
	<i>Li, Juan; Liu, Jianhua</i>	
	Rolling Manipulation Control of the Disk-on-Disk on a Two-Link Arm	840
	<i>Ryu, Ji-Chul; Lynch, Kevin M.</i>	
	EFT Research of SPI-DeviceNet Protocol Converter	846
	<i>Jia, Chao; Cao, Shiqin</i>	
	Sampled-data Design for Decoherence Control in Open Quantum System with Operator Errors	851
	<i>Hu, Jujun; Wang, Yifan; Ji, Yinghua</i>	
MP3-5	Control Strategy (III)	
	5-Axis Feed Drive Modelling and Spatial Contour Error Analysis based on Dynamics of Servo System	856
	<i>Pi, Shiwei; Liu, Qiang; Liu, Huan</i>	
	A CMOS Monolithic Calibrated Position-Sensitive Detector (PSD) for Detecting Light-Spot Position Applications	862
	<i>Chiang, Cheng-Ta; Hou, Yu-Ting</i>	
	Development of an Autonomous Beach Cleaning Robot “Hirottaro”	868
	<i>Ichimura, Tomoyasu; Nakajima, Shin-ichi</i>	
	Dynamic Lane Tracking System Based on Multi-model Fuzzy Controller	873
	<i>Shi, Qing; Zhao, Jin; Han, Lei; Ning, Youjiang; Wang, Guangwei</i>	
MP1-6	Biomedical Robotic System (I)	

	A Novel Variable Stiffness Actuator-based Exoskeleton Device for Home Rehabilitation	878
	<i>Zhang, Ying; Guo, Shuxiang; Cao, Guohua; Zhang, Songyuan; Liu, Yi</i>	
	Design and Kinematic Analysis of a Hybrid Manipulator for Spine Surgery	884
	<i>Peng, Yi; Yu, Hongjian; Du, Zhijiang</i>	
	Dynamic Electro-thermal Modeling of V- and Z-shaped Electrothermal Microactuator	890
	<i>Zhang, Zhuo; Yu, Yueqing; Liu, Xinyu; Zhang, Xuping</i>	
	A Needle Insertion Concept and Robot System for Breast Tumor	896
	<i>Zhao, Honghua; Liu, Tao; Chen, Mianpeng; Tian, Qianqian; Li, Zhiping; Cao, Shukun; Ai, Changsheng</i>	
	Preoperative Setup Planning for Robotic Surgery Based on a Simulation Platform and Gaussian Process	902
	<i>Zhang, Fan; Yan, Zhiyuan; Du, Zhijiang</i>	
	A Patient-driven Control Method for Lower-Limb Rehabilitation Robot	908
	<i>Wang, Xiaonan ; Lu, Tao; Wang, Shijun ; Gu, Jiaojiao; Yuan, Kui</i>	
MP2-6	Biomedical Robotic System (II)	
	High-Resolution Cell Manipulation for Longstanding Load on Red Blood Cells	914
	<i>Tsai, Chia-Hung Dylan; Horade, Mitsuhiro; Ito, Hiroaki; Kaneko, Makoto; Takana, Motomu</i>	
	Automated Construction System for Cellular Tissue Based on Laminar Flow Fibers	920
	<i>Kojima, Masaru; Fukushima, Akira; Takata, Suguru; Horade, Mitsuhiro; Ohara, Kenichi; Sakai, Shinji; Kamiyama, Kazuto; Mae, Yasushi; Arai, Tatsuo</i>	
	Design and Control of an Anthropomorphic Prosthetic Hand with a Cosmesis	926
	<i>Zeng, Bo; Fan, Shaowei; Jiang, Li; Cheng, Ming; Liu, Hong</i>	
	Design and Control of Mechanical Structures for Sit-to-stand Rehabilitation Training	931
	<i>Liu, Kun; Ye, Ming; Yan, Pengfei ; Li, Chao</i>	
	Design and Performance Evaluation of a Novel Master Manipulator for the Robot-assist Catheter System	937
	<i>Guo, Jian; Yu, Yang; Guo, Shuxiang; Du, Wenjuan</i>	
	Design and Research on High Voltage Power Supply of Medical X-ray Machine	943
	<i>Li, Feng; Wang, Shaobin; Hou, Wei; Qin, Xiaofei</i>	
MP3-6	Intelligent Biomedical Instrument Technology and Application	
	Automatic Segmentation of Vessel Lumen in Intravascular Optical Coherence Tomography Images	948

Wang, Ancong; Tang, Xiaoying

An EOG Signals Recognition Method Based on Improved Threshold Dual Tree Complex Wavelet Transform 954

Dong, Enzeng; Li, Changhai; Chen, Chao

Human Brain Activation Network for Chinese Character Processing: An fMRI Study 960

Li, Xiujun; Yang, Jingjing; Li, Qi; Tong, Dan; Wu, Jinglong

A CMOS Particulate Matter 2.5 (PM2.5) Concentration to Frequency Converter with Calibration Circuits for Air Quality Monitoring Applications 966

Chiang, Cheng-Ta; Huang, Ssu-Wei; Liu, Guan-Xian

MP1-7 Robot Navigation and Control Algorithm (I)

Human-inspired Robot Navigation in Unknown Dynamic Environments 971

Pradeep, Yazhini C.; Ming, Zhu; Rosario, Manuel Del; Chen, Peter C. Y.

Navigation Research on Outdoor Miniature Reconnaissance Robot 977

Liu, Yi; Gao, Junyao; Shi, Xuanyang; Zhao, Jingchao; Gao, Haoxiang; Zhao, Fangzhou; Liu, Chuzhao

Improved Cubature Kalman Filtering for Tightly Coupled GPS/SINS Integrated Navigation System 983

Wei, Zhu; Wei, Wang; Yuan, Gannan

Autonomous Landing of a Quadrotor on an UGV 988

Fu, Mengyin; Zhang, Kuan; Yi, Yang; Shi, Chao

Distributed SLAM System Using Particle Swarm Optimized Particle Filter for Mobile Robot Navigation 994

Pei, Fujun; Wu, Xiaoping; Yan, Hong

Formally Verifying Navigation Safety for Ground Robots 1000

Zhang, Manni; Zhang, Xinyu

MP2-7 Robot Navigation and Control Algorithm (II)

Dynamic Path Planning Algorithm for Autonomous Vehicles in Cluttered Environments 1006

Wang, Jiefei; Garratt, Matthew; Anavatti, Sreenatha

Mission and Motion Control of AUV for Terrain Survey Mission Using Discrete Event System Theory 1012

Chen, Tao; Wang, Yuzhu; Xu, Da; Zhang, Honghan; Zhou, Jiajia

Global Path Planning Methods of UUV in Coastal Environment 1018

Zhang, Hong-han; Gong, Liming; Chen, Tao; Wang, Lu; Zhang, Xun

Pedestrian Localization in Distributed Vision System for Mobile Robot Global Path Planning 1024

Guo, Yue; He, Yijia; Wen, Feng; Yuan, Kui

Research on Path Planning Algorithm based on Security Patrol Robot 1030

Du, Juan; Zheng, Peng; Xie, Zhongyu; Yang, Yu ; Chu, Hongxia; Yu, Gaobo

Trajectory-tracking Control based on UKF for Autonomous Underwater Vehicle with Process and Measurement Noise 1036

Liu, Bo; Yuan, Jian

MP3-7 Robot Navigation and Control Algorithm (III)

Indoor Place Recognition Based on Set Operation of Keypoints Databases 1041

Long, Xuexiong; Wang, Ke; Li, Ruifeng; Zhao, Lijun

Efficient Wall-Corner Collision Avoidance using D-Images 1048

Fu, Guohe; Zhang, Xinyu

The Embedded Intelligent Network Video Surveillance System Based on ARM and Linux 1054

Li, Yusen; Qu, Peng

Fast Map Segmentation Method Based On Spectral Partition For Robot Semantic Navigation 1059

Tian, Yafu; Wang, Ke; Li, Ruifeng; Zhao, Lijun

TA1-1 Legged Robots

Walking Pattern Generation in Sagittal Plane Possessing Characteristics of Human Normal Walking 1066

Lee, Sangwook; Lee, Jongwoo; Lee, Dong Gun; Oh, Yonghwan

Realization of Biped Robot Gait Planning Based on NAO Robot Development Platform 1073

Dong, Enzeng; Wang, Dandan; Chen, Chao; Tong, Jigang

New Tripod Walking Method for Legged Inspection Robot 1078

Kriengkamol, Pakpoom; Kamiyama, Kazuto; Kojima, Masaru; Horade, Mitsuhiro; Mae, Yasushi; Arai, Tatsuo

Virtual Constraint Based Adaptive Control for Biped Robot with Speed Regulation 1084

Li, Jianfei; Wang, Yaobing; Zhang, Dawei; Liu, Li

An Embedded Controller for a Quadruped Robot Based on ARM and DSP 1090

Wang, Conglin; Wang, Wei

	Mechanical Design of a Self-adaptive Transformable Tracked Robot for Cable Tunnel Inspection	1096
	<i>Zou, Minghe; Bai, Han; Wang, Yang; Yu, Suyang</i>	
TA2-1	Human-Machine Interaction and Interface	
	A Projection-based Making-human-feel-safe System for Human-Robot Cooperation	1101
	<i>Liu, Diyi; Kinugawa, Jun; Kosuge, Kazuhiro</i>	
	An Image Registration Method for Surgical Robots Based on Human-Robot Cooperation	1107
	<i>Gao, Lei; Liu, Hao; Zhou, Yuanyuan; Han, Jianda</i>	
	Binary Linear Regression and Statistical Learning of Behavior Model for Human Teleoperator	1113
	<i>Hu, Tianjian; Wang, Tianshu; Li, Junfeng; Wang, Xueqian; Zhu, Xiaojun</i>	
	Craniotomy Robot System Based on Human-Machine Parallel Collaboration	1119
	<i>Zhan, Yue; Duan, Xing-guang; Cui, Teng-fei; Han, Ding-qiang</i>	
	Design and Kinematic Simulation of a Novel Exoskeleton Rehabilitation Hand Robot	1125
	<i>Guo, Shuxiang; Zhang, Weijie; Guo, Jian; Gao, Jiange; Hu, Yuye</i>	
	Analysis of Dynamic Characteristics of Rugged Vessel in the Process of Hepatic Perfusion	1131
	<i>Wang, Songli; Liu, Jun; Liu, Yihe; Ge, Weimin</i>	
TP1-1	Humanoid Robot System	
	Comparison of Several Acoustic Features for the Vowel Sequence Reproduction of a Talking Robot	1137
	<i>Thanh, Vo Nhu; Sawada, Hideyuki</i>	
	Study on a Multi-Robot Cooperative Wireless Communication Control System for the Spherical Amphibious Robot	1143
	<i>Guo, Shuxiang; Li, Xin; Guo, Jian</i>	
	Novel Design of a 3-DOF Series-parallel Torso for Humanoid Robots	1149
	<i>Zhang, Weimin; Guo, Xinran; Huang, Hulin; Huang, Qiang</i>	
	Passive Buffering Arm for a Humanoid Robot against Falling Damage	1155
	<i>Zhang, Zezheng; Huang, Qiang; Liu, Huaxin; Zhang, Weimin; Chen, Xuechao; Yu, Zhangguo</i>	
	From Human Spine to Humanoid Robot Torso	1161
	<i>Zhang, Qingqing; Li, Tao; Luo, Minzhou; Yao, Peng</i>	

	Analysis of Human Spine Functionality from the Perspective of Humanoid Robots	1167
	<i>Yao, Peng; Li, Tao; Luo, Minzhou; Zhang, Qingqing</i>	
TP2-1	Rehabilitation Robotics	
	A VR-based Self-rehabilitation System	1173
	<i>Guo, Shuxiang; Liu, Yi; Zhang, Ying; Zhang, Songyuan; Yamamoto, Keiji</i>	
	Development of a Hybrid Motion Capture Method Using MYO Armband with Application to Teleoperation	1179
	<i>Xu, Yanbin; Yang, Chenguang; Liang, Peidong; Zhao, Lijun; Li, Zhijun</i>	
	Design of the Structural Optimization for the Upper Limb Rehabilitation Robot	1185
	<i>Guo, Shuxiang; Gao, Jiange; Guo, Jian; Zhang, Weijie; Hu, Yuye</i>	
	Gait Tracking for Lower Extremity Exoskeleton Based on Sliding Mode Control with CMAC Compensation	1191
	<i>Du, Zhijiang; Zhang, Zhiming; Long, Yi; Dong, Wei</i>	
	An EMG-based Muscle Force Evaluation Method Using Approximate Entropy	1197
	<i>Guo, Shuxiang; Hu, Yuye; Guo, Jian; Zhang, Weijie</i>	
	Solar Air-Source Heat Pump Hot Water Unit Control System Design	1203
	<i>Li, Yang; He, Tian; Juyuan, Jiang</i>	
TA1-2	Industrial Applications (I)	
	Controlled Start Transmission Hydraulic Clutch Disc Temperature Modelling and Applications	1209
	<i>Martinsson, Joel; Liu, Bin</i>	
	The Method of Residual Stress Gradient Measurement Based on Ultrasonic Technology	1215
	<i>Pan, Qinxue; Ren, Yanfei; Wei, Yuan; Mi, Yu</i>	
	Study on the Deformation Measurement and Reconstruction of Heavy-duty Machine Column Based on FBG sensor	1221
	<i>Liu, Mingyao; Wang, Lina; Yun, Kang; Zhu, Zaisi</i>	
	The Research and Development of Automatic Vertical Drilling Tool	1226
	<i>Yan, Wenhui; Peng, Yong; Wu, Heng</i>	
	PD Mechanism and Pattern Investigation for Stator Winding Insulation of HV Motors	1232
	<i>Wang, Wei; Yan, Lin; Wang, Tianzheng; Yu, Hua; Han, Yu; Liu, Xingting; Zhang, Na; Wu, Na</i>	
	Dynamic Load Identification Method of Rock Roadheader Using Multi Neural Network and Evidence Theory	1238

Wang, Wei; Yan, Lin; Wang, Tianzheng; Guan, Shaoping; Zhang, Chao; Zhang, Ying; Wang, Dawei

TA2-2 Industrial Applications (II)

[Development of a Dynamics Model for the Baxter Robot](#) 1244

Smith, Alex; Yang, Chenguang; Li, Chunxu; Ma, Hongbin; Zhao, Lijun

[Performance Optimization of a 2-DoF Parallel Mechanism Based on Multiple Indices](#) 1250

Hao, Qi; Liu, Bo; Wang, Mingxin; Zhou, Jing

[Hysteretic Damping System Parameter Identification Based on HABC-CS Algorithm](#) 1256

Kang, Weixin; Ye, Youdao; Zhao, Tianwei; Raja, Asifwagan

[Analysis of Mechanical Properties for Membrane Structure by the Absolute Nodal Coordinate Formulation](#) 1262

Zhang, Yingying; Liu, Rongqiang; Guo, Hongwei; Deng, Zongquan; Zhao, Haojiang

[Application Prospect of 4G/LTE Technology in PROFIBUS](#) 1268

Zhou, Yuan; Li, Xiaokun; Liu, Mingshan; Sui, Jinglin; Gao, Fengxi

[Inertial Error Study and Simulation of the Simulating Inertial System](#) 1273

Li, Hongbo; Zhao, Jiliang; Su, Yu; Shi, Hailin

TP1-2 Manufacturing Technology

[Sensor Fault Diagnosis of Dynamic Positioning Ship Based on Finite Impulse Response Filter](#) 1278

Ding, Fuguang; Ban, Xicheng; Liu, Xiangbo

[An Investigation on Drilling Micro Holes in Different Processes using Micro-EDM](#) 1283

Li, Yiqian; Hou, Wanwu; Xu, Jinkai; Yu, Huadong

[The design of Micro-machine Tool Storage and Analysis of key parts](#) 1289

Sun, Guiyan; Li, Xiaozhou

[A Method of Testing Residual Stress by Ultrasonic Shear and Longitudinal Waves](#) 1295

Pan, Qinxue; Mi, Yu; Wei, Yuan; Ren, Yanfei

[The Noise Analysis and Improved Design of Flow Characteristics for Control Valve with High Differential Pressure in Circulating Fluidized Bed](#) 1300

Shao, Haiyan; Ma, Yuzhen; Han, Qing; Wu, Tao

[A Fine Manipulation Tweezer with Embedded Ultrasonic Motor for Assembly and Gripping Miniature Parts](#) 1305

Li, Chaodong; Wu, Biyun; Li, Si; Zhang, Quan

TP2-2	Measurement for Manufacturing	
	Fracture Failure Analysis of Valve Bolt in the Gas Transmission Station	1310
	<i>Guo, Yanbao; Yang, Xu; Liu, Ben; Liu, Shuhai</i>	
	Measurement Method of Compressibility Coefficient for Density Standard Liquid at 2329 kg/m ³ with a Vibrating Tube Densimeter	1316
	<i>Li, Zhihao; Wang, Jintao; Tong, Lin; Liu, Xiang</i>	
	The Surface Tribological Properties of 7075 Aluminum Alloy by HS-WEDM	1321
	<i>Xu, Jinkai; Qiu, Rongxian; Xia, Kui; Zhang, Linshuai; Xu, Lining; Yu, Huadong</i>	
	The Heave Motion Estimation for Active Heave Compensation System in Offshore Crane	1327
	<i>Ning, Xianliang; Zhao, Jiawen; Xu, Jianan</i>	
	Crack Growth and the Correlation of Model Coefficient for Typical Aircraft Metal Material	1333
	<i>Liu, Wenlin; Yu, Dazhao</i>	
	Automatic Path and Trajectory Planning for Laser Cladding Robot Based on CAD	1338
	<i>Zheng, Huadong; Cong, Ming; Liu, Dong; Liu, Yi; Du, Yu</i>	
TA1-3	Robust Control	
	The Application of Robust Adaptive Cubature Particle Filter Algorithm in Initial Alignment of SINS	1344
	<i>Chi, Fengyang; Gao, Wei</i>	
	Study on Stabilizing Power of Dynamic Positioning Ship Based on Thrust Allocation	1350
	<i>Ding, Fuguang; Yang, Dong; Huang, Wei</i>	
	Robust Controller Design for 90 Degrees Stand Motion of a Front-wheel Drive Bicycle Robot	1356
	<i>Guo, Lei; Hei, Kai; Song, Yuan; Xing, Bin</i>	
	Steady Glide Reentry Trajectory Optimization with Waypoint and No-fly Zone Constraints	1363
	<i>Li, Jinglin; Chen, Wanchun; Min, Changwan</i>	
	Dynamic Modeling and Robust Controller Design for Circular Motion of a Front-wheel Drive Bicycle Robot	1369
	<i>Xing, Bin; Guo, Lei; Wei, Shimin; Song, Yuan</i>	
	Fidelity of Robust Control in Open Quantum System with Superconducting Qubit	1374
	<i>Ji, Yinghua; Huang, Jianhua; Hu, Juju</i>	
TA2-3	Intelligent Control	

	The Research and Design of Pneumatic Multi-pipe Deep Lunar Soil Drilling Device	1379
	<i>Liang, Ping; Hou, Xuyan; Zhang, Kailiang; Zhang, Kaidi; Deng, Zongquan</i>	
	ALCM Descending-phase Guidance Law including Derivative of Normal Acceleration Restriction	1385
	<i>Li, Heng; Chen, Wanchun</i>	
	Multi-objective Optimization of Synchronous Buck Converter Based on NSGA-II Algorithm	1391
	<i>Chang, Wei; Wang, Jiuhe; Chen, Qili</i>	
	Study on Prediction Model of Blast Furnace Hot Metal Temperature	1396
	<i>Yue, Youjun; Dong, An; Zhao, Hui; Wang, Hongjun</i>	
	A Force Control Structure Based on the Concept of Virtual Plant	1401
	<i>Ma, Zheng; Hong, Geoksoon; Ang Jr, Marcelo H.; Poo, Aun-Neow</i>	
	Research of Coke Ratio Prediction Based on Concept Lattice and Genetic Algorithm	1407
	<i>Yang, Kai; Jin, Yonglong</i>	
TP1-3	Fuzzy Control	
	Design Sliding Mode Control of Fuzzy Switching Gain for Lift-feedback Fin Stabilizers	1412
	<i>Lian, Lihua; Sun, Mingxiao; Luan, Tiantian</i>	
	Generalized Predictive and Fuzzy Control in 600MW Supercritical Unit Coordinated Control System	1418
	<i>Wu, Zhigang</i>	
	Research on Crawling Conditions for an AMT Vehicle Based on the Fuzzy Control Method	1423
	<i>Zhang, Hongkun; Li, Wenjun; Hua, Fugen</i>	
	An Adaptive Path Tracking Method for Autonomous Land Vehicle based on Neural Dynamic Programming	1429
	<i>Zhu, Qi; Huang, Zhenhua; Liu, Daxue; Dai, Bin</i>	
	Position Control for Filter Rod Splint Based on Fuzzy-PID	1435
	<i>Yang, Zhi; Du, Jun; Zhou, Shuaijun</i>	
	The Fuzzy-PID Control of Brushless DC Motor	1440
	<i>Jing, Jianli; Wang, Yanchun; Huang, Yinghui</i>	
TP2-3	Fuzzy, Neural Control	
	Control Fusion Strategy via Differential Equations Based Hysteresis Operator	1445

Ramli, Mohd Hanif Mohd; Chen, Xinkai

The Application of Dual Neural Network for Control System of Four Stabilizer Fins of Ship Anti-rolling 1451

Yu, Lijun; Dong, Zequan; Wang, Zhengkun; Wang, Hui

Neural Network-based Adaptive Fast Terminal Sliding Mode Control for a Class of SISO Uncertain Nonlinear Systems 1456

Fu, Mingyu; Liu, Tong; Liu, Jia; Gao, Shuang

T-S Fuzzy Controller Design of a Wire-Moving Robot Based on LMI 1461

Mo, Xihu; Guo, Lei; Song, Yuan

Fuzzy PID Control Strategy Based on Piecewise Biomechanical Model for Sit-to-stand Movement 1466

Liu, Kun; Li, Chao; Yan, Pengfei ; Ye, Ming

Research on the Stability of the Semi-trailer Based on Neural Network Control 1472

Yu, Zhixin; Xing, Dong; Cao, Quande; Li, Shaosong

TA1-4 Space Robotics and Mechatronics (I)

Rocket Engine Experimental Data Reconstruction Based on Compressive Sensing with MOD Dictionary 1477

Liu, Yu; Tong, Xiaoyan; Tian, Jiuling; Guo, Dongxin

Motion Analysis of the Four-bar Tensegrity Robot 1483

Liu, Heping; Yu, Yue; Sun, Penghao; Xin, Hao; Hao, Xiaodong; Tian, Wei

Simulation and Research on Landing Impact between Lander and Lunar Regolith Based on DEM 1489

Hou, Xuyan; Xue, Pingping; Zhang, Kailiang; Zhang, Kaidi; Liang, Ping; Wang, Yongbin

Mechanical Analysis and Design of a Light Weight and High Stiffness Space Manipulator 1495

Liu, Jiayu; Fan, Qinglin; Deng, Tao; Wang, Yanbo; Huang, Qiang

On-board Real-time Path Planning Design for Large-scale 7-DOF Space Manipulator 1501

Yu, Jiyang; Huang, Dan; Liang, Changchun; Wang, Bin; Zhang, Xiaodong; Lu, Lan

Time-varying Spectrum Based Active Disturbance Rejection Control for Hypersonic Reentry Vehicle 1507

Pu, Zhiqiang; Zhang, Jianhong; Yuan, Ruyi; Yi, Jianqiang

TA2-4 Space Robotics and Mechatronics (II)

	Study on Charging Mechanism Model of Lunar Dust for Technology of Particle Removal from Detector	1513
	<i>Hou, Xuyan; Fu, Hua; Yang, Xiaoping; Xue, Pingping; Zhang, Kailiang; Jiang, Jing</i>	
	Study on Optimization of Structure Parameters to the Penetrator	1518
	<i>Shen, Yi; Jiang, Shengyuan; Xu, Chuanxi; Zhang, Weiwei; Wu, Xiang</i>	
	Guideline and Design of a Six-dimensional Constraint Gripper	1524
	<i>Liu, Hong; Wu, Jun; Fan, Shaowei; Li, Zhiqi; Jin, Minghe</i>	
	Multi-level Speed Planning Based Capturing Strategy of Simultaneous Three-fingered End-effectors	1530
	<i>Wu, Jun; Fan, Shaowei; Li, Zhiqi; Jin, Minghe; Liu, Hong</i>	
	Research on High Accuracy, Long Life, and High Reliability Technique of Control Moment Gyroscope	1536
	<i>Li, Gang; Wu, Dengyun; Lu, Ming; Lai, Lin; Tian, Xing; Zhang, Jiyang</i>	
	A Practical Detection of Non-Cooperative Satellite Based on Ellipse Fitting	1541
	<i>Liu, Yang; Xie, Zongwu; Wang, Bin; Liu, Hong; Jing, Zheng; Huang, Cong; Bao, Shi</i>	
TP1-4	Mobile Robot Systems	
	The Application of Image Mosaic in Information Collecting for an Amphibious Spherical Robot System	1547
	<i>Guo, Shuxiang; Sun, Shan; Guo, Jian</i>	
	The Novel Control Method for the Adit Data Collection System	1553
	<i>Yang, Lei; Li, En; Liang, Zize</i>	
	Overview of Rotary Steerable System and Its Control Methods	1559
	<i>Zhang, Chi; Zou, Wei; Cheng, Ningbo</i>	
	Research on an Omni-directional AGV with Differential Wheels	1566
	<i>Wang, Xiaoyan; Cui, Wang; Xu, Xiujun; Ye, Changlong</i>	
	Intelligent Multiple-Fault Diagnosis of a Mobile Robot System in the Presence of Hide Effect	1572
	<i>Yu, Ming; Chen, Si; Xia, Hao; Li, Mengxin; Wang, Hai; Xu, Juan; Zhang, Yanru</i>	
	Intuitive Robot Teaching by Hand Guided Demonstration	1578
	<i>Zhao, Lijun; Li, Xiaoyu; Liang, Peidong; Yang, Chenguang; Li, Ruifeng</i>	
TP2-4	Micro and Nano System	

	Development of Micro-fiber Array with High-friction and Lowadhesion for Wafer Transfer on a Wafer Transfer Robot	1584
	<i>Han, Haijun; Liu, Yanjie; Sun, Lining</i>	
	Thermoelastic Damping in Micro-wedged Cantilever Resonator with Rectangular Cross-section	1590
	<i>Zhou, Hongyue; Li, Pu; Zuo, Wanli</i>	
	Effect of Interaction Manipulation on Nonconductive Micro Sphere under Scanning Electron Microscope	1596
	<i>Cao, Ning; Wu, Zhizheng; Liu, Mei; Li, Hengyu; Pu, Huayan; Xie, Shaorong; Luo, Jun; Gong, Zhenbang</i>	
	Micro Texture Cutting Tool Simulation and Experimental Study on High Speed Micro-turning	1602
	<i>Yu, Zhanjiang; Cai, Qianqian; Li, Yiquan; Wang, Zhitong; Wang, Xingxing; Yu, Huadong</i>	
	A Study on the Micro Machining Characteristics in Micro Cutting of Polycrystalline Metals	1607
	<i>Li, Yiquan; Yu, Wenchuan; Yu, Zhanjiang; Xu, Jinkai; Yu, Huadong</i>	
	A Comparative Investigation of Micro-EDM Drilling Capability for Ti-6Al-4V Alloy Against Austenitic Stainless Steel SUS 316	1612
	<i>Li, Yiquan; Yu, Wenchuan; Xu, Jinkai; Yu, Huadong</i>	
TA1-5	Vision-based Detection and Mapping	
	Efficient Monocular Coarse-to-Fine Object Pose Estimation	1617
	<i>Feng, Rong; Zhang, Hong</i>	
	A Handle Inspection Device for Curtain Wall Installation Based on Structured Laser	1623
	<i>Li, Haoyuan; Duan, Xingguang; Zhan, Yue; Gao, Liang</i>	
	FPGA Based Real-time Vehicle Detection System under Complex Background	1629
	<i>Gu, Jiaojiao; Xiao, Han; He, Wenhao; Wang, Shijun; Wang, Xiaonan; Yuan, Kui</i>	
	Velocity Measurement of Intelligent Wheelchair Based on Restoration of Optical Flow Field	1635
	<i>Li, Xiuzhi; Xu, Chuanluo; Jia, Songmin; Li, Shangyu</i>	
	A Framework of Teleoperated and Stereo Vision Guided Mobile Manipulation for Industrial Automation	1641
	<i>Chen, Fei; Gao, Boyang; Selvaggio, Mario; Li, Zhijun; Caldwell, Darwin; Kershaw, Keith; Masi, Alessandro; Castro, Mario Di</i>	
	An Efficient Scan-to-Map Matching Approach for Autonomous Driving	1649

Fu, Hao; Ye, Lei; Yu, Rui; Wu, Tao

TA2-5	Vision-based Recognition and Control	
	Multiple Collaborative Representations for Face Recognition	1655
	<i>Ma, Zhongli; Liu, Quanyong; Hao, Liangliang</i>	
	3D Smiling Facial Expression Recognition Based on SVM	1661
	<i>Liu, Shuming; Chen, Xiaopeng; Fan, Di; Chen, Xu; Meng, Fei; Huang, Qiang</i>	
	Vision-based Keyhole Detection and Parameter Extraction in Door Opening Task	1667
	<i>Li, Jiajun; Xu, Xu; Tao, Jianguo; Ding, Liang; Gao, Haibo; Deng, Zongquan</i>	
	DSRF: A Flexible Descriptor for Effective Rigid Body Motion Trajectory Recognition	1673
	<i>Guo, Yao; Li, Youfu; Shao, Zhanpeng</i>	
	Vision Based Embedded Tiny Spur Gear Inspection and Measurement System	1679
	<i>Huang, Yibin; Gu, Jiaojiao; Wang, Shijun; Xiao, Han; Yuan, Kui</i>	
	Nonlinear Model Predictive Control for Visual Servoing from a Set of Points	1685
	<i>Ye, Guoqiang; Li, Weiguang; Wan, Hao</i>	
TP1-5	Image Processing	
	A Novel Method to Retrieve Sea Wave Components from Radar Image Sequence	1691
	<i>Wei, Yanbo; Lu, Zhizhong; Zhang, Jiankang</i>	
	MRI Image Segmentation by Fully Convolutional Networks	1697
	<i>Wang, Yabiao; Sun, Zeyu; Liu, Chang; Peng, Wenbo; Zhang, Juhua</i>	
	The Research of Video Tracking Based on Improved SIFT Algorithm	1703
	<i>Cong, Yang; Liu, Wanyu; Zhang, Yanli; Liang, Hong</i>	
	Motion Estimation Using Optical Flow Sensors and Rate Gyros	1708
	<i>Liu, Xiaoming; Chen, Zhongyuan; Chen, Wanchun; Xing, Xiaolan</i>	
	Research of Behavior Recognition Algorithm Based on Block Matrix	1716
	<i>Chu, Hongxia; Yang, Yu; Xie, Zhongyu; Zhang, Rongyi; Liu, Fanming</i>	
	3D Reconstruction for Soft Tissue of the Human Body	1721
	<i>Zhu, Ling; Li, Yandong; Yu, Ying; Zhang, Baoquan; Wang, Lijing</i>	
TP2-5	Localization and Mapping	
	Laser Sensor Based Localization of Mobile Robot Using Unscented Kalman Filter	1726
	<i>Xu, Qiang; Ren, Chang; Yan, Haoyue; Ji, Junhong</i>	

	A Multi-feature Localization Algorithm for Mobile Robots Indoor Environment Mapping	1732
	<i>Zhao, Lijun; Huo, Guanglei; Wang, Ke; Li, Ruifeng</i>	
	A Novel Segmentation Correction Method for Fusion of Vision and Laser	1738
	<i>Yuan, Yawei; Zhao, Jianghai; Fang, Shihui; Xu, Qunshan</i>	
	Optimal Identification for Dynamic State Space Model of FOG in Engineering Application	1744
	<i>Liu, Peng; Huang, Weiquan; Sun, Fengzhao</i>	
	On the Development of a Sensing System by Using Monocular Vision Sensor for Mobile Robot	1749
	<i>Yu, Huachen; Yuan, Zuqiang; Takahata, Kenji; Yang, Lin; Yang, Jianming</i>	
	A Modified FastSLAM for an Autonomous Mobile Robot	1755
	<i>Zhang, Juzhong; Jiang, Yi; Wang, Kai</i>	
TA1-6	Industrial, Manufacturing Process and Automation (I)	
	A Model for Static Contact of Revolute Cylinder Based on Geometric Constraint and Elastic Half-space Theory	1760
	<i>Li, Yuntao; Quan, Qiquan; Tang, Dewei; Deng, Zongquan</i>	
	Hole Contour Reconstruction From Point Cloud Based on Optimization and Statistical Distribution	1766
	<i>Jin, Chunming; Zhao, Ziyun; Li, Baojun</i>	
	Stress of a Trunnion Joint	1771
	<i>Zhang, Bo; Zhan, Ying; Feng, Sheng; Geng, Haipeng; Zhou, Jian; Yu, Lie; Cheng, Wenjie</i>	
	The Prediction Model of Surface Roughness Based on Experiments of Turning Titanium Alloy	1776
	<i>Yang, Cuilei; Zheng, Qingchun; Hu, Yahui</i>	
	High Cycle Fatigue Analysis of Third Stage Blade Based on Shroud Gap Effect	1781
	<i>Lin, Hao; Geng, Haipeng; Zhou, Xifeng; Yu, Lie</i>	
	Design Method and Test Research of D-Knotter Based on Rigid-flexible Contact Dynamics	1787
	<i>Gao, Qiang; Wang, Xinxin; Jianjun, Yin</i>	
TA2-6	Industrial, Manufacturing Process and Automation (II)	
	Application of SimulationX® – Based Technique to the Reduction of Pressure Pulsation according to Tilting Angles of a Swash Plate and Notch Shapes of a Valve Plate for Swash Plate Type Piston Motor	1792

	<i>Yoo, SeongJeong; Won, JeeChung; Seok, JeongKang; Young, WookJeong; Jin, WoongSa</i>	
	Research on Precise Assembly of Large Optical Components Technology	1798
	<i>Pei, Guoqing; Xu, Xu; Du, Weifeng; Xiong, Zhao; Ye, Lang; Yan, Han; Yuan, Xiaodong; Zhou, Hai; Han, Mengmeng</i>	
	A Quality Evaluation Model for Diesel Engine Using RBF Neural Network Based on Trial Run Data	1804
	<i>Lu, Xuefeng; Chang, Wenbing; Li, Lei; Zhou, Shenghan</i>	
	Research on Starting Performance for Low Speed Direct-driven PMSM	1809
	<i>Zhao, Yangyang; Yang, Xiumin; Wang, Sen; Bao, Yan; Xu, Haibiao; Liu, Dongling</i>	
	Research on Error Synthetical Modeling of Multi-functional Composite Five-Axis CNC Machine Tool	1814
	<i>Zhao, Jiali; Liu, Yuan; Li, Qiaolin</i>	
	Thermally Induced Variation of Bolt Load Considering Thermal Contact Resistance	1822
	<i>Zhuo, Ming; Yang, Lihua; Yu, Lie</i>	
TP1-6	Industrial, Manufacturing Process and Automation (III)	
	A Deep Study to Reuse of Processing Instructions in Automatic Programming Techniques	1828
	<i>Gao, Xuwei; Yuan, Kui; Xu, Qiaoyu</i>	
	Fast Selection of Face Regarding the Model in Automatic Programming Techniques	1834
	<i>Gao, Xuwei; Chai, Xiaojie; Yuan, Kui</i>	
	Residual Life Prediction of Rolling Bearings for Rail Vehicles Based On Proportional Hazard Model	1840
	<i>Zhang, Yuan; Du, Yanping; Gao, Zhenqing; Qin, Yong; Wei, Xiukun</i>	
	Selective Maintenance Model for Modular System	1845
	<i>Hou, Jinxin; Qian, Yanling</i>	
	The Production Instruction System for Smart Job Shop	1850
	<i>Wang, Chuang; Jiang, Pingyu; Lu, Tiantian</i>	
	Research on Multi-section Effective Linear Motor Pumping Unit	1855
	<i>Zhao, Yangyang; Yan, Hongkui; Wang, Sen; Zhao, Dongsheng; Liu, Dongling; Xu, Haibiao; Yang, Xiumin</i>	
TP2-6	Industrial, Manufacturing Process and Automation (VI)	
	Fast Ferry Vertical Acceleration Reduction using Mixed Sensitivity Approach	1860

Ticherfatine, Mounia; Zhu, Qidan

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TA1-7 Signal Processing (I)

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	Dynamic Data Outliers Eliminating and Filtering Method for Motion Information of Hovercraft	1931
	<i>Wang, Yuanhui; Zhang, Bo; Zhao, Qiang</i>	
	A Simulation Method for X-ray Pulsar Signal Based on Monte Carlo	1937
	<i>Jin, Jing; Liu, Yixiao; Li, Xiaoyu; Shen, Yi; Huang, Liangwei</i>	
	A Detection Method of Port Fuel Injector Spray Distribution	1943
	<i>Zhu, Junchao; Xie, Junwu; Zhang, Baofeng</i>	
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TP1-7	Biomedical Signals and Image Processing	
	3D-Reconstruction of Synapses Based on EM Images	1959
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TP2-7	Signal Processing for mechatronic system	
	Effects of Spatial Frequency on Audiovisual Integration for Communication between Human and Robot	1995
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	Study on Spectrum Eigenvalues of Transformer Vibration and its Application on Winding Deformation Detecting	2024
	<i>Li, Yaning; Wang, Kun; Shi, Tengfei; Zhu, Xiaoyan; Yu, Hong</i>	
WA1-1	Control Theory and Application	
	Command-Shaping Control of Quayside Cranes with Eight-Pole Reeving Mechanism	2030
	<i>Shah, Umer Hameed; Piao, Mingxu; Hong, Keumshik; Choi, Sanghei</i>	
	Research of Output Feedback H^∞ Switched Control to Dynamical Positioning of A Vessel	2036
	<i>Lin, Xiaogong; Sui, Renfeng</i>	
	Sideslip Control Method of Air Cushion Vehicle Based on Nonsingular Fast Terminal Slide Mode	2043
	<i>Fu, Mingyu; Gao, Shuang; Wang, Chenglong; Liu, Tong</i>	
	Constrained Output Feedback H^∞ Control of a Four-tank System	2048
	<i>Yu, Shuyou; Wang, Yan; Wang, Jing; Chen, Hong</i>	
	Delay-Range-Dependent H^∞ Control for Sampled-Data Active Suspension System	2054
	<i>Su, Xiaoyu; Shen, Wei</i>	
	The Control Technology of Wellbore Trajectory Control ToolBased on Radio Frequency Identification Device (RFID)	2060
	<i>Feng, Ding; Wang, Jie; Xiang, Zhengxin; Zhang, Hong; Chen, Kejian</i>	
WP1-1	Force Control	
	Heuristic Sample Reduction Based Support Vector Regression Method	2065
	<i>Yu, Hui; Sun, Wenzhu; Zhuo, Xiuzhi; Zhu, Guotao; Hu, Wenting</i>	

	Hybrid Force/Position Control of Industrial Robotic Manipulator Based on Kalman Filter <i>Xia, Guihua; Li, Chao; Zhu, Qidan; Xie, Xinru</i>	2070
	Research of kind of Variable Step Size Perturbation and Observation MPPT Based on Power Prediction <i>Sun, Chao; Wang, Yunliang</i>	2076
	Characteristic Model-based Adaptive Discrete-time Sliding Mode Design for Hypersonic Vehicle Attitude Control <i>Chang, Yafei</i>	2082
	Dynamic Algorithm for Safe and Reachable Frontier Point Generation for Robot Exploration <i>Li, Xiuzhi; Qiu, Huan; Jia, Songmin; Gong, Yue</i>	2088
	A Novel Hexapod Robot: Design and Mobility Analysis <i>Chen, Long; Zhong, Guoliang; Liu, Zhuoxi; Deng, Hua</i>	2094
WP2-1	Control Optimization	
	Optimization Design of Thrust Fluctuation of Six Degree of Freedom of Magnetic Suspension Positioning Platform <i>Zhang, Wenwen; Chen, Liguang; Liu, Jizhu; Pan, Mingqiang; Wang, Yangjun</i>	2099
	Optimal Scheme of PV Array in Partial Shading : A Reconfiguration Algorithm <i>Liu, Hongda; Wan, Lidong; Pei, Biying</i>	2105
	Trajectory Optimization for Agile-Turn of Vertically Launched Missile <i>Du, Wenhao; Zhou, Hao; Chen, Wanchun</i>	2110
	Sub-optimal Ground-Strike Guidance based on Perturbation Method <i>Meng, Jingwei; Chen, Wanchun; Yu, Wenbin</i>	2116
	A Kind of Online Self-Tuning Smith Predictor <i>Chen, Xu; Meng, Fei; Chen, Xiaopeng; Huang, Qiang</i>	2123
	Improved PSO-Based Energy Management of Stand-Alone Micro-Grid Under Two-time Scale <i>Wang, Yi; Jiang, Hanhong; Xing, Penxiang</i>	2128
WA1-2	Force Sensing	
	Non Negative Linear Combination Grasp Force Optimization <i>Wang, Xinqing; Liu, Yanli; Gao, Juan</i>	2134

	Methods of Target Motion Estimation for AUV Target Tracking	2139
	<i>Wang, Ying; Wang, Hongjian; Li, Chun; Li, Qing</i>	
	An Indirect Stiffness Estimation of Flexible Joint Based on System Function Approximation	2145
	<i>Liu, Zhangxing; Jin, Hongzhe; Yang, Decai; Fan, Jizhuang; Liu, Yubin; Zhang, He; Dong, Huijuan</i>	
	Thermal Design Scheme of FOG Based on Thermal Insulation Technology	2151
	<i>Zhang, Zhuo; Du, Shipeng; Yu, Fei; Wang, Qiuying</i>	
	A Force Measurement System for Lithium-ion Battery Forming Tab-Clamp and Its Electromagnetic Shielding Design	2156
	<i>Ding, Caihong; Yang, Yanzhu; Liu, Pei</i>	
	Indirect Force Estimation for Resiliently Mounted Machinery	2161
	<i>Peng, Weicai</i>	
WP1-2	Sensor System	
	Application of Isomorphic Haptic Device in Excavator Simulation	2166
	<i>Ni, Tao; Wang, Shuang; Zheng, Huanfei; Zhao, Yinghuan; Chen, Xiangxian; Zhang, Mingxi</i>	
	Encoding Anticipation Mechanism for Network Coding in Underwater Acoustic Sensor Networks	2173
	<i>Zhao, Danfeng; Wen, Jie</i>	
	A Novel Spatial-temporal Encoding Strategy for Presenting Time on the Wrist using Vibrotactile Cues	2179
	<i>Afzal, Naqash; Wang, Dangxiao; Serir, Amine; Zhang, Yuru</i>	
	An Online Monitoring Measure Consistency Computing Algorithm by Sliding Window in Multi-Sensor System	2185
	<i>Ma, Siyuan; Si, Gangquan; Yue, Wenmeng; Ding, Zhiqiang</i>	
	Study of Remote Monitoring System of Working States of Metro Door system	2191
	<i>Zhu, Songqing; Xu, Quanjun; Xu, Youxiong</i>	
	Force Feedback-based Robotic Catheter Training System for the Vascular Interventional Surgery	2197
	<i>Guo, Shuxiang; Yan, Lin; Guo, Jian</i>	
WP2-2	Sensor Design	
	Effect of Force Feedback on a Bulldozer-Type Robot	2203
	<i>Minamoto, Masahiko; Kawashima, Kenji; Kanno, Takahiro</i>	

	Bio-Magnetic Sensor Circuit Design Based on Giant Magneto-Impedance Effect	2209
	<i>Wang, Zhihua; Xu, Ming; Xu, Xiaohong; Zhou, Zongtan</i>	
	Study on the Deformation Measurement of Structure Based on Fiber Bragg Grating Sensor	2215
	<i>Xiao, Shuang; Liu, Mingyao; Tan, Yuegang; Zhang, Zhijian; Yun, Kang</i>	
	Covariance Matching Based Adaptive CKF for Distributed Multi-sensor	2222
	<i>Lin, Xiaogong; Liu, Yingqian</i>	
	Study on the Optimization of Ring Type Composite Sensing Structure	2228
	<i>Lu, Liying; Liu, Mingyao; Zhang, Zhijian; Yun, Kang</i>	
	Comparative Study on the Optimal Path Problem of Wireless Sensor Networks	2234
	<i>Xu, Yulong; Wang, Xiaopeng; Zhang, Han</i>	
WA1-3	Structrue and Mechanism Design	
	Operator Based Robust Two Loop Nonlinear Free Vibration Control of a Flexible Plate	2240
	<i>Jin, Guang; Deng, Mingcong</i>	
	Design and Optimization of a 2-Link Type Overboarding Mechanism for the Drop/Lift Automation of an Active/Passive Sonar System in a Surface Ship	2246
	<i>Seok, Jeong Kang; Won, JeeChung; Jong, KapChoi; Seong, HakPark; Yoo, SeongJeong; Hyo, GonKim</i>	
	The Research on the Effects of Motion Parameter on Adhesive Ability of a Lunar Crater Exploration Rover Wheel Based on DEM Simulation	2253
	<i>Zhang, Kailiang; Hou, Xuyan; Zhang, Kaidi; Cui, Jinsheng; Quan, Qiquan; Deng, Zongquan</i>	
	Design and Research on Asteroid Anchor System Based on DEM Simulation	2259
	<i>Chen, Shutong; Wang, Yongbin; Jiang, Wansong; Zhu, Qian; Wu, Shiqing; Zhang, Kaidi; Zhang, Kailiang</i>	
	Mobility Analysis of A Family of One-dimensional Deployable Mechanisms Based on Sarrus Mechanism	2265
	<i>Song, Xiaoke; Guo, Hongwei; Deng, Zongquan; Liu, Rongqiang; Li, Bing</i>	
	The Study of High Strength Hydraulic Bolt on the Tensile Resilience	2272
	<i>Zhang, Zuti; Ruan, Chunhong; Qu, Xuliang; Chai, Xuesong</i>	
WP1-3	Modeling and Analysis	
	Dynamic Analysis of A Cable Underwater Robot in A Nuclear Reaction Pool	2278
	<i>Li, Zhandong; Tao, Jianguo; Luo, Yang; Ding, Liang; Deng, Zongquan</i>	

	Structure Design and Dynamic Modelling of a Novel Modular Self-reconfigurable Robot <i>Huang, Jie; Ge, Weimin; Wang, Xiaofeng; Liu, Jun</i>	2284
	A Novel Model Analysis Method and Dynamic Modelling for Hybrid Structure Flexible Manipulator <i>Long, Teng; Li, En; Yang, Guodong; Liang, Zize</i>	2290
	Improved Algorithm of Interaural Time Difference Based on Correlation Method <i>Chen, Xiaomei; Hu, Chenming; Zhong, Bo; Xu, Huan; Feng, Xiujuan</i>	2296
	Dynamics Modeling for Curved-type Fully Compliant Mechanism Based on Pseudo-rigid-body Modeling <i>Li, Na; Liu, Chang; Jiang, Haiyong</i>	2302
	Mathematical Modeling and Researching for the Optimization Problem of Grouping Interview <i>Xu, Yulong; Wang, Zhongyi; Wang, Xiaohui</i>	2308
WP2-3	Modeling of Mechatronic System	
	Muscle Synergy Analysis of a Set of Lower Extremity Movements in Quiet Standing Scenario: A Preliminary Study <i>Li, Zhan; Cheng, Hong; Yin, Ziguang</i>	2314
	Study of Audiovisual Asynchrony Signal Processing: Robot Recognition System of Different Ages <i>Ren, Yanna; Yang, Weiping; Wu, Qiong; Wu, Fengxia; Takahashi, Satoshi; Yoshimichi, Ejima; Wu, Jinglong</i>	2320
	Research on Microblog Filtering Technology Based on Improved Online Support Vector Machine Model <i>Ning, Hui; Li, Song; Zeng, Fanhu; Xu, Li</i>	2326
	An Artificial Neural Network Based Haptic Rendering of Contact with Deformable Bodies <i>Chen, Wei; Liu, Guanyang; Zhang, Yuru; Shirinzadeh, Bijan</i>	2332
	The Effect of Temporal Asynchrony on Audiovisual Integration <i>Yang, Jingjing; Li, Xiujuan; Li, Qi; Wu, Jinglong</i>	2338
	Active Disturbance Rejection Control of Single Phase Grid Connected Inverter <i>Li, Sijia; Xiong, Hejun</i>	2344
WA1-4	Modeling and Simulation (I)	

	Establishment of Actuation Model of the Three-layer Structure Piezoelectric Bimorph and Simulation Analysis Based on Analysis of the Internal Energy	2349
	<i>Guo, Xiaodong; Zhang, Fuxing; Yan, Shaoze</i>	
	SEE Vulnerability Bit Analysis Method for Switch Matrix of SRAM-based FPGA Circuits	2355
	<i>He, Wei; Wang, Yueke; Xing, Kefei; Deng, Wei</i>	
	Finite Element Simulation and Capacitive Analysis on Coupling Capacitor Using Complex Variable Method of Quasi-Electrostatic Field	2360
	<i>Zhan, Yinyu; Deng, Jiahao; Ye, Yong; Liu, Shichuan; Liu, Yuting</i>	
	A Study on a Method Solving Optimal Currents of IPMSM Based on the PDS for Electric Vehicles	2366
	<i>Wu, Qinmu; Zhang, Wenli; Chen, Xiangping; Cao, Min</i>	
	Modeling and Simulation of Marine Propeller Load	2371
	<i>Meng, Fanrong; Zhang, Chuanqing; Zhao, Yanqi</i>	
	Design and Performance Evaluation of a Novel Mechanism with Screw Jet Motion for a Hybrid Microrobot Driven by Rotational Magnetic Field	2376
	<i>Fu, Qiang; Guo, Shuxiang</i>	
WP1-4	Modeling and Simulation (II)	
	Design and Modeling of a Torsion Spring-Based Actuator (TSA) with Valid Straight-Arm Length Adjustable for Stiffness Regulation	2381
	<i>Yang, Decai; Jin, Hongzhe; Liu, Zhangxing; Fan, Jizhuang; Zhu, Yanhe; Zhang, He; Dong, Huijuan</i>	
	A Method of Encircle Tactic Based on Geometric Analysis in Pursuit-evasion Games	2387
	<i>Lei, Ming; Yin, Quanjun; Yao, Xinyu</i>	
	Modeling and High Accuracy Parameter Estimates for a Friction Based Electro-hydraulic Load Simulator	2392
	<i>Zheng, Dake; Xu, Hongguang</i>	
	Consistent Modeling for Device Control and Simulation in Large-scale Heterogeneous Systems	2398
	<i>Luo, Jun; Ni, Zhigao; Du, Xinlin</i>	
	A Research on Weapon-Target Assignment Based on Combat Capabilities	2403
	<i>Yan, Yudu; Zha, Yabing; Qin, Long; Xu, Kai</i>	
	A New Inducer for Pipeline Inner Inspection based on ACFM	2408
	<i>Feng, Yijing; Zheng, Wenpei; Zhang, Laibin</i>	

WP2-4	Modeling and Simulation (III)	
	Research on Hydrodynamic Characteristics of Magnus Rotor Wing at Medium/low Speed	2413
	<i>Liang, Lihua; Zhao, Peng; Zhang, Songtao</i>	
	Magnetically-guided Manipulation of Microfiber for Fabrication of Porous Cell Scaffold	2419
	<i>Li, Xingfu; Shi, Qing; Wang, Huaping; Sun, Tao; Li, Jianing; Yu, Ning; Huang, Qiang; Fukuda, Toshio</i>	
	An Improved Vascular Model Based on Mass Spring Model and Parameters Optimization by Gaussian Processes	2425
	<i>Wu, Dongmei; Lv, Chaoshun; Bao, Yidong</i>	
	Mission-Based Command and Control Behavior Model	2431
	<i>Sun, Lin; Zha, Yabing; Jiao, Peng; Xu, Kai; Liu, Xiaocheng</i>	
	Dynamic Modeling and Sliding Mode Controller Design of a Two-wheeled Self-balancing Robot	2437
	<i>Song, Yuan; Guo, Lei; Xing, Bin</i>	
	Design of Nonlinear Adaptive Power-level Controller for PWR in Load Following Operation	2443
	<i>Li, Cuiying; Wang, Junling; Luan, Xiuchun; Zhou, Jie; Yang, Zhida</i>	
WA1-5	UAV/ UGV	
	Design of Wireless Power Transfer Device for UAV	2449
	<i>Wang, Chunjie; Ma, Zheng</i>	
	Research on The Algorithm of Multi-Autonomous Underwater Vehicles Navigation and Localization Based on The Extended Kalman Filter	2455
	<i>Li, Juan; Zhang, Juan</i>	
	Hazardous Gas Detection Four-rotor UAV System Development	2461
	<i>Shi, Liang; Wang, Xin; Zhang, Tao; Hu, Chunrong; Luo, Kaixin; Bai, Bing</i>	
	Integrated Navigation System for UAVs based on the Sensor of Polarization	2466
	<i>Jin, Rencheng; Sun, Huisheng; Sun, Jialiang; Chen, Wen; Chu, Jinkui</i>	
	Research on Optimization Design of UAV Main Propulsion Motor Based on Particle Swarm Optimization Algorithm	2472
	<i>Li, Yufeng; Xiang, Song; Wang, Sen; Huang, Jin; Zhao, Yangyang; Guo, Jiacheng</i>	
	Action Synchronization between Human and UAV Robotic Arms for Remote Operation	2477
	<i>Lan, Gongjin; Bu, Yasheng; Liang, Jinhao; Hao, Qi</i>	

WP1-5	Underwater Robots	
	Nonlinear Depth Control in Under-actuated AUV	2482
	<i>Zhang, Guocheng; Du, Chengrong; Huang, Hai; Wu, Haibo</i>	
	A Group Evaluation Method for Science Popularization Using Generalized Fuzzy Similarity and TOPSIS	2487
	<i>Zang, Tianlei; Qiu, Lu; He, Zhengyou; Qian, Qingquan</i>	
	Delay-independent Stabilization of Depth Control for Unmanned Underwater Vehicle	2494
	<i>Zhang, Xun; Xiao, Yao; Zhang, Gengshi; Sun, Xixun; Zhao, Xiaofang</i>	
	Research on Situation Awareness Based on Ontology for UUV	2500
	<i>Yao, Hongfei; Wang, Hongjian; Lv, Hongli; Wang, Ying</i>	
	Research on Optimal Planning Method of USV for Complex Obstacles	2507
	<i>Wang, Yuanhui; Chi, Cen</i>	
	Task Allocation of Multiple Autonomous Underwater Vehicle System Based on Multi-objective Optimization	2512
	<i>Lv, Hongli; Wang, Hongjian; Li, Qing; Yao, Hongfei</i>	
WP2-5	Design and Analysis of Mobile Robots	
	Experimental Evaluation for the New Fluid Analytical Technique around Tail Fin of a Fish Robot	2518
	<i>Yoshinaga, Naoto; Hirata, Hideyuki; Hinayama, Yuki; Guo, Shuxiang</i>	
	High Precise Haptic Device for the Robotic Catheter Navigation System	2524
	<i>Guo, Shuxiang; Qin, Mingyang; Xiao, Nan; Wang, Yuan; Peng, Weili; Bao, Xianqiang</i>	
	The Structure Design and Analysis of a Wheel-track robot	2530
	<i>Cui, Dengqi; Guo, Wenzeng; Dong, Han; Gao, Xueshan</i>	
	Dynamic Analysis of a Frog Skating Robot	2536
	<i>Xu, Zili; Lu, Song; Huang, Zhihong; Yang, Wenjun</i>	
	A Method to Detect Stairs with Three-dimensional Scanning for Hexapod Robot Stair Climbing	2541
	<i>Zheng, Zhiheng; Zhong, Guoliang; Deng, Hua</i>	
	The Convenient Assembly Method for the Virtual Robot Kit	2547
	<i>Gao, Haitao; Xu, Youxiong; Han, Yali; Zhu, Songqing; Zhou, Yinglu</i>	
WA1-6	Manipulator and Manipulation	

	Analysis of Bracing-Constraint Dynamics with Energy-efficient for Elbow-bracing Manipulator	2552
	<i>Li, Xiang; Minami, Mamoru; Han, Han; Wei, Yanhui</i>	
	Design Optimization of six DOF Manipulator Based on CO Algorithm	2558
	<i>Han, Dingqiang; Duan, Xingguang; Cui, Tengfei; Zhan, Yue</i>	
	Dynamic Collision Avoidance Method for Co-Worker Robot Using Time Augmented Configuration-Space	2564
	<i>Wada, Hisaka; Kanazawa, Akira; Konada, Kazuya; Wakabayashi, Yuta; Kamioka, Masaya; Kondo, Shuhei; Kinugawa, Jun; Kosuge, Kazuhiro</i>	
	An Integrated System of Detecting End-effector Motion States and Wafer Stick-slip on a Wafer Transfer Robot	2570
	<i>Liu, Yanjie; Han, Haijun; Sun, Lining; Li, Kang; Liu, Tao</i>	
	The 3D Map Building of the Mobile Robot	2576
	<i>Cao, Haoxiang; Gao, Junyao; Zhao, Fangzhou; Zhao, Jingchao; Liu, Chuzhao; Liu, Yi; Shi, Xuanyang</i>	
	Design and Implementation of a Automatic Carpet Edge-Cutting System	2582
	<i>Zhang, Qiang; Luo, Huifu; Zhu, Wei; Qi, Guanglin; Wang, Yanghong</i>	
WP1-6	Human-System Interaction	
	A Basic Study for Improving the Predictability of Amber Traffic Lights: Comparing the Brief and Long Interval Rhythm Prediction	2587
	<i>Xu, Zhihan; Wu, Qiong; Li, Yujie; Kataoka, Yuta; Takahashi, Satoshi; Wu, Jinglong; Li, Chunlin; Ohno, Seiichiro</i>	
	Bilingual Representation of Speech Sounds in Chinese-Japanese Bilinguals	2593
	<i>Lu, Sa; Wang, Kun; Wang, Xin; Tang, Xiaoyu; Ren, Yanna; Wu, Jinglong</i>	
	Residual Power Spectrum Analysis in the Application of EEG De-noising	2599
	<i>Wan, Yongtao; Chen, Feng; Huo, Zhixiang</i>	
	An Overview on Cloud Computing Platform Spark for Human Genome Mining	2605
	<i>Ding, Dongliang; Wu, Dongyue; Yu, Fuli</i>	
	Improving Classification Accuracy of SVM Ensemble using Random Training Set for BCI P300-speller	2611
	<i>Li, Qi; Shi, Kaiyang; Ma, Shengyuan; Gao, Ning</i>	
	Design and Workspace Analysis of Valve Opening Device for Manipulator in Nuclear Power Plant Disaster	2617
	<i>Xing, Hongjun; Ding, Liang; Deng, Zongquan; Gao, Haibo; Ma, Changyou; Tao, Jianguo</i>	

WP2-6 Power Generation and Distribution

- [On the Development of a Control System for a Small Bio-Methane Gas Engine Generator](#) 2623
Okamura, Koichi; Dong, Yijun; Takahata, Kenji; Yang, Jianming
- [Research on A Novel 12-Phase Rectifier Power Generation System and its Rectifier-side Short Circuit Fault](#) 2629
Zhang, Jingnan; Bai, Linlin; Zhang, Tianhao
- [The Design and Implementation of Proton Exchange Membrane Fuel Cell's Control System](#) 2634
Dong, Chao; Li, Hongpeng; Zhao, Muyuan
- [Key Technologies of Smart Distribution Grid](#) 2639
Ma, Youjie; Liu, Feng; Zhou, Xuesong; Gao, Zhiqiang
- [Operation Optimization of a PV-Wind-Storage System Based on Improved Quantum Evolution Algorithm](#) 2644
Zheng, Xiaokun; Li, Shuangbo; Zhang, Tao; Wang, Rui
- [A Strategy for Day-ahead Prediction of Residual Capacity of Energy Storage Unit of Micro Grid in Islanded State](#) 2652
Zhang, Ying; Zhang, Chao; Wang, Tianzheng; Qu, Ying; Wang, Wei; Bai, Lu; Hao, Jie; Guan, Shaoping